FUTURING SMART ENERGY

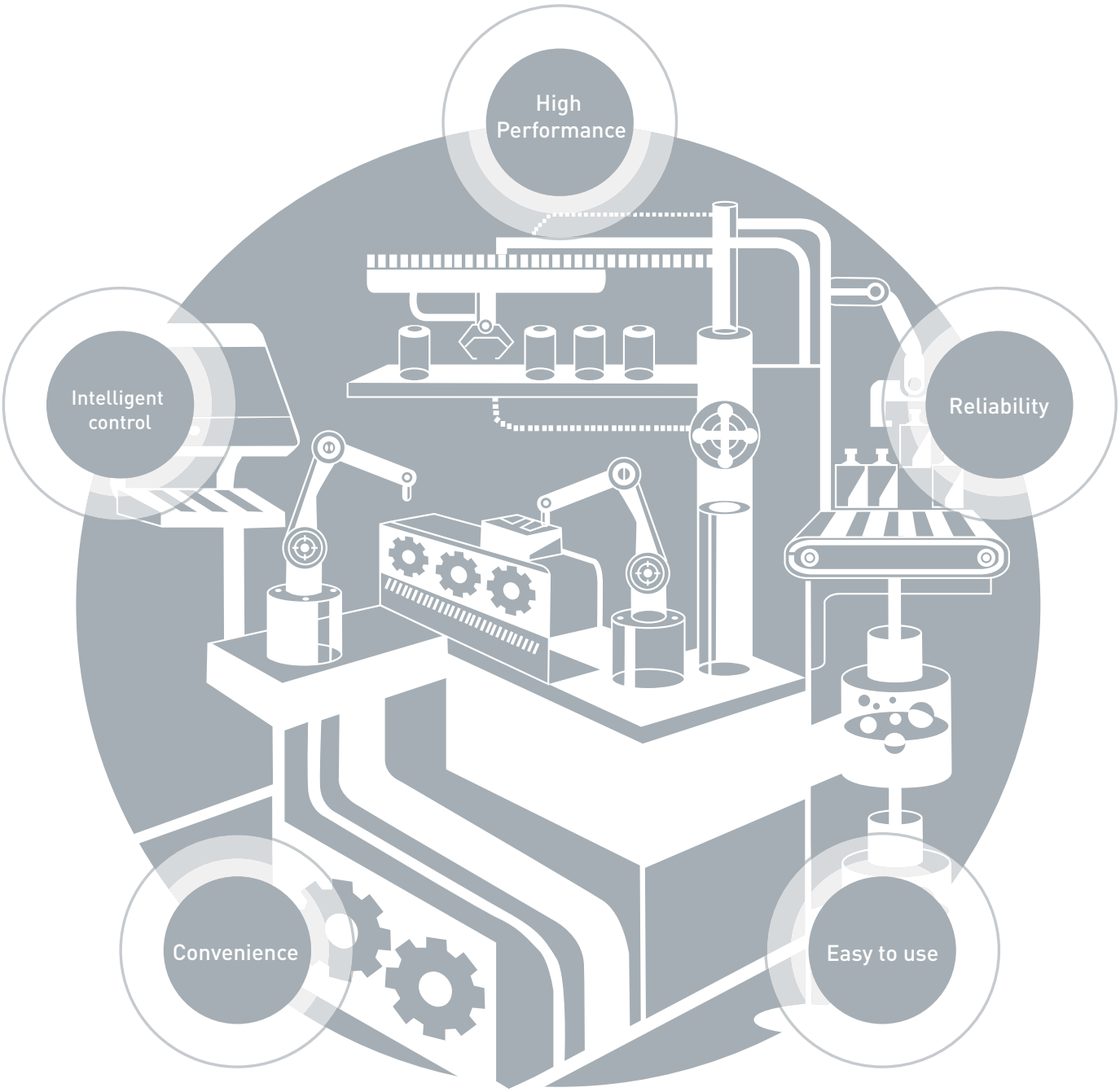
www.lsis.com



XDL/XML Series

XGT Servo System

LS IS


High Performance
Intelligent control
Reliability
Convenience
Easy to use

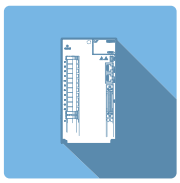
XGT Servo System

XDL/XML Series



Features
4 ~ 13

Features



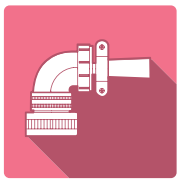
Servo Drive
14 ~ 57

Servo Drive



Servo Motor
58 ~ 99

Servo Motor



Options and Accessories
100 ~118

Options and Accessories



Application
122 ~ 135

Application

User-oriented XDL/XML Series LSIS XGT Servo systems complete your optimal solution.



XDL /

Your motion systems visualize the perfect solution though the
LS comprehensive product ranges for the optimal drives and applications.
Its high-performance vector, precision and speed control are user-friendly
and cost effective.



XML Series

It's Slim

Compact size with high capacity

Capacity	400W (44% Down Size)			1kW (46% Down Size)			3.5kW (62% Down Size)		
Series	XDL	VS	Competitor	XDL	VS	Competitor	XDL	VS	Competitor
L [mm]	38	80	40	58	88	60	88	137	90
W [mm]	169	187	168	169	210	168	169	256	168
H [mm]	173	132	170	198	195	195	198	225	195

38 mm

The Minimized Width
to 38mm!!! (400W)



400W

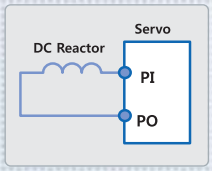
Reliability

Main capacitor quality improved

- Long-life type capacitor applied (2.5 times improvement)

Convenient DC reactor installable

- Power connection to DC-link
- Easier wiring and smaller size compared to 3-phase AC reactor
- Connection for DC input (PI, N)



Stable turn-off function based on the detection of the control power turn-off

Upgraded protection function (I)

- Triple protection functions for power module
  : IPM fault, CL detecting, over current detecting with S/W
- Main power mis-wiring detecting function : Selecting 3 phase or single phase, and alarm or warning is available
- Protecting overheating with thermal sensor in the drive and motor
- Alarm code grouping and exclusive output contacts (AL00, AL01, AL02)
- Warning function (digital output, warning output)
  : Mis-wiring of power, low voltage for encoder battery, over speed command, over torque command, over load, mis-matched motor and drive



1kW

3.5kW

52%

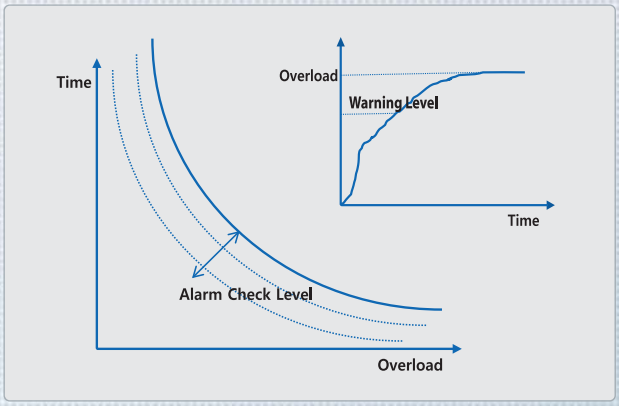
Compared with VS Drive
Max 52% Slim

5%

Compared with
competitor's Drive
Max 5% Slim

Upgraded protection function (II)

- Detecting function for accumulated over load of regenerative resistor
  : Protect algorithm is provided with embedded resistor characteristic
  : Protection by capacity (P0-11) and resistance (P0-10)
  : Providing de-rating factor for radiant heat
- Available continuous overload capacity setting as followed operating condition
  : Protect with separated overload table at stall & operation
  : Set overload check level (P0-12)
  : Setting warning signal output level is available (P0-13)



CE, RoHS certificated

lead-free

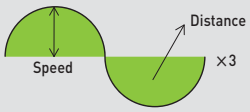
Easy to USE

Reliable partner with global standard performance and easy control by user-centric environment



Easy gain tuning with automatic inertia estimating function

- Quick & Accurate Inertia Estimating
- On-Line Tuning: L7NH, L7P
- Off-Line Tuning: L7N, L7S
- Parameter for Estimation (Speed &Distance)



Encoder with bi-directional high speed serial communication

- Automatic Identification (Motor ID /Encoder pulse)
- BiSS protocol
- Easy wiring (15 encoder wires→7 encoder wires) and anti-external noise

BiSS INTERFACE

Sufficient input/output contacts and various functions

- L7S: Digital input contacts: 10, output contacts: 8 / Analog input contacts: 2 and output contacts: 2
- L7N: Digital input contacts: 6, output contacts: 4 / Analog input contacts: 2 and output contacts: 2
- L7NH: Digital input contacts: 8, output contacts: 4 / Analog input contacts: 1 and output contacts: 2
- L7P: Digital input contacts: 16, output contacts: 8 / Analog input contacts: 2 and output contacts: 2
- PEGASUS: Digital input contacts: 4, output contacts: 2 / Analog input contacts: 1 and output contacts: 1
- Flexible assignment of input/output signals by parameters and contact setting based on the input/output contact type (N.O / N.C contacts)

Using the rotary switch to configure the drive node address [L7NH, L7P, and PEGASUS]

- Using the rotary switch to configure the drive node address conveniently
- L7NH: 0-99, L7P: 0-31, PEGASUS: 0-15



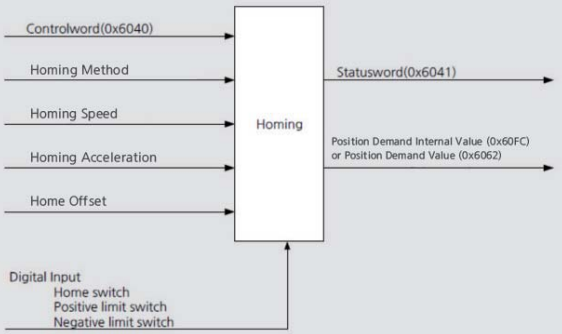
Plug-in type power connector

- Expanded to 100 W - 3.5 kW for improved wiring convenience



Various homing functions [L7NH, L7P, and PEGASUS]

- The drive provides the homing function.
- You can specify the speed, acceleration, offset, and homing method.



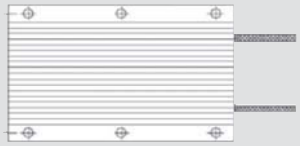
Easy firmware upgrade [L7NH, L7P, and PEGASUS]

- Supporting the USB OTG function to allow firmware download with a USB memory
- Useful where space is limited or environmentally unfavorable



Built-in regenerative braking resistance in the drive

- Drive installed inside to improve user convenience (100 W - 3.5 kW)
- Providing the connection for external installation
- Enhanced protection algorithm





XGT Servo series with high speed, incredible performance,
smart and convenience. It' time to check value of XDL/XML series



High Performance

Serial encoder of high resolution (16 bit - 21 bit)

- Stability improved during precision position control and low-speed operation

Stable low-speed properties based on precise speed measurement

- Stable speed measurement at low speed

Calculation speed improved [L7NH, L7P, and PEGASUS]

- FPU (Floating Point Unit) for reliable precision calculation
- 16 kHz switching frequency for precision current control
- 32 bit operation for increased synchronous command processing rate (MIPS)

Dedicated PC program

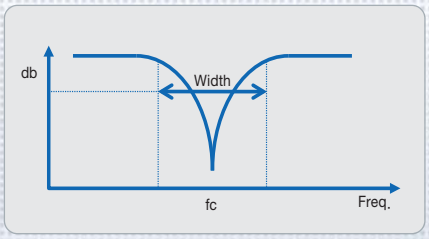
- L7S, and L7N: LIVE-I.C.E / L7NH, L7P, and PEGASUS: Drive CM
- PC program for shortened equipment tuning time and debugging
- Monitoring for speed, torque, current feedback, position values and positional error values and alarm occurrence time



Intelligent Control

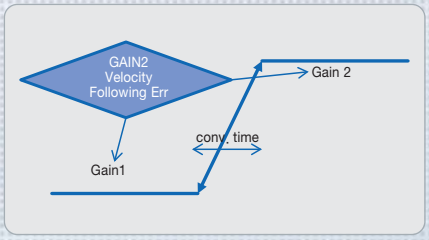
Notch filter for resonance suppression

- 4-step notch filter
- 2-step vibration suppression filter at the load position
- FFT function for real-time frequency analysis



Various gain switching modes for improved control performance

- P/PI auto-switching function to reduce overshooting during acceleration/deceleration
- Various Gain1↔Gain2 switching modes



Various dynamic brake control modes

- Configuring the operation mode at stop and after stop

Convenience

Providing various functions– backup, network diagnosis, monitoring and built-in functions focused on improving efficiency



High Performance

- High speed, Real-time capability and Synchronization mechanism

Open Network

- Over 1600 worldwide members

Cost Effective

- Standard Ethernet Cabling + Connectors, Less implementation efforts for master and slave

Easy to Use

- Versatile topology and Diagnostics

XDL Drive with Built-in EtherCAT Interface

- 100BASE-TX(100Mbps) Ethernet based real-time communication
- Support CiA402(IEC61800-7) drive profile
- Interoperability
- Max. 100m between nodes
- Precise synchronization mechanism (1us)
- Freely settable process data length and mapping
- Four status indication LEDs (L/A0, L/A1, RUN, ERR)
- Standard RJ45 connector and cabling(CAT5)
- Support various homing modes
- Support Full-Closed control (Being developed)

Various operation modes

- L7N: Using the EtherCAT communication to support Cyclic (P/S/T) and Profile (P/S/T) modes
- L7NH and PEGASUS: Using the EtherCAT communication to support Cyclic & Profile (P/S/T) modes, EOE, COE, and FOE

Safe torque off function

- Torque-off forced by hardware signals without involvement of the drive CPU and FPGA (ASIC); international standards adopted (IEC61508)

High speed position capture function

- Touch probe function(PROBE1, PROBE2)

Adjustment function linked with XGT series from LSIS

- Inertia detection, position/speed gain manual adjustment, gain switching setup, etc.

Have conformity of EtherCAT device

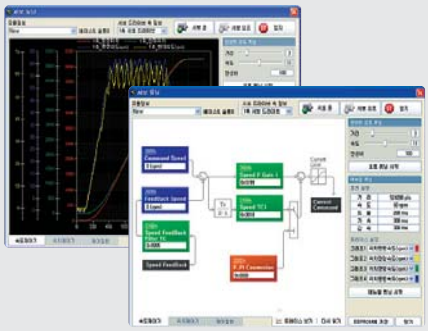
- In-house test using CTT(Conformance Test Tool)





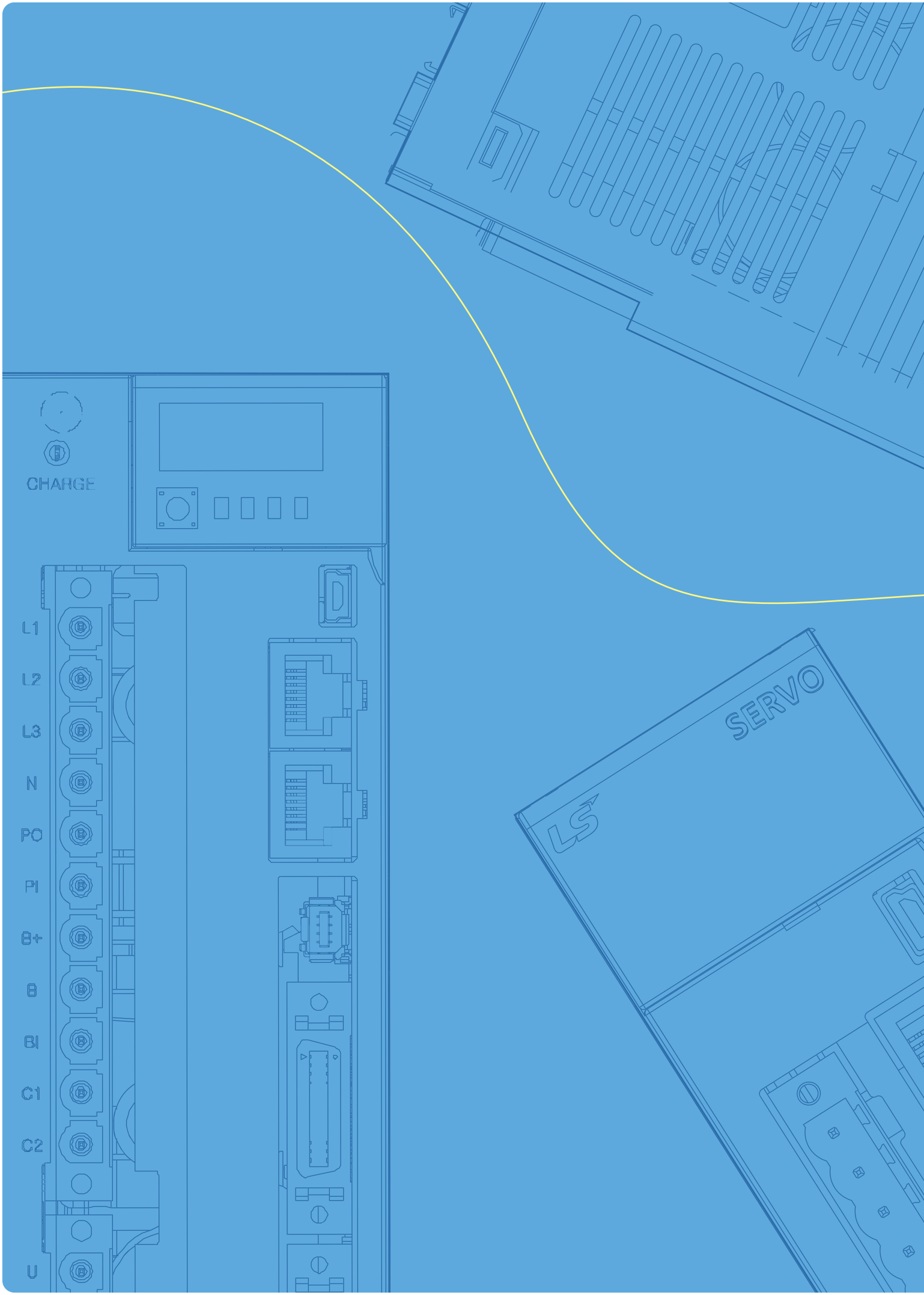


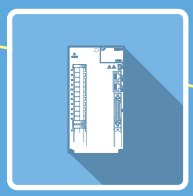
LSIS XGT PLC + PN8B



Provide gain tuning tools and commissioning packages

- Automatic inertia tuning and PI gains
- Gain conversion setting
- Manual fine gain tuning tool
- Object save and initialization function
- Alarm history function(recently issued 20 alarm codes)


CHARGE
L1
L2
L3
N
P0
P1
B+
B
BI
C1
C2
U
SERVO
LS



Servo Drive

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L7P Series
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XIP(PEGASUS) Series
Integrated Servo System Type ---------- 52

XDL-L7S Series



Servo Drive Designation

XDL	-	L7	S	A	004	B	AA
Model Name			Communication	Input Power Supply	Capacity	Encoder Type	Option
XDL Series			S : Standard I/O Type	A : 200VAC	001 : 100W	A : Quadrature (Pulse Type)	Exclusive Option Code
				B : 400VAC	002 : 200W	B : Serial (Communication Type)	
					004 : 400W		
					008 : 750W		
					010 : 1.0kW		
					020 : 2.0kW		
					035 : 3.5kW		
					050 : 5.0kW		
					075 : 7.5kW		
					150 : 15.0kW		

* Range
- 200V : 0.1kW~5.0kW
- 400V : 1.0kW~15kW

Pulse, Analog Command Type XDL-L7S

Easy to USE

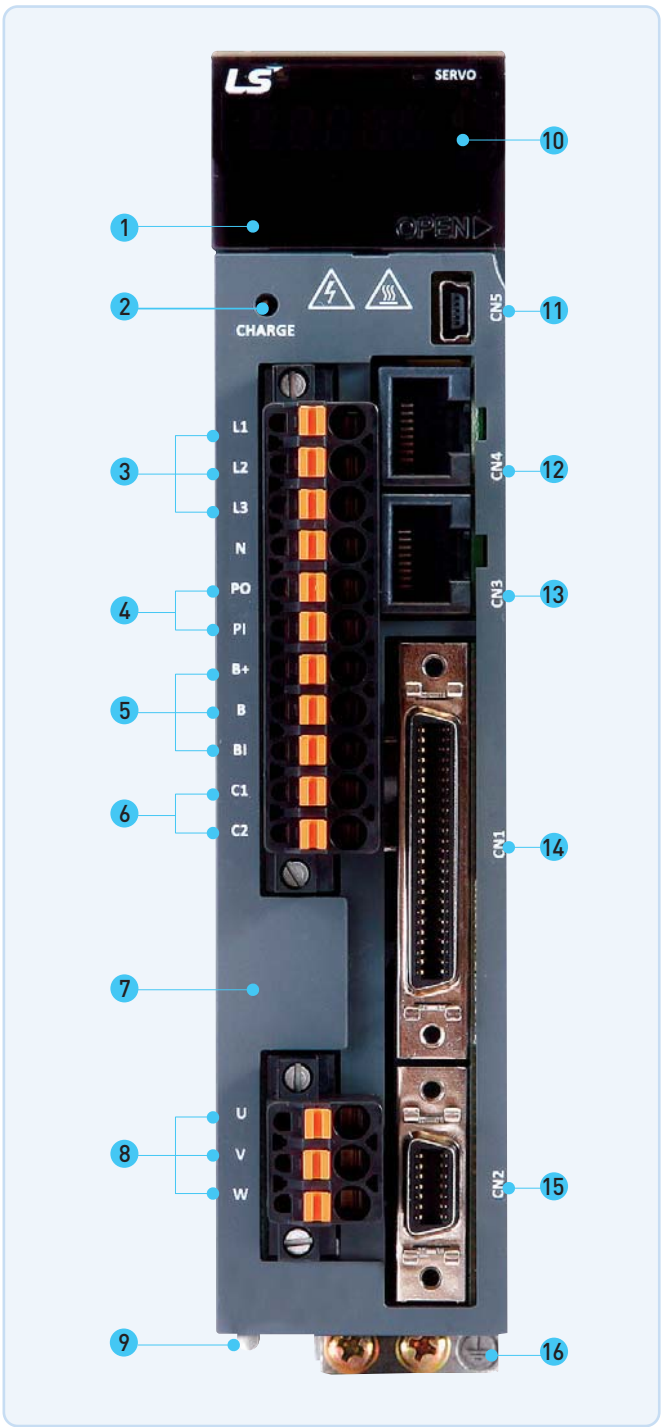
- Easy Gain Tuning with Automatic Inertia Estimating Function
- Easy Setting Built-in Panel Operator
- Many I/O Contacts and Various Functions (Digital Input: 10 contacts, Digital Output:8 contacts / Analog input, output : 2 contacts)]

Reliability for Protection Function

- CE, RoHS Certificated
- Drive Protection Function and Warn unction

High Response for Precision Control

- High Resolutions Serial type Encoder(19Bit, BiSS)
- Improved Speed Response(≒1Khz) Frequency



1. Operation keys (Mode, Up, Down, Set)
2. Charge Lamp
3. Main Power Connector (L1, L2, L3)
4. DC Reactor Connector(PO, PI)
   - Short-Circuit when not used
5. Regenerative resistance connector (B+, B, BI)
   - Short-Circuit B, BI terminals when standard type
   - Use B+, B terminals when using external resistor
6. Control Power Connector (C1, C2)
7. Front Cover
8. Motor Power Cable Connector (U, V, W)
9. Heat Sink
10. Display
11. CN5 : USB Connector
12. CN4 : RS-422 Communication Connector
13. CN3 : RS-422 Communication Connector
14. CN1 : Control Signal Connector
15. CN2 : Encoder Signal Connector
16. Ground

Drive Combination Table

XDL-L7SA Incremental Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable	Power Cable		
					Quadrature Type	INC	For power	Power + Brake	Brake
3,000	5,000	□40	SAR3A	L7SA001A	* 2,048P/R	XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□KB
		□40	SAR5A	L7SA001A					
		□40	SA01A	L7SA001A					
		□40	SA015A	L7SA002A					
		□60	SB01A	L7SA002A	* 3,000P/R				
		□60	SB02A	L7SA002A					
		□60	SB04A	L7SA004A					
		□80	SC04A	L7SA004A					
		□80	SC06A	L7SA008A					
		□80	SC08A	L7SA008A					
		□80	SC10A	L7SA010A					
		□130	SE09A	L7SA008A		XLCS-E□□□BS	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE15A	L7SA020A					
		□130	SE22A	L7SA020A					
		□130	SE30A	L7SA050A					
		□180	SF30A	L7SA035A			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SF50A	L7SA050A			XLCS-P□□□JS	XLCS-P□□□LB	
2,000	3,000	□80	SC03D	L7SA004A		XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□KB
		□80	SC05D	L7SA008A					
		□80	SC06D	L7SA008A					
		□80	SC07D	L7SA008A					
		□130	SE06D	L7SA008A		XLCS-E□□□BS	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE11D	L7SA010A					
		□130	SE16D	L7SA020A					
		□130	SE22D	L7SA020A					
		□180	SF22D	L7SA020A			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	LF35D	L7SA035A					
		□180	SF55D	L7SA050A			XLCS-P□□□JS	XLCS-P□□□LB	
	3,000	□220	SG22D	L7SA020A			XLCS-P□□□IS		XLCS-P□□□SB
		□220	LG35D	L7SA035A					
		□220	SG55D	L7SA050A			XLCS-P□□□JS		
1,500	3,000	□130	SE05G	L7SA008A			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE09G	L7SA010A					
		□130	SE13G	L7SA020A					
		□130	SE17G	L7SA020A					
		□180	SF20G	L7SA035A			XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	LF30G	L7SA035A					
	3,000	□180	SF44G	L7SA050A			XLCS-P□□□JS	XLCS-P□□□LB	
	3,000	□220	SG20G	L7SA020A			XLCS-P□□□IS		XLCS-P□□□SB
	2,700	□220	LG30G	L7SA035A					
	3,000	□220	SG44G	L7SA050A			XLCS-P□□□JS		
1,000	2,000	□130	SE03M	L7SA004A			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE06M	L7SA008A					
		□130	SE09M	L7SA010A					
		□130	SE12M	L7SA020A					
		□180	SF12M	L7SA020A			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SF20M	L7SA035A					
	1,700	□180	LF30M	L7SA035A					
	2,000	□180	SF44M	L7SA050A			XLCS-P□□□JS	XLCS-P□□□LB	
		□220	SG12M	L7SA020A			XLCS-P□□□IS		XLCS-P□□□SB
		□220	SG20M	L7SA035A					
	1,700	□220	LG30M	L7SA035A					
	2,000	□220	SG44M	L7SA050A			XLCS-P□□□JS		
3,000	3,500	□60	HB01A	L7SA002A	* 1,048P/R	XLCS-E□□□AS	XLCS-P□□□GS		
		□60	HB02A	L7SA002A					
		□60	HB04A	L7SA004A					
		□130	HE09A	L7SA008A	* 2,048P/R	XLCS-E□□□BS	XLCS-P□□□HS		
		□130	HE15A	L7SA020A					
		□130	HE30A	L7SA050A					

XDL-L7SA Serial Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable		Power Cable		
					Serial Type	Serial	Abs	For power	Power + Brake	Brake
3,000	5,000	□40	FALR5A	L7SA001B	* 18Bit Serial / M-Turn Abs	XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□LS		XLCS-P□□□QS
		□40	FAL01A	L7SA001B						
		□40	FAL015A	L7SA002B						
		□60	FBL01A	L7SA001B						
		□60	FBL02A	L7SA002B						
		□60	FBL04A	L7SA004B						
		□80	FCL04A	L7SA004B						
		□80	FCL06A	L7SA008B						
		□80	FCL08A	L7SA008B						
		□80	FCL10A	L7SA010B						
		□60	FB01A	L7SA001B				XLCS-P□□□FS		
		□60	FB02A	L7SA002B						
		□60	FB04A	L7SA004B						
		□80	FC04A	L7SA004B						
		□80	FC06A	L7SA008B						
		□80	FC08A	L7SA008B						
		□80	FC10A	L7SA010B						
		□130	FE09A	L7SA010B		XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE15A	L7SA020B						
		□130	FE22A	L7SA020B						
		□130	FE30A	L7SA035B						
		□180	FF30A	L7SA035B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF50A	L7SA050B				XLCS-P□□□JS	XLCS-P□□□LB	
2,000	3,000	□80	FCL03D	L7SA004B		XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□LS		XLCS-P□□□QS
		□80	FCL05D	L7SA008B						
		□80	FCL06D	L7SA008B						
		□80	FCL07D	L7SA008B						
		□80	FC03D	L7SA004B						
		□80	FC05D	L7SA008B				XLCS-P□□□FS		
		□80	FC06D	L7SA008B						
		□80	FC07D	L7SA008B						
		□130	FE06D	L7SA008B						
		□130	FE11D	L7SA010B	* 19Bit Serial / M-Turn Abs	XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE16D	L7SA020B						
		□130	FE22D	L7SA020B						
		□180	FF22D	L7SA020B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF35D	L7SA035B						
		□180	FF55D	L7SA050B				XLCS-P□□□JS	XLCS-P□□□LB	
	3,000	□220	FG22D	L7SA020B				XLCS-P□□□IS		XLCS-P□□□SB
	2,700	□220	FG35D	L7SA035B						
	3,000	□220	FG55D	L7SA050B				XLCS-P□□□JS		
1,500	3,000	□130	FE05G	L7SA008B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE09G	L7SA010B						
		□130	FE13G	L7SA020B						
		□130	FE17G	L7SA020B						
		□180	FF20G	L7SA020B				XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	FF30G	L7SA035B						
	3,000	□180	FF44G	L7SA050B				XLCS-P□□□JS	XLCS-P□□□LB	
	3,000	□220	FG20G	L7SA020B				XLCS-P□□□IS		XLCS-P□□□SB
	2,700	□220	FG30G	L7SA035B						
	3,000	□220	FG44G	L7SA050B				XLCS-P□□□JS		
1,000	2,000	□130	FE03M	L7SA004B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE06M	L7SA008B						
		□130	FE09M	L7SA010B						
		□130	FE12M	L7SA020B						
		□180	FF12M	L7SA020B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF20M	L7SA020B						
	1,700	□180	FF30M	L7SA035B						
	2,000	□180	FF44M	L7SA050B				XLCS-P□□□JS	XLCS-P□□□LB	
		□220	FG12M	L7SA020B				XLCS-P□□□IS		XLCS-P□□□SB
		□220	FG20M	L7SA020B						
	1,700	□220	FG30M	L7SA035B						
	2,000	□220	FG44M	L7SA050B				XLCS-P□□□JS		

Drive Combination Table

XDL-L7SB Serial Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable		Power Cable		
					Serial Type	Serial	Abs	For power	Power + Brake	Brake
3,000	5,000	□130	FEP09A	L7SB010B	* 19Bit Serial / M-Turn Abs	XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP15A	L7SB020B						
		□130	FEP22A	L7SB035B						
		□130	FEP30A	L7SB035B						
		□180	FFP30A	L7SB035B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FFP50A	L7SB050B				XLCS-P□□□JS	XLCS-P□□□LB	
2,000	3,000	□130	FEP06D	L7SB010B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP11D	L7SB010B						
		□130	FEP16D	L7SB020B						
		□130	FEP22D	L7SB020B						
		□180	FFP22D	L7SB020B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FFP35D	L7SB035B						
		□180	FFP55D	L7SB050B				XLCS-P□□□JS	XLCS-P□□□LB	
	2,500	□180	FFP75D	L7SB075B						
	3,000	□220	FGP22D	L7SB020B				XLCS-P□□□IS		XLCS-P□□□SB
		□220	FGP35D	L7SB035B						
		□220	FGP55D	L7SB050B				XLCS-P□□□JS		
	2,500	□220	FGP75D	L7SB075B						
		□220	FGP110D	L7SB150B				XLCS-P□□□MS		
1,500	3,000	□130	FEP05G	L7SB010B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP09G	L7SB010B						
		□130	FEP13G	L7SB020B						
		□130	FEP17G	L7SB020B						
		□180	FFP20G	L7SB020B				XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	FFP30G	L7SB035B						
	3,000	□180	FFP44G	L7SB050B				XLCS-P□□□JS	XLCS-P□□□LB	
	2,500	□180	FFP60G	L7SB075B						
	2,200	□180	FFP75G	L7SB075B				XLCS-P□□□MS		
	3,000	□220	FGP20G	L7SB020B				XLCS-P□□□IS		XLCS-P□□□SB
	2,700	□220	FGP30G	L7SB035B						
	3,000	□220	FGP44G	L7SB050B				XLCS-P□□□JS		
	2,500	□220	FGP60G	L7SB075B						
		□220	FGP85G	L7SB150B				XLCS-P□□□MS		
	2,000	□220	FGP110G	L7SB150B						
		□220	FGP150G	L7SB150B						
1,000	2,000	□130	FEP03M	L7SB010B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP06M	L7SB010B						
		□130	FEP09M	L7SB010B						
		□130	FEP12M	L7SB020B						
		□180	FFP12M	L7SB020B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FFP20M	L7SB020B						
	1,700	□180	FFP30M	L7SB035B				XLCS-P□□□JS	XLCS-P□□□LB	
	2,000	□180	FFP44M	L7SB050B						
		□220	FGP12M	L7SB020B				XLCS-P□□□IS		XLCS-P□□□SB
		□220	FGP20M	L7SB020B						
		□220	FGP30M	L7SB050B				XLCS-P□□□JS		
		□220	FGP44M	L7SB050B						
		□220	FGP60M	L7SB075B				XLCS-P□□□MS		

XDL-L7SA Drive

Item \ Type Name			XDL-L7SA001 □	XDL-L7SA002 □	XDL-L7SA004 □	XDL-L7SA008 □	XDL-L7SA010 □	XDL-L7SA020 □	XDL-L7SA035 □	XDL-L7SA050 □
Input Power	Main Power Supply		3 Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]							
	Control Power Supply		Single Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]							
Rated Current[A]			1.4	1.7	3.0	5.2	6.75	13.5	16.7	32
Peak Current[A]			4.2	5.1	9.0	15.6	20.25	40.5	50.1	96
Encoder Type			Quad. Type Incremental Line Driver Max 6000 [P/R] Serial Type 19Bit							
Control Performance	Speed Control	Speed Control Range	Maximum 1: 5000							
		Frequency Response	Maximum 1 [kHz] or above (When using 19bit Serial Encoder							
		Speed Command	DC -10 [V]~+10 [V] (Reverse rotation in case of negative voltage)							
		Accel/Decel Time	Straight or S-curve acceleration/deceleration (0-10,000 [ms], possible to be set by one [ms] unit)							
		Speed Variation Ratio	±0.01 [%] or lower [when load changes between 0 and 100%] ±0.1[%] or lower [temperature 25 ±10°C]							
	Position Control	Input Frequency	1[Mpps], Line Driver / 200[kpps], Open Collector							
		Input Pulse Type	Symbol + Pulse Series, CW+CCW, A/B Phase							
		Electric Gear Ratio	Four digital gear ratios can be set, selected and tuned.							
	Torque Control	Torque Command	DC-10~+10 [V] (Reverse direction torque in case of negative voltage)							
		Speed Limit	DC 0~10 [V], internal speed command within ±1[%]							
		Repetition accuracy	Within ±1[%]							
Input/Output Signal	Analog Input	Input Range	DC -10 ~ 10[V]							
		Resolution	12[bit]							
	Analog Output	Output Range	DC -10 ~ 10[V]							
		Resolution	12[bit]							
	Digital Input		Total 10 Input Channels(assignment available) SVON, SPD1, SPD2, SPD3, ALMRST, DIR, CCWLIM, CWLIM, EMG, STOP, EGEAR1, EGEAR2, PCON, GAIN2, P_CLR, T_LMT, MODE, ABS_RQ, ZCLAMP Above 19 functions can be used selectively for assignment Signal can be set as positive logic or negative logic							
	Digital Output		Total 5 Channels(assignment available), 3 Channels(set as alarm code) ALARM, READY, ZSPD, BRAKE, INPOS, TLMT, VLMT, INSPD, WARN Above 9 outputs can be used selectively for assignment Signal can be set as positive logic or negative logic							
Communication	RS-422		Accessible to PC software and the RS422 server							
	USB		Status monitoring, JOG operation, parameter upload/download are available with PC Software							
Encoder			Serial BiSS encoder and quadrature encoder supported							
Encoder Output Type			Random pre-scale output through FPGA (maximum 6.4 Mpps)							
Built-in functions	Dynamic Braking		Standard built-in (activated when the servo alarm goes off or when the servo is off)							
	Regenerative Braking		Both default built-in and external installation possible							
	Display		Seven segments (5 DIGIT)							
	Setting Function		Loader (SET, MODE, UP, and [DOWN] keys)							
	Additional Function		Auto gain tuning, phase Z detection, manual JOG operation, program JOG operation, automatic analog input calibration							
	Protective Function		Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheat(power module overheat, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem							
Environment	Temperature		0 ~ 50[°C]							
	Humidity		Below 90[%]RH(avoid dew-condensation)							
	Environment		Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust.							

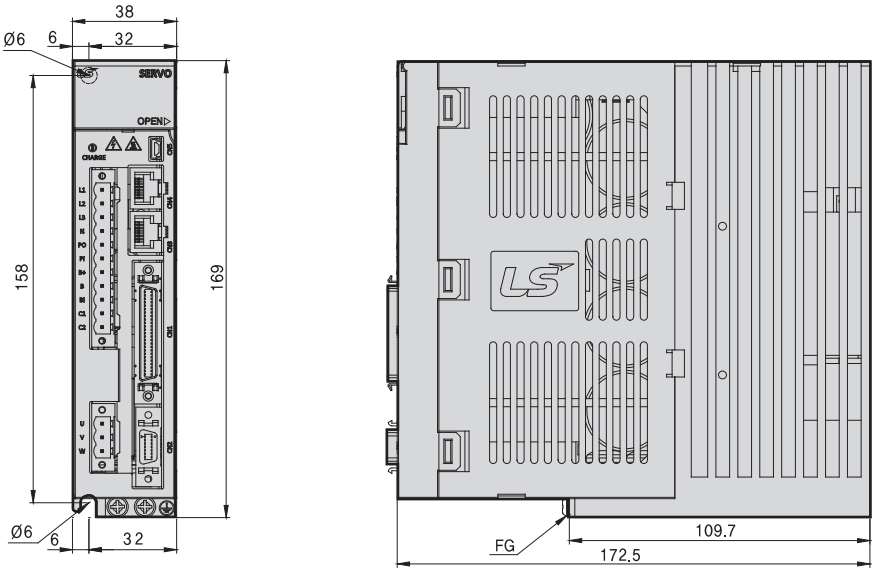
XDL-L7SB Drive

Item \ Type Name			XDL-L7SB010□	XDL-L7SB020□	XDL-L7SB035□	XDL-L7SB050□	XDL-L7SB075□	XDL-L7SB150□
Input Power	Main Power Supply		3 Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz]					
	Control Power Supply		Single Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz]					
Rated Current[A]			3.7	8	10.1	17.5	22.8	39
Peak Current[A]			11.1	24	30.3	52.5	57	97.5
Encoder Type			Quad. Type Incremental Line Driver Max 6000 [P/R] Serial Type 19Bit					
Control Performance	Speed Control	Speed Control Range	Maximum 1: 5000					
		Frequency Response	Maximum 1 [kHz] or above (when the 19-bit serial encoder is applied)					
		Speed Command	DC -10 [V]~+10 [V] (Reverse rotation in case of negative voltage)					
		Accel/Decel Time	Straight or S-curve acceleration/deceleration (0-10,000 [ms], possible to be set by one [ms] unit)					
		Speed Variation Ratio	±0.01 [%] or lower [when load changes between 0 and 100%], ±0.1[%] or lower [temperature 25 ±10°C]					
	Position Control	Input Frequency	1[Mpps], Line Driver / 200[kpps], Open Collector					
		Input Pulse Type	Symbol + pulse series, CW+CCW, A/B phase					
		Electric Gear Ratio	Four digital gear ratios can be set, selected and tuned.					
	Torque Control	Torque Command	DC-10~+10 [V] (Reverse direction torque in case of negative voltage)					
		Speed Limit	DC 0~10 [V], internal speed command within ±1[%]					
		Repetition accuracy	Within ±1[%]					
Input/Output Signal	Analog Input	Input Range	DC 0 ~ 10[V]					
		Resolution	12[bit]					
	Analog Output	Output Range	DC 0 ~ 10[V]					
		Resolution	12[bit]					
	Digital Input		A total of 10 input channels (allocable) SVON, SPD1, SPD2, SPD3, ALMRST, DIR, CCWLIM, CWLIM, EMG, STOP, EGEAR1, EGEAR2, PCON, GAIN2, P_CLR, T_LMT, MODE, ABS_RQ, ZCLAMP You can selectively allocate a total of 19 functions. You can set the positive/negative logic of the selected signal.					
	Digital Output		A total of 5 channels (allocable), 3 channels (fixed with alarm codes) ALARM, READY, ZSPD, BRAKE, INPOS, TLMT, VLMT, INSPD, WARN You can selectively allocate a total of nine kinds of output. You can set the positive/negative logic of the selected signal.					
Communication	RS-422		Accessible to PC software and the RS422 server					
	USB		Status monitoring through PC software, JOG operation, and parameter uploading/downloading are possible.					
Encoder			Serial BiSS encoder and quadrature encoder supported					
Encoder Output Type			Random pre-scale output through FPGA (maximum 6.4 Mpps)					
Built-in functions	Dynamic Braking		Standard built-in (activated when the servo alarm goes off or when the servo is off)					
	Regenerative Braking		Both default built-in and external installation possible					
	Display		Seven segments (5 DIGIT)					
	Setting Function		Loader (SET, MODE, UP, and [DOWN] keys)					
	Additional Function		Auto gain tuning, phase Z detection, manual JOG operation, program JOG operation, automatic analog input calibration					
	Protective Function		Overcurrent, overload, overvoltage, voltage lack, main power input error, control power input error, overspeed, motor cable, heating error (power module heating, drive temperature error), encoder error, excessive regeneration, sensor error, communication error					
Environment	Temperature		0 ~ 50[°C]					
	Humidity		90[%] RH or lower (no condensation)					
	Environment		Indoors, a place free from corrosive gas or combustible gas, or a place without liquid or conductive dust.					

External Dimensions

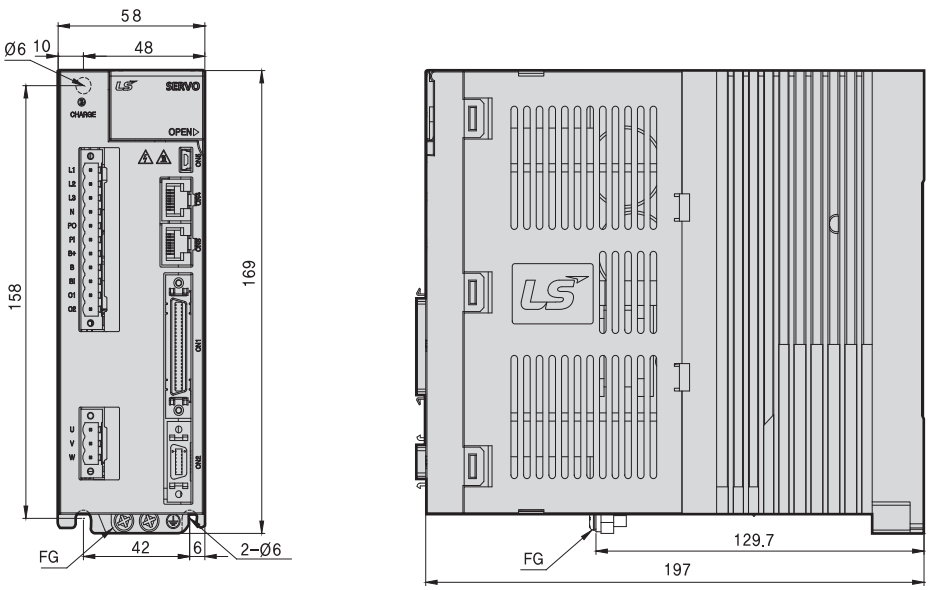
XDL-L7SA001□~XDL-L7SA004□ [Weight1.2kg]

*Unit [mm]



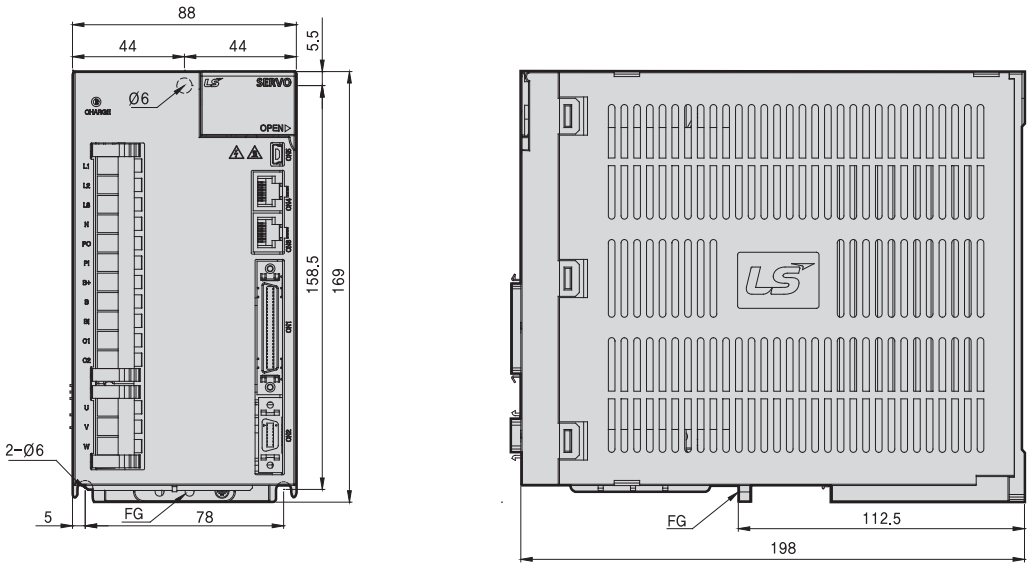
XDL-L7SA008□~XDL-L7SA010□ [Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]



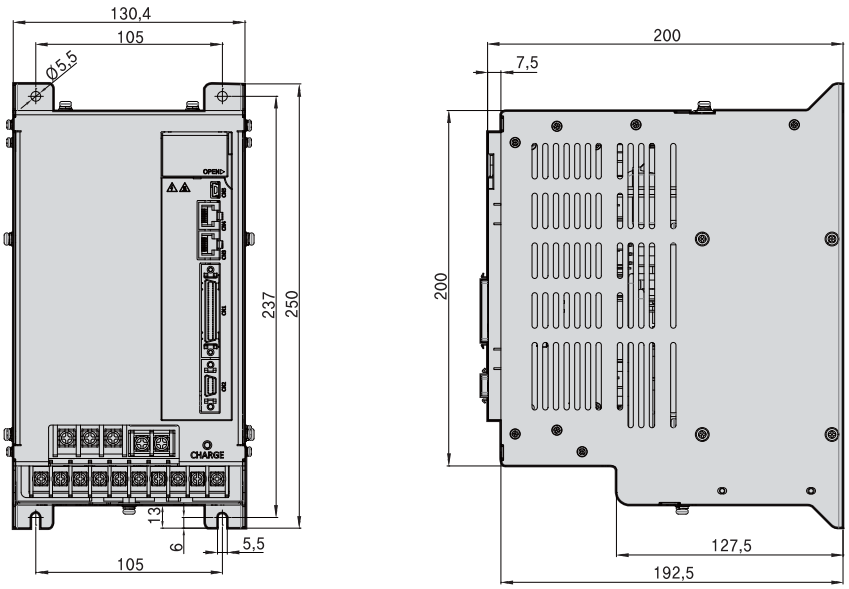
XDL-L7SA020□ ~ XDL-L7SA035□ [Weight : 2.5kg(Fan-Cooling included)]

*Unit [mm]



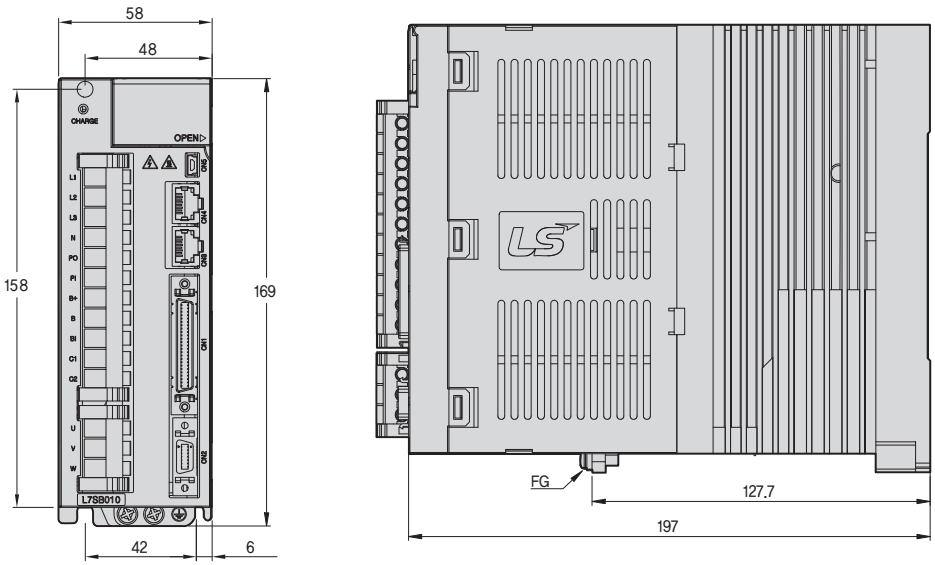
XDL-L7SA050□ [Weight : 5.5kg(Fan-Cooling included)]

*Unit [mm]



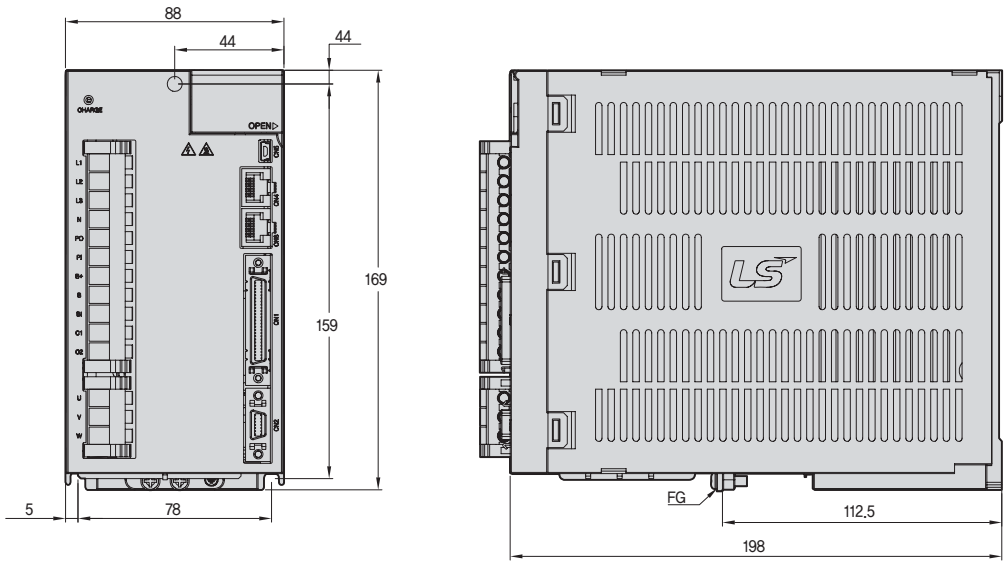
XDL-L7SB010□[Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7SB020□/ XDL-L7SB035□[Weight : 2.5kg(Fan-Cooling included)]

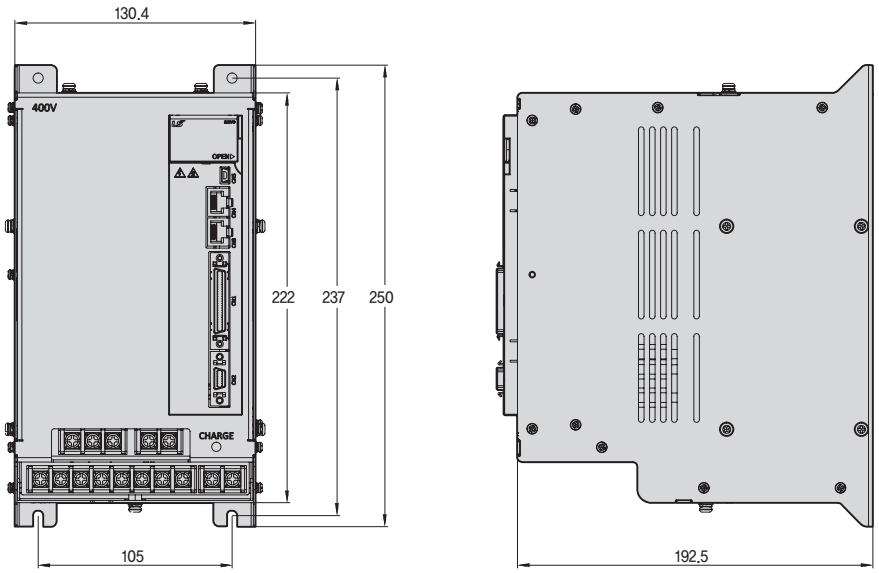
*Unit [mm]



External Dimensions

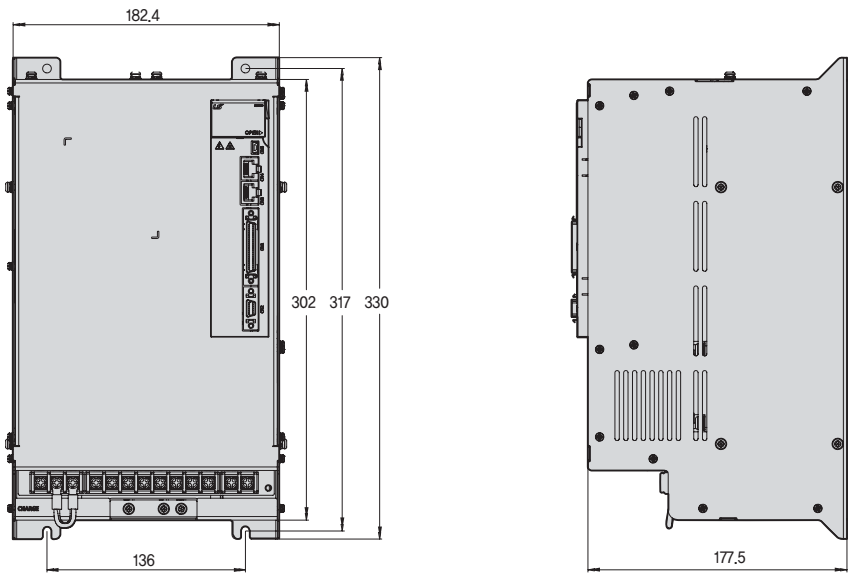
XDL-L7SB050□ [Weight : 5.5kg(Fan-Cooling included)]

*Unit [mm]



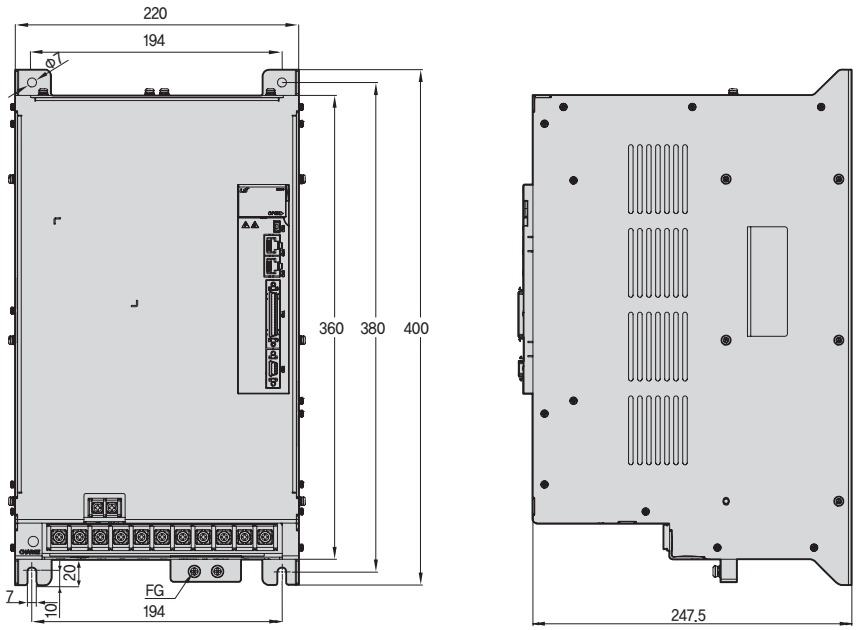
XDL-L7SA075□ [Weight : 8.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7SB150□ [Weight : 15.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7N Series



Servo Drive Designation

XDL	-	L7	N	A	004	B	AA

Model Name	Communication	Input Power Supply	Capacity	Encoder Type	Option
XDL Series	Network Type	A : 200VAC	001 : 100W	B : Serial (Communication Type)	Exclusive Option Code
			002 : 200W		
			004 : 400W		
			008 : 750W		
			010 : 1.0kW		
			020 : 2.0kW		
			035 : 3.5kW		
			050 : 5.0kW		

EtherCAT Communication Type XDL-L7N

Real-time control by EtherCAT

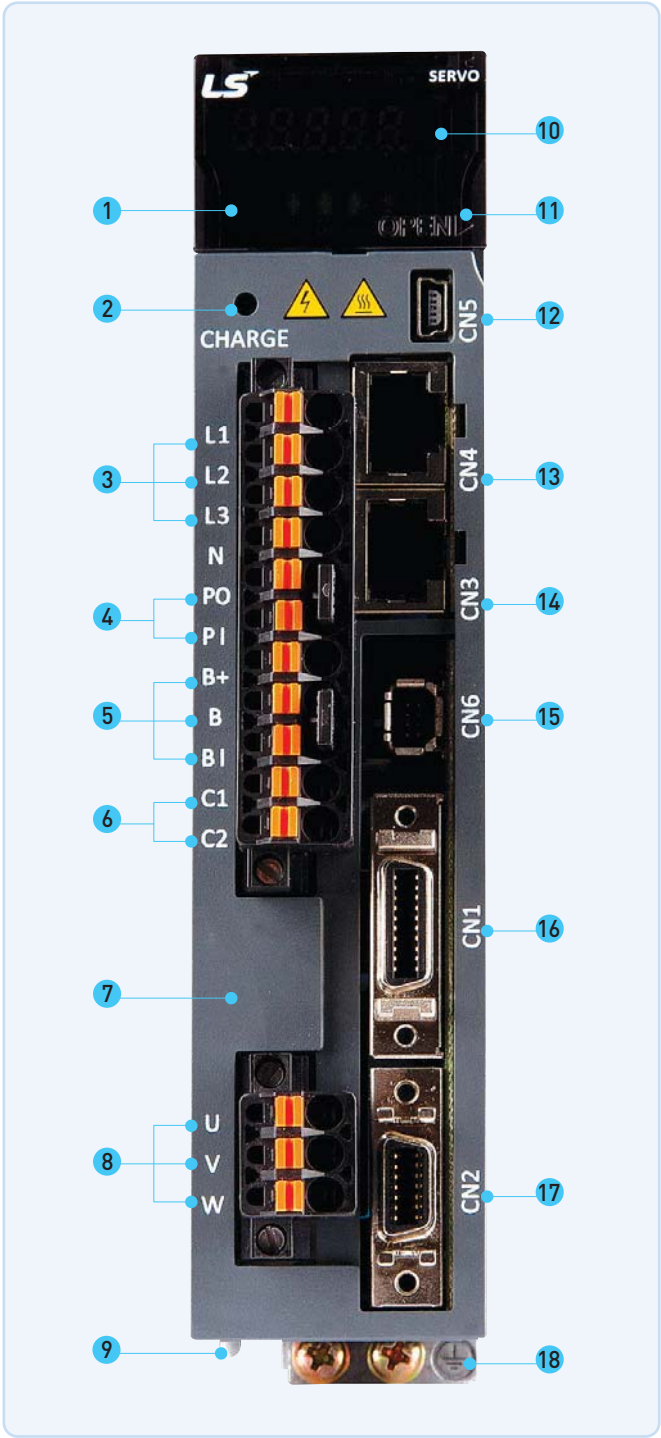
- High speed, Real-time capability and Synchronization mechanism
- 100BASE-TX(100Mbps) EtherNET based real-time communication

Support Various Operation Mode

- Cyclic(P/S/T) Mode and Profile (P/S/T)Mode, Homing Mode

High Response for Precision Control

- High Resolutions Serial type Encoder(19Bit, BiSS)
- Improved Speed Response(=1Khz) Frequency



1. Operation keys (Mode, Up, Down, Set)
2. Charge lamp
3. Main power connector (L1, L2, L3)
4. DC reactor connector(PO, PI)
   - Short circuit when not used
5. Regenerative Resistor Connector (B+, B, BI)
   - Short-Circuit B, BI terminals when standard type
   - Use B+, B terminals when using external resistor
6. Control Power Connector (C1, C2)
7. Front cover
8. Servo Motor Connecting Terminals (U, V, W)
9. Heat Sink
10. Display
11. Status LED
12. CN5:USB connector
13. CN4:EtherCAT Communication Port (IN)
14. CN3:EtherCAT Communication Port (OUT)
15. CN6 : STO Connector
16. CN1 : Control Signal Connector
17. CN2 : Encoder Signal Connector
18. Ground

XDL Drive Combination Table

XDL-L7N Serial Type

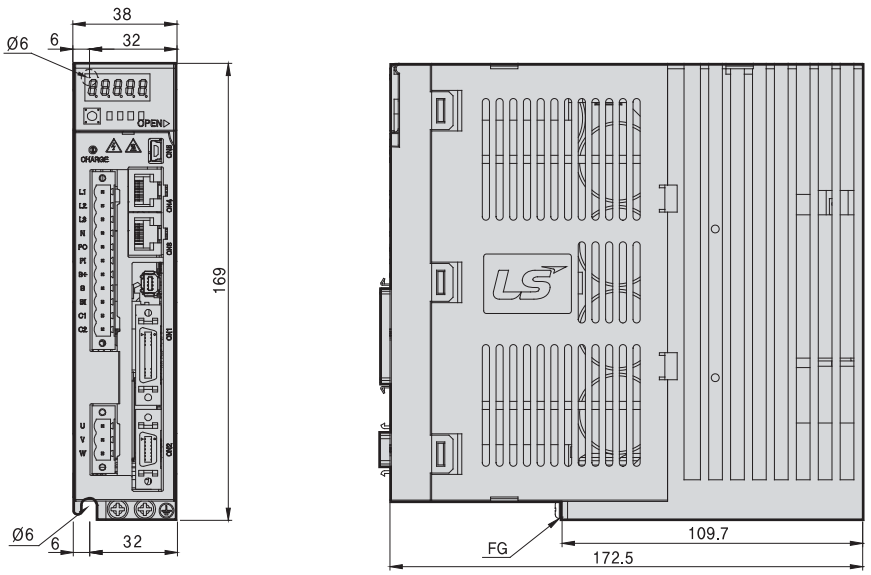
Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable		Power Cable		
					Serial Type	Serial	Abs	For power	Power + Brake	Brake
3,000	5,000	□40	FALR5A	L7NA001B	* 18Bit Serial / M-Turn Abs	XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□LS		XLCS-P□□□QS
		□40	FAL01A	L7NA001B						
		□40	FAL015A	L7NA002B						
		□60	FBL01A	L7NA001B	* 19Bit Serial / M-Turn Abs					
		□60	FBL02A	L7NA002B						
		□60	FBL04A	L7NA004B						
		□80	FCL04A	L7NA004B						
		□80	FCL06A	L7NA008B						
		□80	FCL08A	L7NA008B						
		□80	FCL10A	L7NA010B						
		□60	FB01A	L7NA001B				XLCS-P□□□FS		
		□60	FB02A	L7NA002B						
		□60	FB04A	L7NA004B						
		□80	FC04A	L7NA004B						
		□80	FC06A	L7NA008B						
		□80	FC08A	L7NA008B						
		□80	FC10A	L7NA010B						
		□130	FE09A	L7NA010B		XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE15A	L7NA020B						
		□130	FE22A	L7NA020B						
		□130	FE30A	L7NA035B						
		□180	FF30A	L7NA035B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF50A	L7NA050B				XLCS-P□□□JS	XLCS-P□□□LB	
2,000	3,000	□80	FCL03D	L7NA004B		XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□LS		XLCS-P□□□QS
		□80	FCL05D	L7NA008B						
		□80	FCL06D	L7NA008B						
		□80	FCL07D	L7NA008B						
		□80	FC03D	L7NA004B				XLCS-P□□□FS		
		□80	FC05D	L7NA008B						
		□80	FC06D	L7NA008B						
		□80	FC07D	L7NA008B						
		□130	FE06D	L7NA008B		XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE11D	L7NA010B						
		□130	FE16D	L7NA020B						
		□130	FE22D	L7NA020B						
		□180	FF22D	L7NA020B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF35D	L7NA035B						
		□180	FF55D	L7NA050B				XLCS-P□□□JS	XLCS-P□□□LB	
	3,000	□220	FG22D	L7NA020B				XLCS-P□□□IS		XLCS-P□□□SB
	2,700	□220	FG35D	L7NA035B						
	3,000	□220	FG55D	L7NA050B				XLCS-P□□□JS		
1,500	3,000	□130	FE05G	L7NA008B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE09G	L7NA010B						
		□130	FE13G	L7NA020B						
		□130	FE17G	L7NA020B						
		□180	FF20G	L7NA020B				XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	FF30G	L7NA035B						
	3,000	□180	FF44G	L7NA050B				XLCS-P□□□JS	XLCS-P□□□LB	
	3,000	□220	FG20G	L7NA020B				XLCS-P□□□IS		XLCS-P□□□SB
	2,700	□220	FG30G	L7NA035B						
	3,000	□220	FG44G	L7NA050B				XLCS-P□□□JS		
1,000	2,000	□130	FE03M	L7NA004B				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE06M	L7NA008B						
		□130	FE09M	L7NA010B						
		□130	FE12M	L7NA020B						
		□180	FF12M	L7NA020B				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF20M	L7NA020B						
	1,700	□180	FF30M	L7NA035B						
	2,000	□180	FF44M	L7NA050B				XLCS-P□□□JS	XLCS-P□□□LB	
		□220	FG12M	L7NA020B				XLCS-P□□□IS		XLCS-P□□□SB
		□220	FG20M	L7NA020B						
	1,700	□220	FG30M	L7NA035B						
	2,000	□220	FG44M	L7NA050B				XLCS-P□□□JS		

XDL-L7NA Drive

Item \ Type Name		XDL-L7NA001B	XDL-L7NA002B	XDL-L7NA004B	XDL-L7NA008B	XDL-L7NA010B	XDL-L7NA020B	XDL-L7NA035B	XDL-L7NA050B
Input Power	Main Power Supply	3 Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]							
	Control Power Supply	Single Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]							
Rated Current[A]		1.4	1.7	3.0	5.2	6.75	13.5	16.7	32
Peak Current[A]		4.2	5.1	9.0	15.6	20.25	40.5	50.1	96
Encoder Type		Quad. Type Incremental Line Driver Max 6000 [P/R] Serial Type 19Bit							
Control Performance	Speed Control Range	Maximum 1: 5000							
	Frequency Response	Maximum 1 kHz or more (when the 19-bit serial encoder is applied)							
	Speed Variation Ratio	±0.01[%] or lower(When the load changes between 0 and 100%), ±0.1[%] or less(Temperature of 25°C[±10]							
	Torque Control Repetition Accuracy	Within ±1%							
Supported Drive Modes (CiA402)		Profile Position Mode Profile Velocity Mode Profile Torque Mode Interpolated Position Mode Cyclic Synchronous Position Mode Cyclic Synchronous Velocity Mode Cyclic Synchronous Torque Mode Homing Mode							
Digital Input/ Output	Digital Input	Total 6 input channels (allocable) PCON, GAIN2, ALMRST, HOME, P-OT, N-OT Above 6 functions can be used selectively for assignment. Signal can be set as positive logic or negative logic.							
	Touch Probe Input	There are 2 input channels. Provides rising and falling edge detection functions for each channel.							
	Digital Output	Total 4 channels (allocable) ALARM, READY, ZSPD, BRAKE, INPOS, INSPD, WARN Above 7 outputs can be used selectively for assignment. Signal can be set as positive logic or negative logic.							
Additional Communication	USB	Program download is available with USB Communication.							
Built-in Functions	Dynamic Braking	Built-in type(operates when Servo alarm or Servo off)							
	Regenerative Braking	Built-in type, and also external connection is available							
	Display	7 segments(5DIGIT)							
	Setting Function	Loder(SET), (MODE)							
	Additional Function	Auto gain tuning function							
	Protective Function	Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheat(power module overheat, abnormal drive operation°Øs temp), encoder problem, over-regenerative, sensor problem, communication problem							
Operation Environment	Temperature	0 ~ 50[°C]							
	Humidity	Below 90[%]RH(avoid dew-condensation)							
	Environment	Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust.							

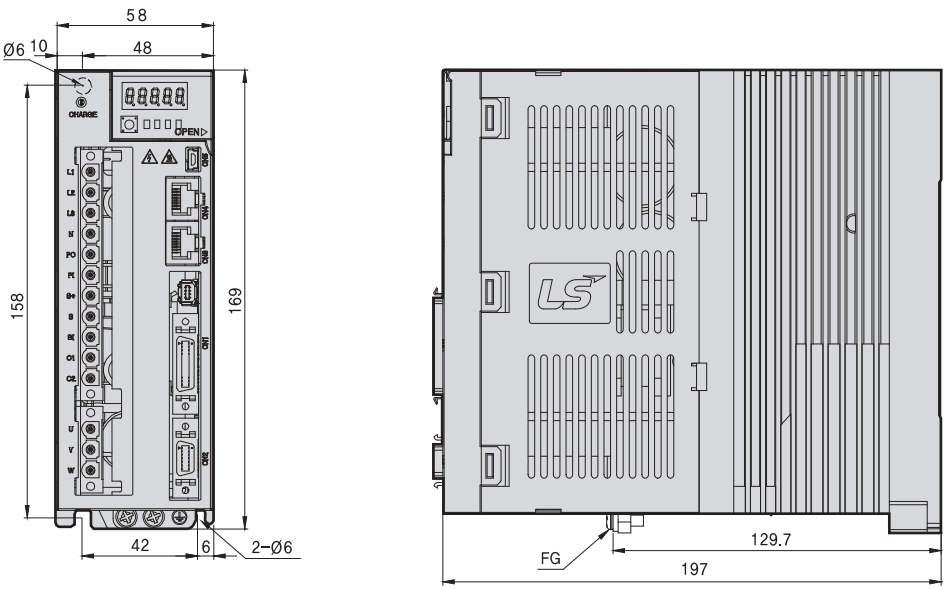
XDL-L7NA001B ~ XDL-L7NA004B[Weight : 1.2kg]

*Unit [mm]



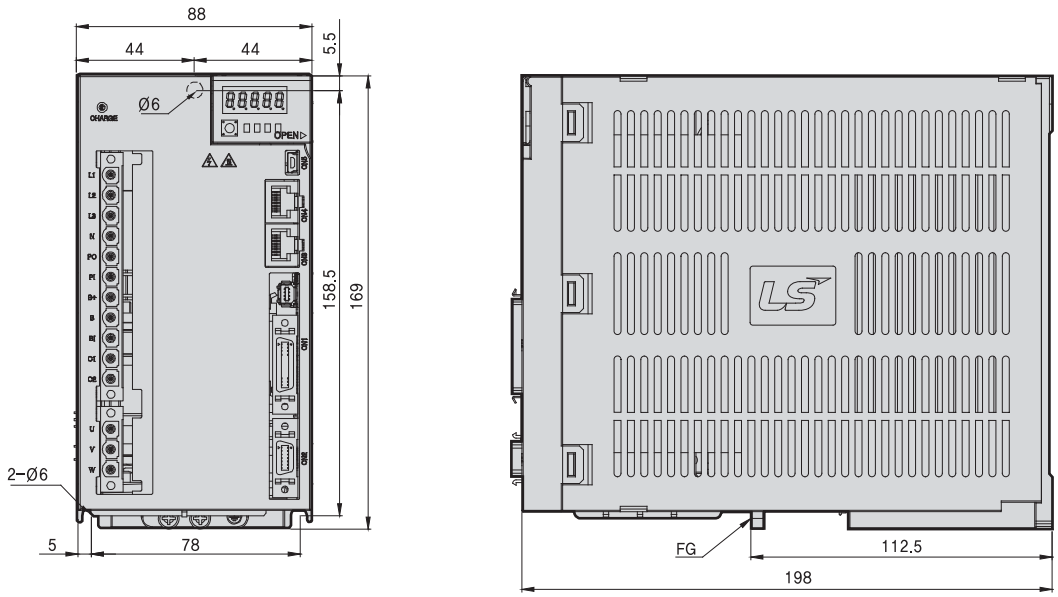
XDL-L7NA008B / XDL-L7NA010B[Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]



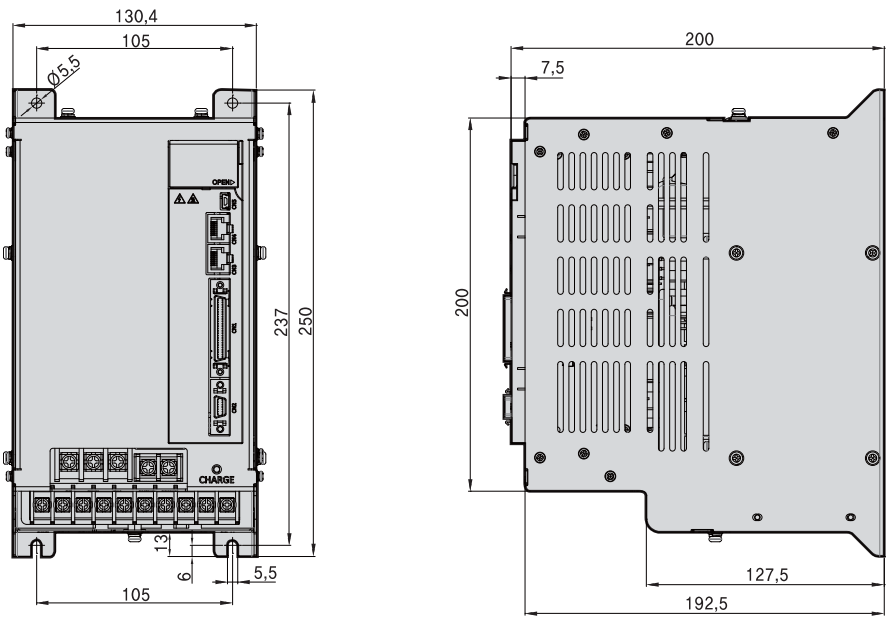
XDL-L7NA020B / XDL-L7NA035B[Weight : 2.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7NA050B[Weight : 5.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7NH Series



Servo Drive Designation

XDL	-	L7	NH	A	004	B	AA
Model Name			Communication	Input Power Supply	Capacity	Encoder Type	Option
XDL Series			Network / All-in-One Type	A:200VAC B:400VAC	001:100W 002:200W 004:400W 008:750W 010:1.0kW 020:2.0kW 035:3.5kW 050:5.0kW 075:7.5kW 110:11kW 150:15kW	U:Universal	Exclusive Option Code

* Range

- 200V : 0.1kW~3.5kW
- 400V : 1.0kW~15kW

All-in-One EtherCAT Communication Type XDL-L7NH

Real-time control through EtherCAT

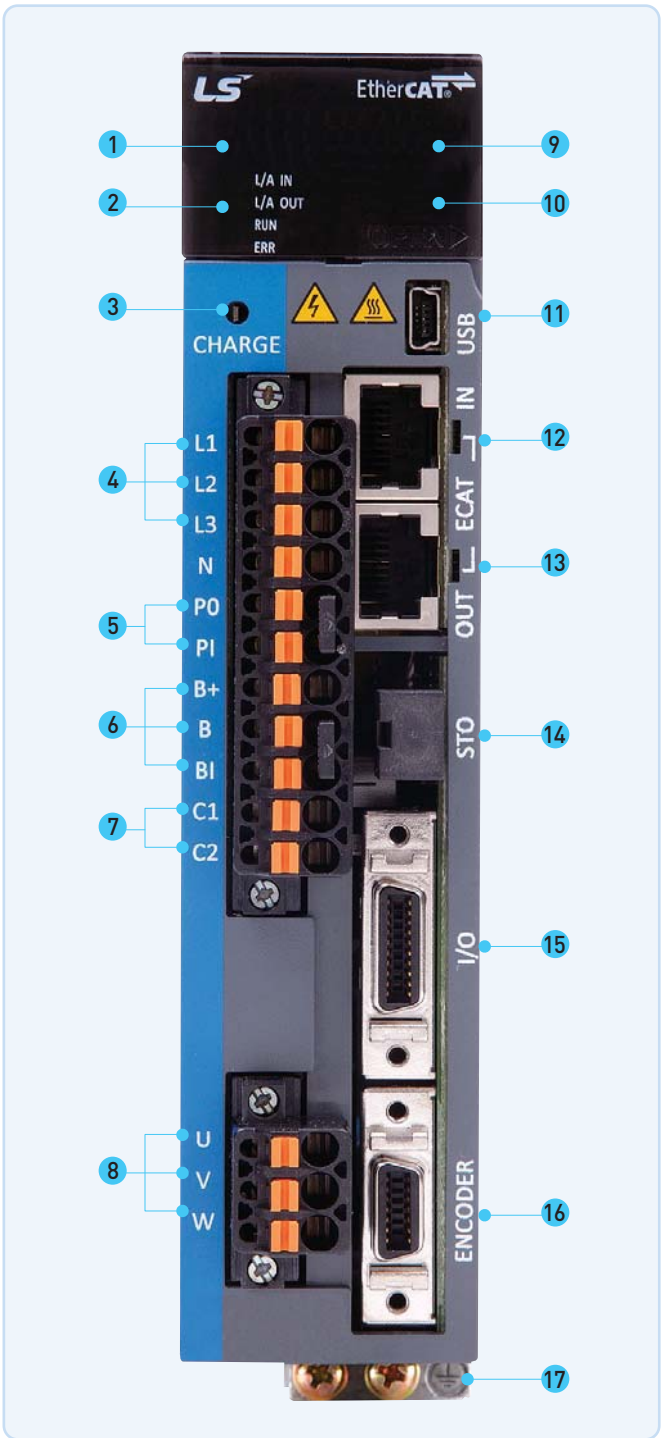
- High speed, Real-time capability and Synchronization mechanism
- Improved EtherCAT communication speed (min. 250us, DC support)
- Supporting CoE, EoE and FoE
- Improved Speed Response(=1.6Khz) Frequency

Support various motor and Encoder drive

- Supporting Rotary, DD and Motor drive (supporting3rd party motor)
- Quadrature, BiSS-C, Tamagawa serial abs, EnDat 2.2, Resolver

Improved Control Performance

- Improved Control bandwidth
- Providing 4-step Notch-Filter
- Vibration control by Real-time FET
- Real-time gain tuning function



1. Display
2. State LED
3. Charge Lamp
4. Main Power Connector (L1, L2, L3)
5. DC Reactor Connector (P0, PI)
6. Regenerative Resistance Connector (B+, B, BI)
   - Short-Circuit B, BI terminals when standard type
   - Use B+, B terminals when using external resistor
7. Control Power Connector (C1, C2)
8. Servo Motor Connecting Terminal (U,V,W)
9. Connector for Analog Monitor
10. Node Address Setting Switch
11. USB Connector
12. EtherCAT Communication Port (IN)
13. EtherCAT Communication Port (OUT)
14. Safety Connector (STO)
15. Input / Output signal /Connector
16. Encoder Connector (ENCODER)
17. Ground Terminal

Drive Combination Table

XDL-L7NHA Incremental Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable	Power Cable		
					Quadrature Type	INC	For power	Power + Brake	Brake
3,000	5,000	□40	SAR3A	L7NHA001U	* 2,048P/R	XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□KB
		□40	SAR5A	L7NHA001U					
		□40	SA01A	L7NHA001U					
		□40	SA015A	L7NHA002U					
		□60	SB01A	L7NHA002U	* 3,000P/R				
		□60	SB02A	L7NHA002U					
		□60	SB04A	L7NHA004U					
		□80	SC04A	L7NHA004U					
		□80	SC06A	L7NHA008U					
		□80	SC08A	L7NHA008U					
		□80	SC10A	L7NHA010U					
		□130	SE09A	L7NHA008U		XLCS-E□□□BS	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE15A	L7NHA020U					
		□130	SE22A	L7NHA020U					
		□180	SF30A	L7NHA035U			XLCS-P□□□IS	XLCS-P□□□PB	
2,000	3,000	□80	SC03D	L7NHA004U		XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□QS
		□80	SC05D	L7NHA008U					
		□80	SC06D	L7NHA008U					
		□80	SC07D	L7NHA008U					
		□130	SE06D	L7NHA008U		XLCS-E□□□BS	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE11D	L7NHA010U					
		□130	SE16D	L7NHA020U					
		□130	SE22D	L7NHA020U					
		□180	SF22D	L7NHA020U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	LF35D	L7NHA035U					
		□220	SG22D	L7NHA020U					XLCS-P□□□SB
		□220	LG35D	L7NHA035U					
1,500	3,000	□130	SE05G	L7NHA008U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE09G	L7NHA010U					
		□130	SE13G	L7NHA020U					
		□130	SE17G	L7NHA020U					
		□180	SF20G	L7NHA035U			XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	LF30G	L7NHA035U					
	3,000	□220	SG20G	L7NHA020U					XLCS-P□□□SB
	2,700	□220	LG30G	L7NHA035U					
1,000	2,000	□130	SE03M	L7NHA004U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE06M	L7NHA008U					
		□130	SE09M	L7NHA010U					
		□130	SE12M	L7NHA020U					
		□180	SF12M	L7NHA020U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SF20M	L7NHA035U					
	1,700	□180	LF30M	L7NHA035U					
	2,000	□220	SG12M	L7NHA020U			XLCS-P□□□IS		
		□220	SG20M	L7NHA035U					
	1,700	□220	LG30M	L7NHA035U					
3,000	3,500	□60	HB01A	L7NHA002U	* 1,048P/R	XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□SB
		□60	HB02A	L7NHA002U					
		□60	HB04A	L7NHA004U					
		□130	HE09A	L7NHA008U	* 1,048P/R	XLCS-E□□□BS	XLCS-P□□□HS		
		□130	HE15A	L7NHA020U					

XDL-L7NHA Serial Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable		Power Cable		
					Serial Type	Serial	Abs	For power	Power + Brake	Brake
3,000	5,000	□40	FALR5A	L7NHA001U	* 18Bit Serial / M-Turn Abs	XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□LS		XLCS-P□□□QS
		□40	FAL01A	L7NHA001U						
		□40	FAL015A	L7NHA002U						
		□60	FBL01A	L7NHA001U	* 19Bit Serial / M-Turn Abs					
		□60	FBL02A	L7NHA002U						
		□60	FBL04A	L7NHA004U						
		□80	FCL04A	L7NHA004U						
		□80	FCL06A	L7NHA008U						
		□80	FCL08A	L7NHA008U						
		□80	FCL10A	L7NHA010U						
		□60	FB01A	L7NHA001U				XLCS-P□□□FS		
		□60	FB02A	L7NHA002U						
		□60	FB04A	L7NHA004U						
		□80	FC04A	L7NHA004U						
		□80	FC06A	L7NHA008U						
		□80	FC08A	L7NHA008U						
		□80	FC10A	L7NHA010U						
		□130	FE09A	L7NHA010U		XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE15A	L7NHA020U						
		□130	FE22A	L7NHA020U						
		□130	FE30A	L7NHA035U						
		□180	FF30A	L7NHA035U				XLCS-P□□□IS	XLCS-P□□□PB	
2,000	3,000	□80	FCL03D	L7NHA004U		XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□LS		XLCS-P□□□QS
		□80	FCL05D	L7NHA008U						
		□80	FCL06D	L7NHA008U						
		□80	FCL07D	L7NHA008U						
		□80	FC03D	L7NHA004U				XLCS-P□□□FS		
		□80	FC05D	L7NHA008U						
		□80	FC06D	L7NHA008U						
		□80	FC07D	L7NHA008U						
		□130	FE06D	L7NHA008U		XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE11D	L7NHA010U						
		□130	FE16D	L7NHA020U						
		□130	FE22D	L7NHA020U						
		□180	FF22D	L7NHA020U				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF35D	L7NHA035U						
		□220	FG22D	L7NHA020U						XLCS-P□□□SB
		□220	FG35D	L7NHA035U						
1,500	3,000	□130	FE05G	L7NHA008U				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE09G	L7NHA010U						
		□130	FE13G	L7NHA020U						
		□130	FE17G	L7NHA020U						
		□180	FF20G	L7NHA020U				XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	FF30G	L7NHA035U						
	3,000	□220	FG20G	L7NHA020U						XLCS-P□□□SB
	2,700	□220	FG30G	L7NHA035U						
1,000	2,000	□130	FE03M	L7NHA004U				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FE06M	L7NHA008U						
		□130	FE09M	L7NHA010U						
		□130	FE12M	L7NHA020U						
		□180	FF12M	L7NHA020U				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FF20M	L7NHA020U						
	1,700	□180	FF30M	L7NHA035U						
	2,000	□220	FG12M	L7NHA020U				XLCS-P□□□IS		XLCS-P□□□SB
		□220	FG20M	L7NHA020U						
	1,700	□220	FG30M	L7NHA035U						

Drive Combination Table

XDL-L7NHB Incremental Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable	Power Cable		
					Quadrature Type	INC	For power	Power + Brake	Brake
3,000	5,000	□130	SEP09A	L7NHB010U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SEP15A	L7NHB010U					
		□130	SEP22A	L7NHB020U					
		□130	SEP30A	L7NHB035U					
		□180	SFP30A	L7NHB035U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SFP50A	L7NHB050U			XLCS-P□□□JS	XLCS-P□□□LB	
2,000	3,000	□130	SEP06D	L7NHB010U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SEP11D	L7NHB010U					
		□130	SEP16D	L7NHB020U					
		□130	SEP22D	L7NHB020U					
		□180	SFP22D	L7NHB020U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SFP35D	L7NHB035U					
		□180	SFP55D	L7NHB050U			XLCS-P□□□JS	XLCS-P□□□LB	
		□180	SFP75D	L7NHB075U					
		□220	SGP22D	L7NHB020U			XLCS-P□□□IS		XLCS-P□□□SB
		□220	SGP35D	L7NHB035U					
		□220	SGP55D	L7NHB050U			XLCS-P□□□JS		
	2,500	□220	SGP75D	L7NHB075U					
		□220	SGP110D	L7NHB150U			XLCS-P□□□MS		
1,500	3,000	□130	SEP05G	L7NHB010U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SEP09G	L7NHB010U					
		□130	SEP13G	L7NHB020U					
		□130	SEP17G	L7NHB020U					
		□180	SFP20G	L7NHB020U	* 3,000P/R	XLCS-E□□□BS	XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SFP30G	L7NHB050U					
		□180	SFP44G	L7NHB050U			XLCS-P□□□JS	XLCS-P□□□LB	
		□180	SFP60G	L7NHB075U					
	2,500	□180	SFP75G	L7NHB075U			XLCS-P□□□MS		
		□220	SGP20G	L7NHB020U			XLCS-P□□□IS		XLCS-P□□□SB
		□220	SGP30G	L7NHB050U					
	3,000	□220	SGP44G	L7NHB050U			XLCS-P□□□JS		
	2,500	□220	SGP60G	L7NHB075U					
		□220	SGP85G	L7NHB150U			XLCS-P□□□MS		
	2,000	□220	SGP110G	L7NHB150U					
		□220	SGP150G	L7NHB150U					
1,000	2,000	□130	SEP03M	L7NHB010U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SEP06M	L7NHB010U					
		□130	SEP09M	L7NHB010U					
		□130	SEP12M	L7NHB020U					
		□180	SFP12M	L7NHB020U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SFP20M	L7NHB020U					
	1,700	□180	SFP30M	L7NHB035U			XLCS-P□□□JS	XLCS-P□□□LB	
	2,000	□180	SFP44M	L7NHB050U					
		□220	SGP12M	L7NHB020U			XLCS-P□□□IS		XLCS-P□□□SB
		□220	SGP20M	L7NHB020U					
		□220	SGP30M	L7NHB050U			XLCS-P□□□JS		
		□220	SGP44M	L7NHB050U					
		□220	SGP60M	L7NHB075U			XLCS-P□□□MS		

XDL-L7NHB Serial Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable		Power Cable		
					Serial Type	Serial	Abs	For power	Power + Brake	Brake
3,000	5,000	□130	FEP09A	L7NHB010U	* 19Bit Serial / M-Turn Abs	XLCS-E□□□DS	XLCS-E□□□DS1	XLCS-P□□□HS	XLCS-P□□□NB	XLCS-P□□□SB
		□130	FEP15A	L7NHB020U						
		□130	FEP22A	L7NHB035U						
		□130	FEP30A	L7NHB035U						
		□180	FFP30A	L7NHB035U				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FFP50A	L7NHB050U				XLCS-P□□□JS	XLCS-P□□□LB	
2,000	3,000	□130	FEP06D	L7NHB010U				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP11D	L7NHB010U						
		□130	FEP16D	L7NHB020U						
		□130	FEP22D	L7NHB020U						
		□180	FFP22D	L7NHB020U				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FFP35D	L7NHB035U						
		□180	FFP55D	L7NHB050U				XLCS-P□□□JS	XLCS-P□□□LB	
	2,500	□180	FFP75D	L7NHB075U						
	3,000	□220	FGP22D	L7NHB020U				XLCS-P□□□IS		
	2,700	□220	FGP35D	L7NHB035U						
	3,000	□220	FGP55D	L7NHB050U				XLCS-P□□□JS		
	2,500	□220	FGP75D	L7NHB075U						
		□220	FGP110D	L7NHB150U				XLCS-P□□□MS		
1,500	3,000	□130	FEP05G	L7NHB010U				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP09G	L7NHB010U						
		□130	FEP13G	L7NHB020U						
		□130	FEP17G	L7NHB020U						
		□180	FFP20G	L7NHB020U						
	2,700	□180	FFP30G	L7NHB050U				XLCS-P□□□IS	XLCS-P□□□PB	
	3,000	□180	FFP44G	L7NHB050U				XLCS-P□□□JS	XLCS-P□□□LB	
	2,500	□180	FFP60G	L7NHB075U						
	2,200	□180	FFP75G	L7NHB075U				XLCS-P□□□MS		
	3,000	□220	FGP20G	L7NHB020U				XLCS-P□□□IS		
	2,700	□220	FGP30G	L7NHB035U						
	3,000	□220	FGP44G	L7NHB050U				XLCS-P□□□JS		
	2,500	□220	FGP60G	L7NHB075U						
		□220	FGP85G	L7NHB150U				XLCS-P□□□MS		
	2,000	□220	FGP110G	L7NHB150U						
		□220	FGP150G	L7NHB150U						
1,000	2,000	□130	FEP03M	L7NHB010U				XLCS-P□□□HS	XLCS-P□□□NB	
		□130	FEP06M	L7NHB010U						
		□130	FEP09M	L7NHB010U						
		□130	FEP12M	L7NHB020U						
		□180	FFP12M	L7NHB020U				XLCS-P□□□IS	XLCS-P□□□PB	
		□180	FFP20M	L7NHB020U						
	1,700	□180	FFP30M	L7NHB035U				XLCS-P□□□JS	XLCS-P□□□LB	
	2,000	□180	FFP44M	L7NHB050U						
		□220	FGP12M	L7NHB020U				XLCS-P□□□IS		
		□220	FGP20M	L7NHB020U						
		□220	FGP30M	L7NHB050U				XLCS-P□□□JS		
		□220	FGP44M	L7NHB050U						
		□220	FGP60M	L7NHB075U				XLCS-P□□□MS		

XDL-L7NHA Drive

Item \ Type Name		XDL-L7NHA001U	XDL-L7NHA002U	XDL-L7NHA004U	XDL-L7NHA008U	XDL-L7NHA010U	XDL-L7NHA020U	XDL-L7NHA035U
Input Power	Main Power Supply	3 Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]						
	Control Power Supply	Single Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]						
Rated Current[A]		1.4	1.7	3.0	5.2	6.75	13.5	16.7
Peak Current[A]		4.2	5.1	9.0	15.6	20.25	40.5	50.1
Encoder Type		Quadrature(Incremental) BiSS-B, BiSS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2						
Control Performance	Speed Control Range	Maximum 1: 5000						
	Frequency Response	Maximum 1[kHz] or above(When the 19-bit Serial Encoder is applied)						
	Speed Variation Ratio	±0.01[%] or lower(When the load changes between 0 and 100%) ±0.1[%] or less(Temperature of 25℃[±10]						
	Torque Control Repetition Accuracy	Within ±1%						
EtherCAT Communication Specifications	Communication Standard	FoE (Firmware download) EoE (Parameter setting by UDP, Tuning, Secondary function, Parameter copy) CoE (IEC 61158 Type12, IEC 61800-7 CIA 402 Drive profile)						
	Physical Layer	100BASE-TX(IEEE802.3)						
	Connector	RJ45 x 2						
	Communication distance	Within connection between nodes 100[m]						
	DC(Distributed Clock)	By DC mode synchronism. minimum DC cycle: 250[us]						
	LED Display	LinkAct IN, LinkAct OUT, RUN, ERR						
	Cia402 Drive Profile	Profile Position Mode Profile Velocity Mode Profile Torque Mode Cyclic Synchronous Position Mode Cyclic Synchronous Velocity Mode Cyclic Synchronous Torque Mode Homing Mode						
Digital Input/ Output	Digital Input	Input Voltage range : DC 12[V] ~ DC 24[V] Total 8 input channels (allocable) Above 12 functions can be used selectively for assignment. (*POT, *NOT, *HOME, *STOP, *PCON, *GAIN2, *P_CL, *N_CL, PROBE1, PROBE2, EMG, A_RST) *Basic allocation signal						
	Digital Output	Service rating: DC 24[V] ±10%, 120[㎃] Total 4 input channels (allocable) Above 11 functions can be used selectively for assignment. (*BRAKE±, *ALARM±, *READY±, *ZSPD±, INPOS±, TLMT±, VLMT±, INSPD±, WARN±, TGON±, INPOS±) *Basic allocation signal						
Analog Monitor		There are 2 input channels. Above 15 functions can be used selectively for assignment.						
Safety Function		2 Input Channels (STO1, STO2), 1 Output Channels (EDM±)						
USB Communication	Function	Firmware download, Parameter setting, Tuning, Secondary function, Parameter copy						
	Communication Standard	USB 2.0 Full Speed (applies standard)						
	Connect	PC or USB storing medium						
Internal Function	Dynamic Braking	Standard built-in brake (activated when the servo alarm goes off or when the servo is off).						
	Regenerative Braking	Both the default built-in brake and an externally installed brake are possible.						
	Display Function	7 segments(5DIGIT)						
	Self-setting Function	The [MODE] key changes the content displayed in 7 segments						
	Additional Function	Auto gain tuning function						
	Protection Function	Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheat(power module overheat, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem						
Environment	Temperature	0 ~ +50[℃] / -20~ +70[℃]						
	Humidity	Below 90[%]RH(avoid dew-condensation)						
	Environment	Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust.						

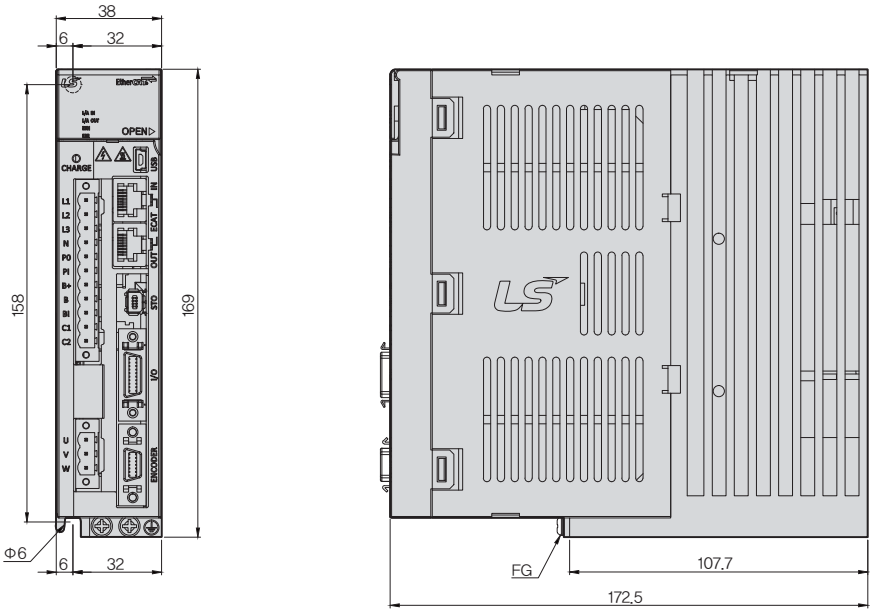
XDL-L7NHB Drive

Item \ Type Name		XDL-L7NHB010U	XDL-L7NHB020U	XDL-L7NHB035U	XDL-L7NHB050U	XDL-L7NHB075U	XDL-L7NHB150U
Input Power	Main Power Supply	3 Phase AC380 ~480[V](-15 ~ +10[%]), 50 ~ 60[Hz]					
	Control Power Supply	Single Phase AC380 ~ 480[V](-15 ~ +10[%]), 50 ~ 60[Hz]					
Rated Current[A]		3.7	8	10.1	17.5	22.8	39
Peak Current[A]		11.1	24	30.3	47.25	57	97.5
Encoder Type		Quadrature(Incremental) BiSS-B, BiSS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2					
Control Performance	Speed Control Range	Maximum 1: 5000					
	Frequency Response	Maximum 1[kHz] or above(When the 19-bit Serial Encoder is applied)					
	Speed Variation Ratio	±0.01[%] or lower(When the load changes between 0 and 100%) ±0.1[%] or less(Temperature of 25℃[±10]					
	Torque Control Repetition Accuracy	Within ±1%					
EtherCAT Communication Specifications	Communication Standard	FoE (Firmware download) EoE (Parameter setting by UDP, Tuning, Secondary function, Parameter copy) CoE (IEC 61158 Type12, IEC 61800-7 CIA 402 Drive profile)					
	Physical Layer	100BASE-TX(IEEE802.3)					
	Connector	RJ45 x 2					
	Communication distance	Within connection between nodes 100[m]					
	DC(Distributed Clock)	By DC mode synchronism. minimum DC cycle: 250[us]					
	LED Display	LinkAct IN, LinkAct OUT, RUN, ERR					
	Cia402 Drive Profile	Profile Position Mode Profile Velocity Mode Profile Torque Mode Cyclic Synchronous Position Mode Cyclic Synchronous Velocity Mode Cyclic Synchronous Torque Mode Homing Mode					
Digital Input/ Output	Digital Input	Input Voltage range : DC 12[V] ~ DC 24[V] Total 8 input channels (allocable) Above 12 functions can be used selectively for assignment. (*POT, *NOT, *HOME, *STOP, *PCON, *GAIN2, *P_CL, *N_CL, PROBE1, PROBE2, EMG, A_RST) *Basic allocation signal					
	Digital Output	Service rating: DC 24[V] ±10%, 120[㎃] Total 4 input channels (allocable) Above 11 functions can be used selectively for assignment. (*BRAKE±, *ALARM±, *READY±, *ZSPD±, INPOS±, TLMT±, VLMT±, INSPD±, WARN±, TGON±, INPOS±) *Basic allocation signal					
Analog Monitor		There are 2 input channels. Above 15 functions can be used selectively for assignment.					
Safety Function		2 Input Channels (STO1, STO2), 1 Output Channels (EDM±)					
USB Communication	Function	Firmware download, Parameter setting, Tuning, Secondary function, Parameter copy					
	Communication Standard	USB 2.0 Full Speed (applies standard)					
	Connect	PC or USB storing medium					
Internal Function	Dynamic Braking	Standard built-in brake (activated when the servo alarm goes off or when the servo is off).					
	Regenerative Braking	Both the default built-in brake and an externally installed brake are possible.					
	Display Function	7 segments(5DIGIT)					
	Self-setting Function	The [MODE] key changes the content displayed in 7 segments					
	Additional Function	Auto gain tuning function					
	Protection Function	Overcurrent, overload, overvoltage, insufficient voltage, main power input problem, control power input problem, overspeed, motor cable, overheat(power module overheat, abnormal drive operation's temp), encoder problem, over-regenerative, sensor problem, communication problem					
Environment	Temperature	0 ~ +50[°C] / -20~ +70[°C]					
	Humidity	Below 90[%]RH(avoid dew-condensation)					
	Environment	Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust.					

External Dimensions

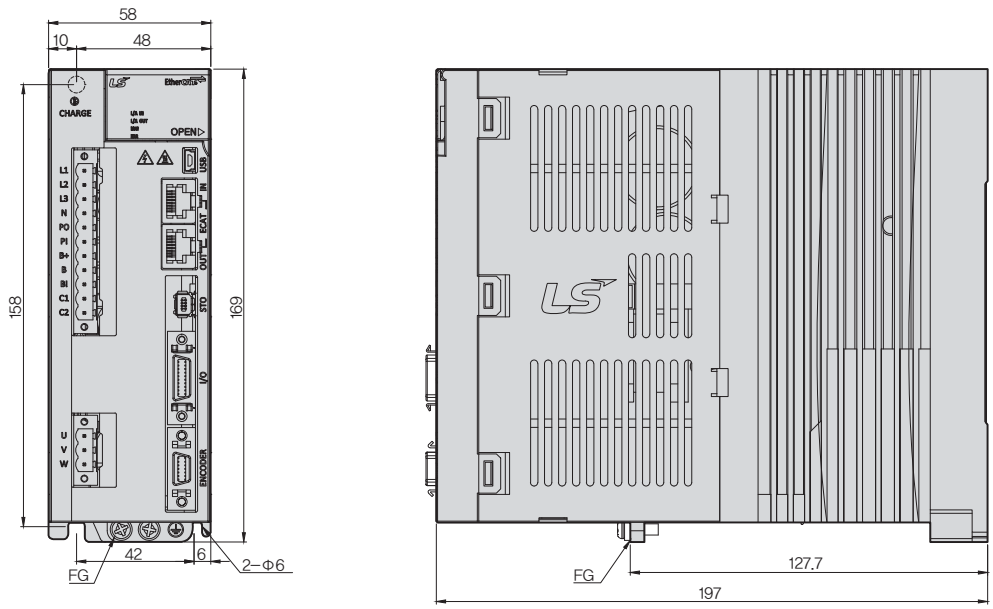
XDL-L7NHA001U ~ XDL-L7NHA004U[Weight : 1.0kg]

*Unit [mm]



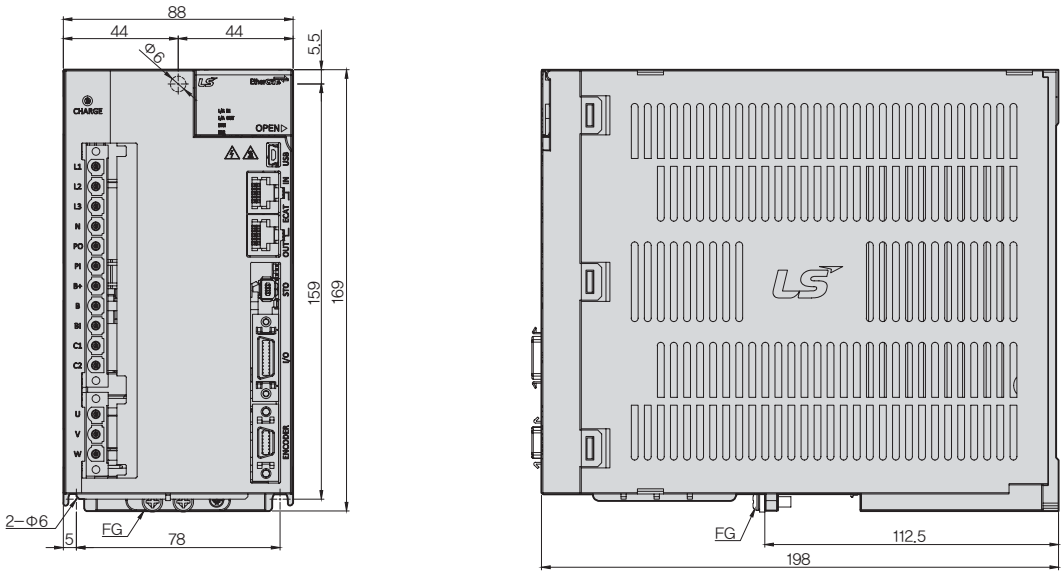
XDL-L7NHA008U / XDL-L7NHA010U[Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]



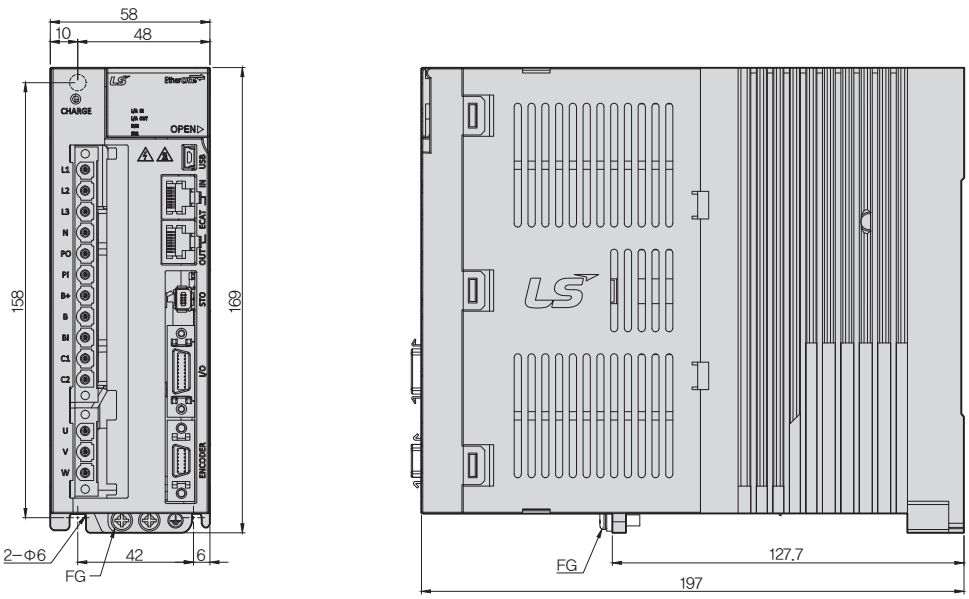
XDL-L7NHA020U / XDL-L7NHA035U[Weight : 2.5kg(Fan-Cooling included)]

*Unit [mm]



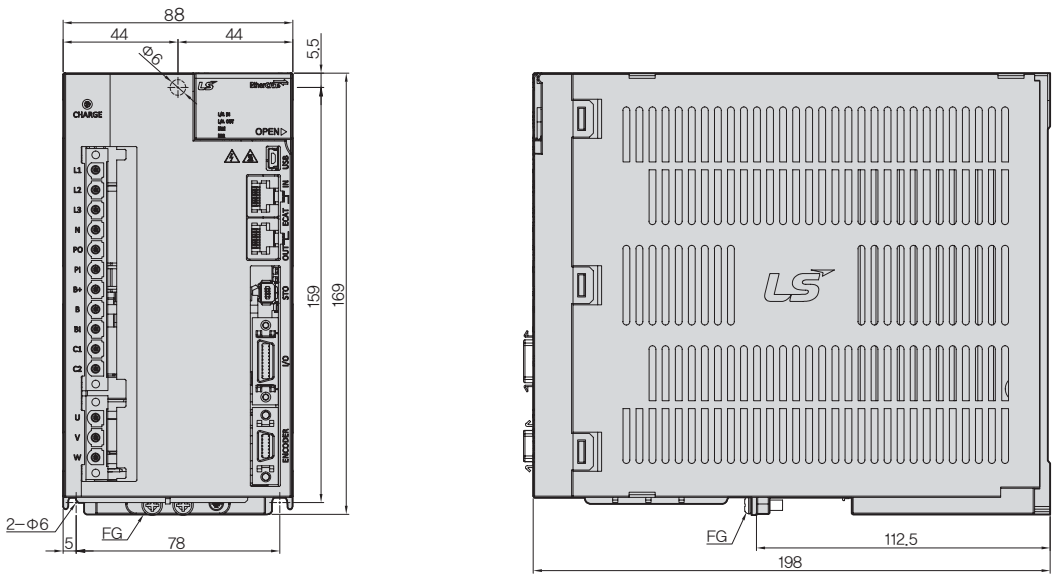
XDL-L7NHB010U[Weight : 1.5kg(Fan-Cooling included)]

*Unit [mm]



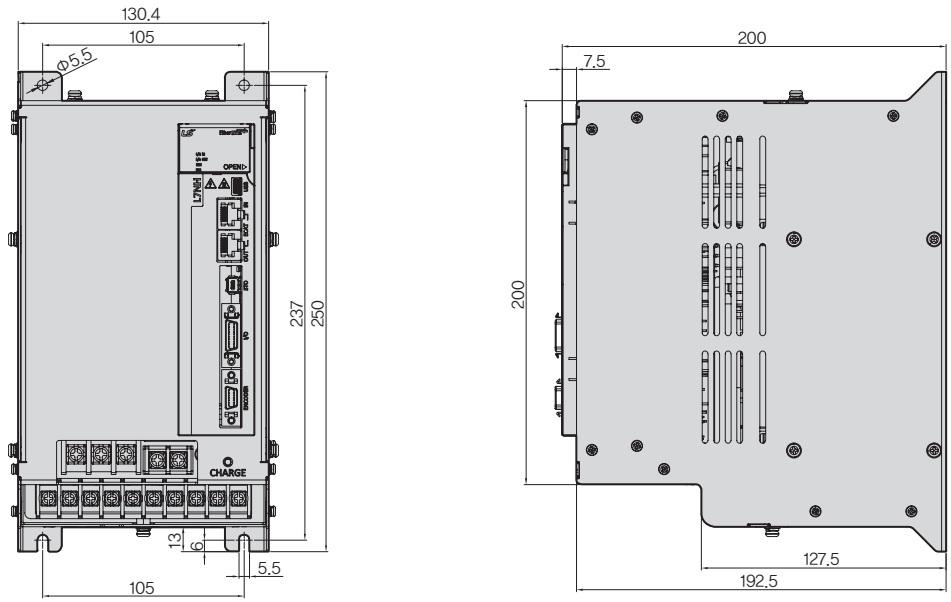
XDL-L7NHB020U / XDL-L7NHB035U[Weight : 2.5kg(Fan-Cooling included)]

*Unit [mm]



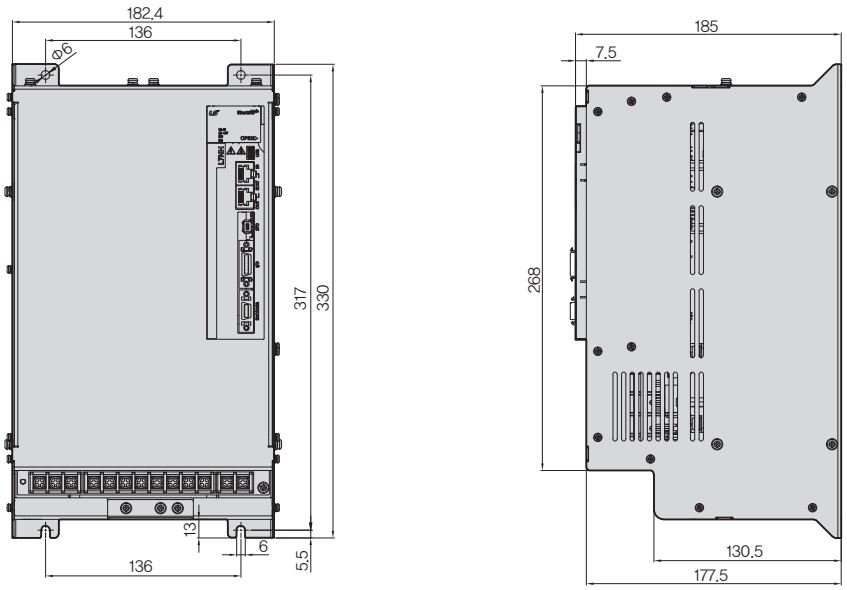
XDL-L7NB050U[Weight : 5.5kg(Fan-Cooling included)]

*Unit [mm]



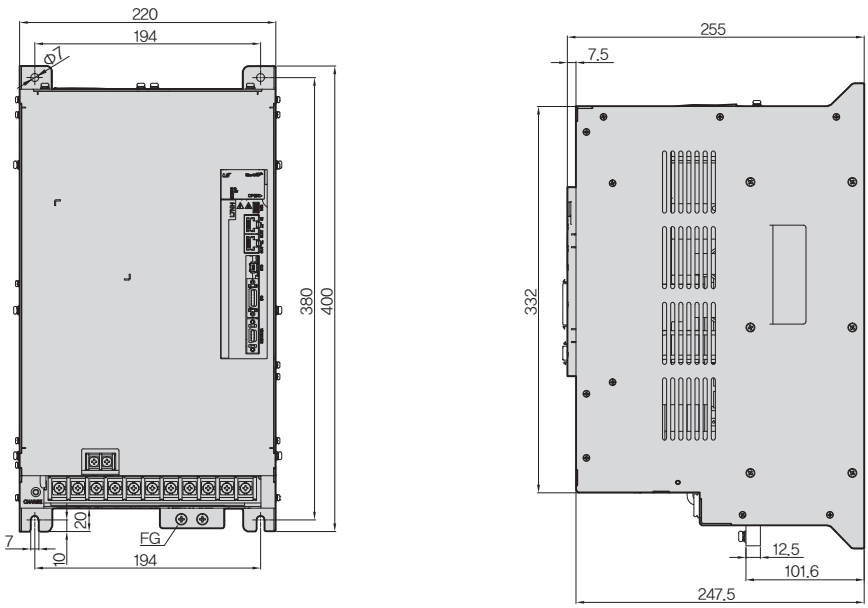
XDL-L7NHB075U[Weight : 8.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7NHB150U[Weight : 15.5kg(Fan-Cooling included)]

*Unit [mm]



XDL-L7P Series



Servo Drive Designation

XDL	-	L7	P	A	004	B	AA
Model Name		Communication		Input Power Supply	Capacity	Encoder Type	Option
XDL Series		Stand I/O & Index Type		A:200VAC	001:100W 002:200W 004:400W 008:750W 010:1.0kW 020:2.0kW 035:3.5kW	U:Universal	Exclusive Option Code

Indexer Function Type XDL-L7P

Providing Program Function built-in single axis position determination module

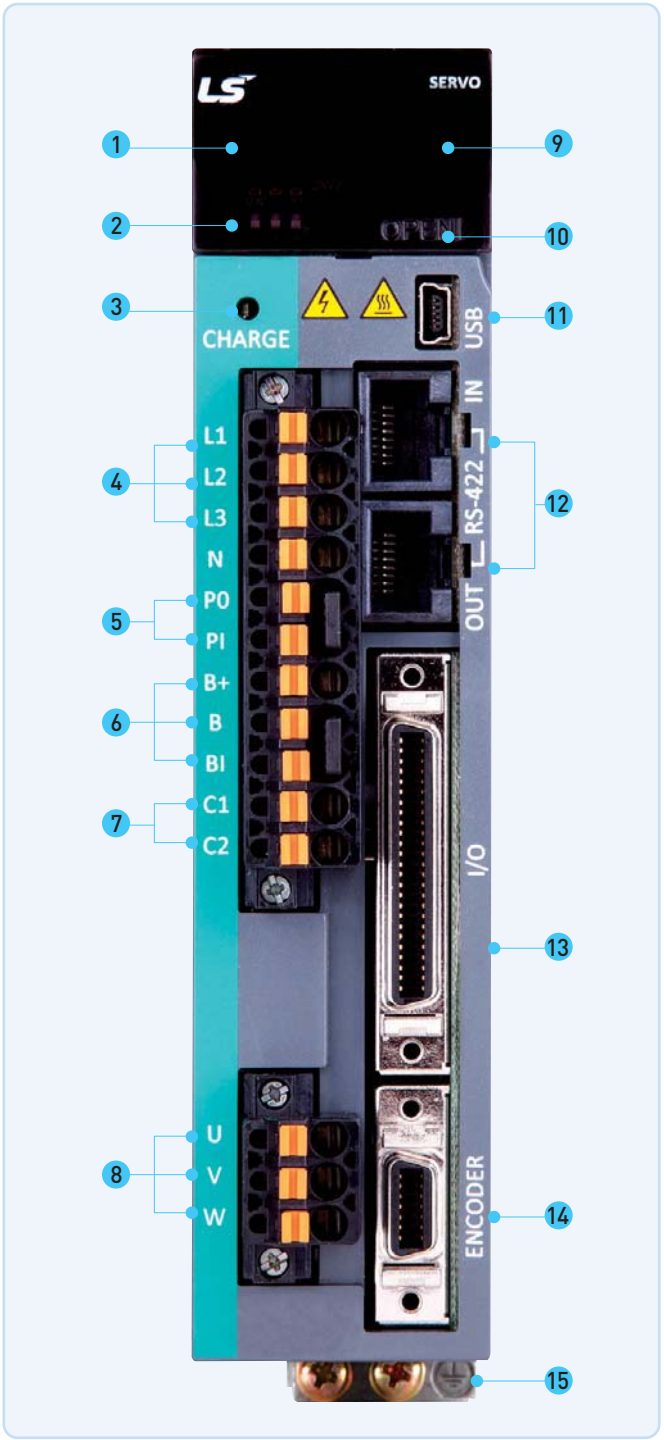
- Supporting position control mode by pulse input
- Position control mode
- Possible to use without upper controller
- Modbus RTU Protocol (RS-422)

Support various motor and Encoder drive

- Supporting Rotary, DD and Motor drive (supporting3rd party motor)
- Quadrature, BiSS-C, Tamagawa serial abs, EnDat 2.2, Resolver

Improved Control Performance

- Improved Control bandwidth
- Providing 4-step Notch-Filter
- Vibration control by Real-time FET
- Real-time gain tuning function



1. Display
2. Status LED
3. Charge Lamp
4. Main Power Connector (L1, L2, L3)
5. DC Reactor Connector(P0, PI) Short-Circuit When Not used
6. Regenerative Resistor Connector (B+, B, BI)
   - Short-Circuit B, BI terminals when standard type
   - Use B+, B terminals when using external resistor
7. Control Power connector (C1, C2)
8. Motor power connector(U, V, W)
9. Connector for analogue monitor
10. Switch for nod address setting
11. USB connector (USB)
12. RS-422 communication connector (CN3, CN4)
13. Control signal connector (I/O)
14. Encoder Connector (ENCODER)
15. Ground

XDL Drive Combination Table

XDL-L7P Incremental Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable	Power Cable		
					Quadrature Type	INC	For power	Power + Brake	Brake
3,000	5,000	□40	SAR3A	L7PA001U	* 2,048P/R	XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□KB
		□40	SAR5A	L7PA001U					
		□40	SA01A	L7PA001U					
		□40	SA015A	L7PA002U					
		□60	SB01A	L7PA002U	* 3,000P/R				
		□60	SB02A	L7PA002U					
		□60	SB04A	L7PA004U					
		□80	SC04A	L7PA004U					
		□80	SC06A	L7PA008U					
		□80	SC08A	L7PA008U					
		□80	SC10A	L7PA010U					
		□130	SE09A	L7PA008U		XLCS-E□□□BS	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE15A	L7PA020U					
		□130	SE22A	L7PA020U					
		□180	SF30A	L7PA035U			XLCS-P□□□IS	XLCS-P□□□PB	
2,000	3,000	□80	SC03D	L7PA004U		XLCS-E□□□AS	XLCS-P□□□GS		XLCS-P□□□KB
		□80	SC05D	L7PA008U					
		□80	SC06D	L7PA008U					
		□80	SC07D	L7PA008U					
		□130	SE06D	L7PA008U		XLCS-E□□□BS	XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE11D	L7PA010U					
		□130	SE16D	L7PA020U					
		□130	SE22D	L7PA020U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SF22D	L7PA020U					
		□180	LF35D	L7PA035U					
		□220	SG22D	L7PA020U					XLCS-P□□□SB
		□220	LG35D	L7PA035U					
1,500	3,000	□130	SE05G	L7PA008U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE09G	L7PA010U					
		□130	SE13G	L7PA020U					
		□130	SE17G	L7PA020U					
		□180	SF20G	L7PA035U			XLCS-P□□□IS	XLCS-P□□□PB	
	2,700	□180	LF30G	L7PA035U					
	3,000	□220	SG20G	L7PA020U					XLCS-P□□□SB
	2,700	□220	LG30G	L7PA035U					
1,000	2,000	□130	SE03M	L7PA004U			XLCS-P□□□HS	XLCS-P□□□NB	
		□130	SE06M	L7PA008U					
		□130	SE09M	L7PA010U					
		□130	SE12M	L7PA020U					
		□180	SF12M	L7PA020U			XLCS-P□□□IS	XLCS-P□□□PB	
		□180	SF20M	L7PA035U					
	1,700	□180	LF30M	L7PA035U					
	2,000	□220	SG12M	L7PA020U			XLCS-P□□□IS		XLCS-P□□□SB
		□220	SG20M	L7PA035U					
	1,700	□220	LG30M	L7PA035U					
3,000	3,500	□60	HB01A	L7PA002U	* 1,048P/R	XLCS-E□□□AS	XLCS-P□□□GS		
		□60	HB02A	L7PA002U					
		□60	HB04A	L7PA004U					
		□130	HE09A	L7PA008U	* 2,048P/R	XLCS-E□□□BS	XLCS-P□□□HS		
		□130	HE15A	L7PA020U					

XDL-L7P Serial Type

Rated Speed (rpm)	Maximum Speed (rpm)	Flange Size	Applicable Motor	Applicable Drive	Standard Encoder Type	Encoder Cable		Power Cable		
					Serial Type	Serial	Abs	For power	Power + Brake	Brake
3,000	5,000	□40	FALR5A	L7PA001U	* 18Bit Serial / M-Turn Abs	XLCS-E□□□ES	XLCS-E□□□ES1	XLCS-P□□□□LS		XLCS-P□□□□QS
		□40	FAL01A	L7PA001U						
		□40	FAL015A	L7PA002U						
		□60	FBL01A	L7PA001U	* 19Bit Serial / M-Turn Abs					
		□60	FBL02A	L7PA002U						
		□60	FBL04A	L7PA004U						
		□80	FCL04A	L7PA004U						
		□80	FCL06A	L7PA008U						
		□80	FCL08A	L7PA008U						
		□80	FCL10A	L7PA010U						
		□60	FB01A	L7PA001U				XLCS-P□□□□FS		
		□60	FB02A	L7PA002U						
		□60	FB04A	L7PA004U						
		□80	FC04A	L7PA004U						
		□80	FC06A	L7PA008U						
		□80	FC08A	L7PA008U						
		□80	FC10A	L7PA010U						
		□130	FE09A	L7PA010U		XLCS-E□□□□DS	XLCS-E□□□□DS1	XLCS-P□□□□HS	XLCS-P□□□□NB	
		□130	FE15A	L7PA020U						
		□130	FE22A	L7PA020U						
		□130	FE30A	L7PA035U						
		□180	FF30A	L7PA035U				XLCS-P□□□□IS	XLCS-P□□□□PB	
2,000	3,000	□80	FCL03D	L7PA004U		XLCS-E□□□□ES	XLCS-E□□□□ES1	XLCS-P□□□□LS		XLCS-P□□□□QS
		□80	FCL05D	L7PA008U						
		□80	FCL06D	L7PA008U						
		□80	FCL07D	L7PA008U						
		□80	FC03D	L7PA004U						
		□80	FC05D	L7PA008U						
		□80	FC06D	L7PA008U						
		□80	FC07D	L7PA008U				XLCS-P□□□□FS		
		□130	FE06D	L7PA008U						
		□130	FE11D	L7PA010U		XLCS-E□□□□DS	XLCS-E□□□□DS1	XLCS-P□□□□HS	XLCS-P□□□□NB	
		□130	FE16D	L7PA020U						
		□130	FE22D	L7PA020U						
		□180	FF22D	L7PA020U						
		□180	FF35D	L7PA035U				XLCS-P□□□□IS	XLCS-P□□□□PB	
		□220	FG22D	L7PA020U						
		□220	FG35D	L7PA035U						XLCS-P□□□□SB
1,500	3,000	□130	FE05G	L7PA008U				XLCS-P□□□□HS	XLCS-P□□□□NB	
		□130	FE09G	L7PA010U						
		□130	FE13G	L7PA020U						
		□130	FE17G	L7PA020U						
		□180	FF20G	L7PA020U				XLCS-P□□□□IS	XLCS-P□□□□PB	
	2,700	□180	FF30G	L7PA035U						
	3,000	□220	FG20G	L7PA020U						XLCS-P□□□□SB
	2,700	□220	FG30G	L7PA035U						
1,000	2,000	□130	FE03M	L7PA004U				XLCS-P□□□□HS	XLCS-P□□□□NB	
		□130	FE06M	L7PA008U						
		□130	FE09M	L7PA010U						
		□130	FE12M	L7PA020U						
		□180	FF12M	L7PA020U				XLCS-P□□□□IS	XLCS-P□□□□PB	
		□180	FF20M	L7PA020U						
	1,700	□180	FF30M	L7PA035U						
	2,000	□220	FG12M	L7PA020U				XLCS-P□□□□IS		XLCS-P□□□□SB
		□220	FG20M	L7PA020U						
	1,700	□220	FG30M	L7PA035U						

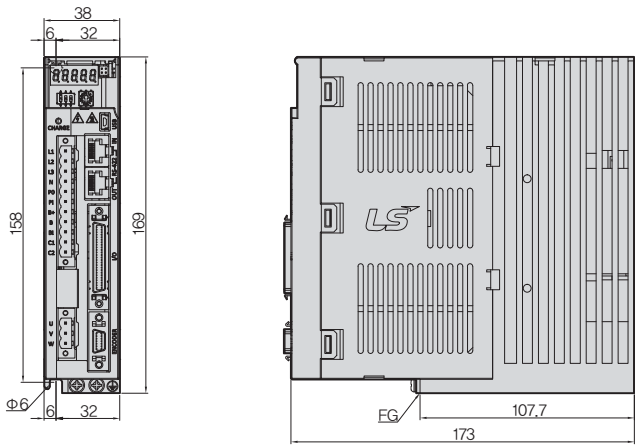
XDL-L7PA Drive

Item \ Type Name		XDL-L7PA001U	XDL-L7PA002U	XDL-L7PA004U	XDL-L7PA008U	XDL-L7PA010U	XDL-L7PA020U	XDL-L7PA035U
Input Power	Main Power Supply	3 Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]						
	Control Power Supply	Single Phase AC200 ~ 230[V](-15 ~ +10[%]), 50 ~ 60[Hz]						
Rated Current[A]		1.4	1.7	3.0	5.2	6.75	13.5	16.7
Peak Current[A]		4.2	5.1	9.0	15.6	20.25	40.5	50.1
Encoder Type		Quadrature(Incremental) BiSS-B, BiSS-C(Absolute, Incremental) Tamagawa Serial(Absolute, Incremental) EnDat 2.2						
Control Performance	Speed Control Range	Maximum 1: 5000						
	Frequency Response	Maximum 1 [kHz] or above (When using 19bit Serial Encoder)						
	Speed Variation Ratio	±0.01 [%] or lower [when load changes between 0 and 100%] ±0.1[%] or lower [temperature 25 ±10℃]						
	Accel/Decel Time	Straight or S-curve acceleration/deceleration (0~10,000[ms], 0~1,000[ms] Unit configurable)						
	Input Frequency	1[Mpps], line drive / 200[kpps], Open Collector						
	Input Pulse Type	Symbol + Pulse Series, CW+CCW, A/B Phase						
RS422 Communication Specifications	Communication Specifications	ANSI/TIA/EIA-422 Standard Specifications						
	Communication Protocol	MODBUS-RTU						
	Connector	RJ45 x 2						
	Synchro Method	Asynchronous						
	Transmission Speed	9600 /19200/38400/57600 [bps] Can be configured at [0x3002]						
	Transmission Distance	Maximum 200 [m]						
	Power Consumption	100[㎃]						
	Terminating Resistance	Dip S/W(On/Off), Built-In 120 Ω						
Input/Output Signal	Digital Input	Input voltage range: DC 12[V] ~ DC 24[V] Total 16 input channel (allocatable) 32 function inputs can be selectively allocated (*SV_ON, *POT, *NOT, *A-RST, *START, *STOP, *REGT, *EMG, *HOME, *HSTART, *ISEL0, *ISEL1, *ISEL2, *ISEL3, *ISEL4, *ISEL5, PCON, GAIN2, P_CL, N_CL, MODE, PAUSE, ABSRQ, JSTART, JDIR, PCLR, AOVR, SPD1/LVSF1, SPD2/LVSF2, SPD3, PROBE1, PROBE2) * Basic allocation signal.						
	Digital Output	Use rating: DC 24[V] ±10%, 120[ÑÃ] Total 8 input channel (allocatable) 19 function inputs can be selectively allocated (*ALARM±, *READY±, *BRAKE±, *INPOS1±, *ORG±, *EOS±, *TGON±, *TLMT±, VLMT±, INSPD±,ZSPD±, WARN±, INPOS2±, IOUT0±, IOUT1±, IOUT2±, IOUT3±, IOUT4±, IOUT5±) * Standard Allocation signal						
Analog Input/output	Analog input	Total 2 channels analog speed override input(-10[V) ~ +10[V]) analog torque command input(-10[V) ~ +10[V])						
	Analog output	Total 2 channels 15 function inputs can be selectively allocated						
USB Communication	Protection	Firmware download, parameter setting, tuning, auxiliary function,parameter copy						
	Communication Specifications	Complies with USB 2.0 Full Speed Specifications						
	Connection Device	PC or USB storage media						
Built-in functions	Dynamic Braking	Standard built-in(activated by servo alarm or servo OFF)						
	Regenerative Braking	Built-in, external brake attachable						
	Display	7 Segment(5 DIGIT)						
	Setting Function	Drive node address can be set using rotary switch						
	Additional Function	Gain tuning, alarm history, JOG operation, origin search						
	Protective Function	Excessive current, overload, excessive current limit, overheating, excessive voltage, low voltage, excessive speed, encoder fail, position following fail, current sensing fail						
Environment	Temperature	0 ~ 50[℃] / -20 ~ 65℃						
	Humidity	Below 90[%]RH(avoid dew-condensation)						
	Environment	Indoor, Avoid corrosive, inflammable gas or liquid, and electrically conductive dust.						

External Dimensions

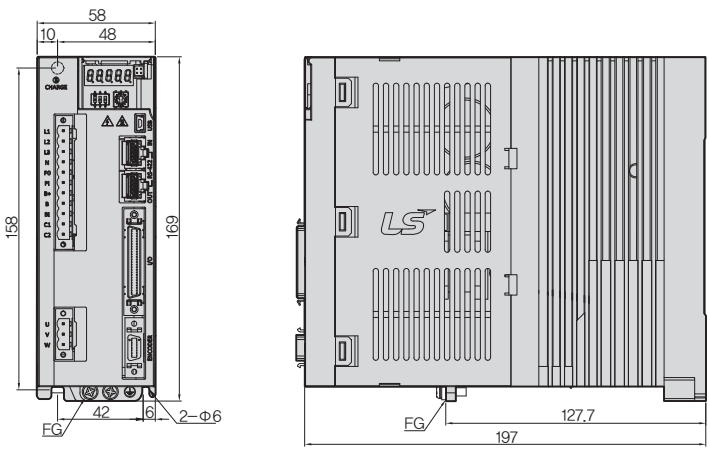
*Unit [mm]

XDL-L7PA001U ~ XDL-L7PA004U [Weight : 1.0kg (Fan-Cooling included)]



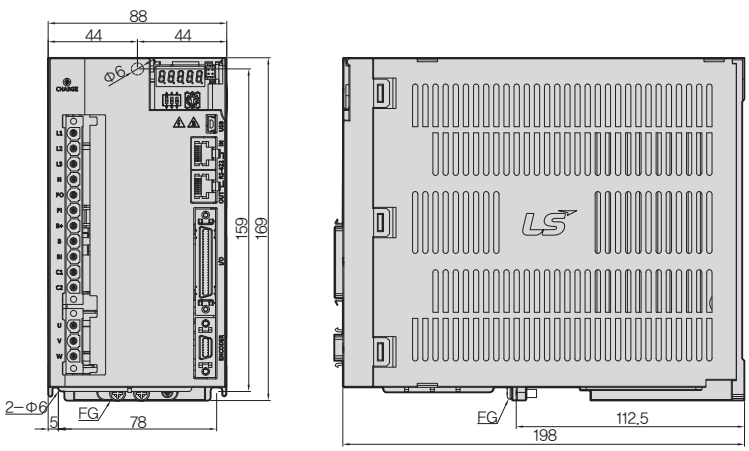
*Unit [mm]

XDL-L7PA008U / XDL-L7PA010U [Weight : 1.5kg (Fan-Cooling included)]



*Unit [mm]

XDL-L7PA020U / XDL-L7PA035U [Weight : 2.5kg (Fan-Cooling included)]



XIP(PEGASUS) Series



Servo Drive Designation

XIP	-	A	R5	A	-	A	N	-	M	A
PEGASUS Series		Flange Size	Motor Capacity	Rated Speed		Drive Voltage	Communication		Encoder Type	Resolution
XIP Series		A: 40 Flange	R5: 50[W]	A: 3000[rpm]		A: 48VDC	N: EtherCAT		M: Magnetic Encoder	A: 12Bit
		B: 60 Flange	01: 100[W]							C: 17Bit(TBD)
			02: 200[W]							
			03: 300[W]							

Integrated Servo System Type XIP(PEGASUS)

Enhanced efficiency integrated servo system

- Cost effective from installation by integrated system of motor, encoder cable and drive
- Maximization for useful space when installed at limited and small space
- High effectiveness for application of multi axis because there is no limitation for space of installation

Real-time control through EtherCAT

- High speed, Real-time capability and Synchronization mechanism
- Improved EtherCAT communication speed
- Supporting CoE, EoE and FoE



1. Input / Output Signal Connector (CN1)
   - This Connector is for Sequence Input / Output Signals
2. EtherCAT Communication Output Port (OUT)
3. Status LED
   - It Indicates the current state of EtherCAT Communication
4. Power Connector (CN3)
5. EtherCAT Communication Input Port (IN)
6. Safety Connector (CN2)
   - This Connector connects Safety Devices
7. USB Connector (CN5, Mini B type)
   - This Connector is to Communicate With a PC
8. Node Address Setting Switch
   - This Switch is to set the node address of the drive
   - You can set the node addresses from 0 to 15

XIP Drive Product Features

Rated Values of Servo Drive

Rated	□40 50W	□40 100W	□60 100W	□60 200W	□60 300W
Continuous output current [Arms]	1.77	2.38	3.62	5	6.8
Maximum output current [Arms]	3.54	3.75	7.24	10	13.6
Input voltage	DC 48V ~ DC 60V				

Basic Specifications

Category			Details
Use conditions	Control method		PWM controlled sine wave current driving method
	Operating temperature /storage temperature		0~+40[℃] / -20~ +60[℃]
	Operating humidity /storage humidity		Below 80% RH / Below 90% RH (no freeze or condensation)
	Vibration-/impact-resistance		TBD
	Degree of protection /degree of pollution		TBD
	Altitude		1000m or lower
	Other		To be free from electrostatic noise, strong electrolysis, or radiation.
Performance	Speed variation	Load variation	At 0 to 100% load: ± 3% (at rated speed)
		Voltage variation	Rated voltage ±10%: 0% (at rated speed)
		Temperature variation	25℃: ±0.1% or less (at rated speed)
Input/ output signal	Input signal		Input voltage range: DC 12 V - DC 30 V The 4-channel input signal can be assigned to 12 functions: POT, NOT, HOME, STOP, PCON, GAIN2, PCL, NCL, PROBE1, PROB2, EMG, and ARST.
	Output signal		Rated voltage and current: DC 24 V ±10%, 120 [㎃] The 2-channel output signal can be assigned to 11 functions: BRAKE, ALARM, RDY, ZSPD, INPOS1, TLMT, VLMT, INSPD, WARN, TGON, and INPOS2.
Analog Monitor			Number of channels: 1, Output voltage range: ±4V, Angular resolution: 12 bits, Stabilization time: 15 us
USB communica-tion	Connecting device		PC or USB storage medium
	Communication standard		Conform to the USB 2.0 Full Speed Standard.
	Function		Firmware download, parameter setting, adjustment, auxiliary functions, and parameter copy function.
Dynamic brake (three-phase short-circuit)			Activates when servo alarm, servo OFF, or Emergency stop (POT, NOT and EMG) is input.
Protection functions			Overcurrent, overload, current limit, overheat, overvoltage, undervoltage, overspeed, encoder error, position follow error, ect.
Auxiliary functions			Gain adjustment, alarm history, JOG drive, programmed JOG drive, etc.
Safety functions	Input		STO1 and STO2
	Compatible standard		TBD

EtherCAT Communication Specification

Category		Details
Communicati on standard	FoE	Firmware download
	EoE	Parameter setting, adjustment, auxiliary functions, and parameter copy through UDP.
	CoE	IEC 61158 Type12, IEC 61800-7 CiA 402 drive profile
Physical layer		100BASE-TX(IEEE802.3)
Connector		RJ45 x 2
Distance		Within 100 m between nodes
DC (Distributed Clock)		Sync by DC mode
LED Display		• L/A0(Link/Act IN) • L/A1(Link/Act OUT) • RUN • ERR
Cia402 drive Profile		Supports CSP, CSV, CST, PP, PV, PT, and HM Modes.

Encoder Specification

Category	Details
Encoder Type	Magnetic Encoder (12bit)

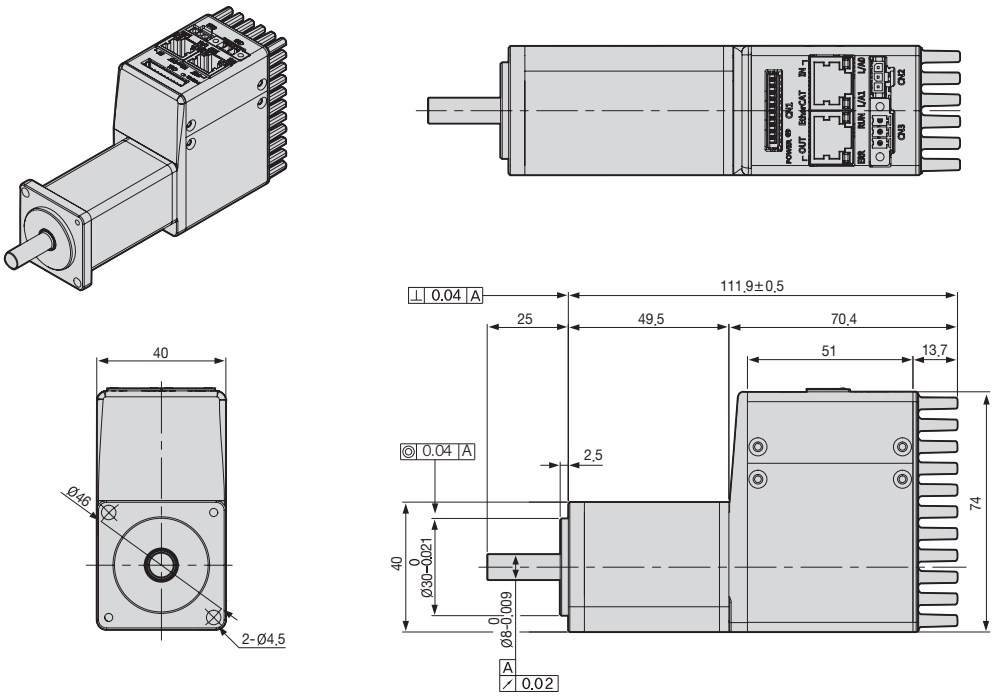
Motor Specification

Model	Unit	□40 50W	□40 100W	□60 100W	□60 200W	□60 300W
Rated Torque	[Kgf cm]	1.62	3.25	3.25	6.50	9.74
Max. Torque	[Kgf cm]	3.24	4.88	6.50	13.0	19.48
Rated Speed	[rpm]	3000	2400	3000	3000	3000
Max Speed	[rpm]	3000	3000	3000	3000	3000
Inertia	[Kg㎡x10-4]	0.0240	0.0450	0.114	0.182	0.321

External Dimensions

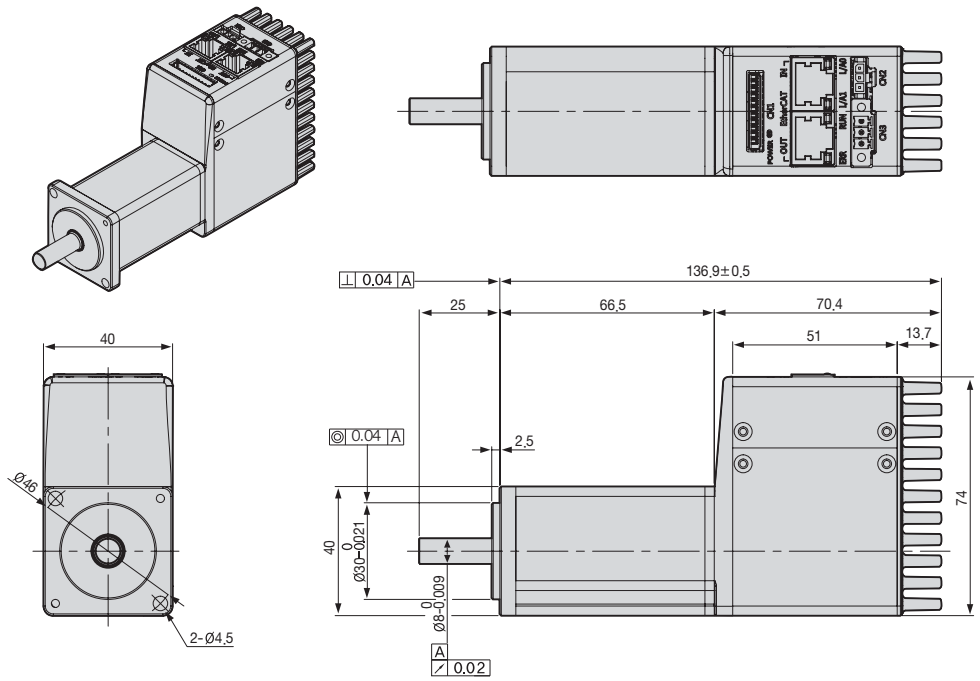
XIP-AR5A

*Unit [mm]



XIP-A01A

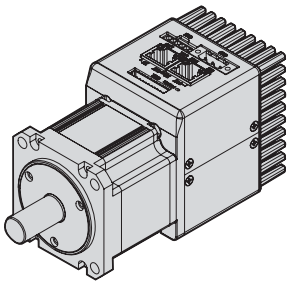
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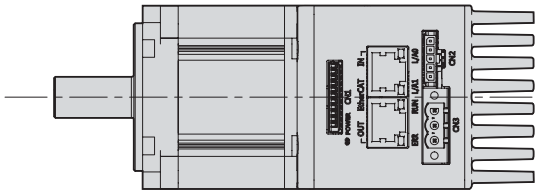


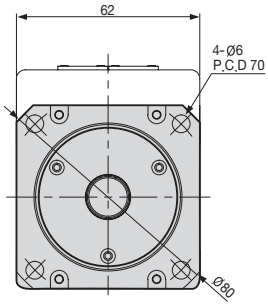
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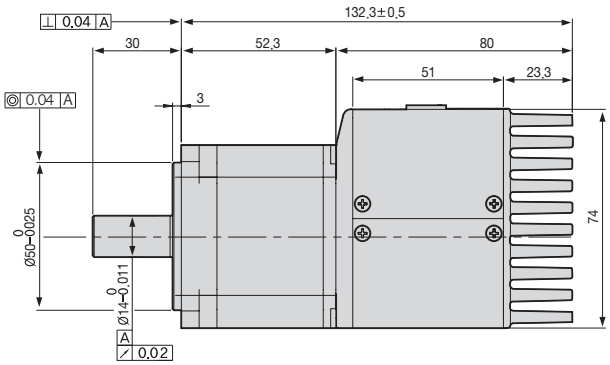
XIP-B01A

*Unit [mm]



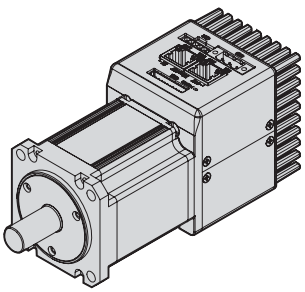


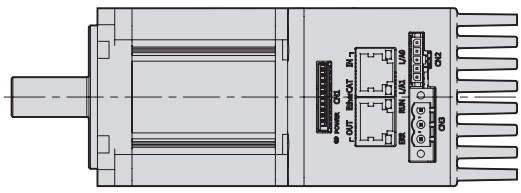


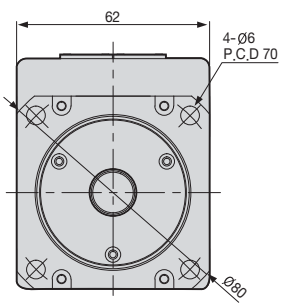


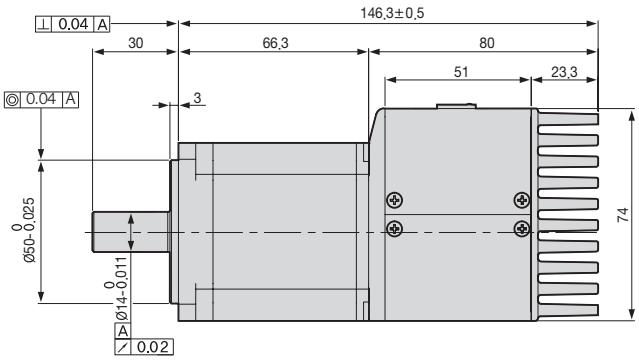
XIP-B02A

*Unit [mm]



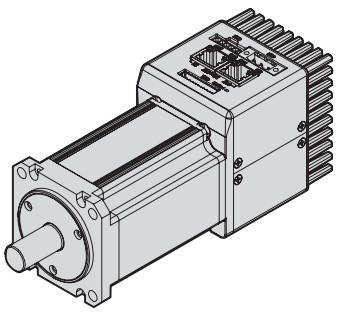


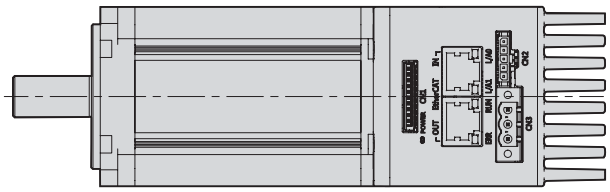


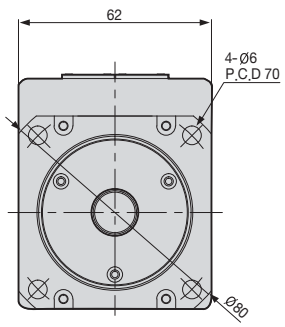


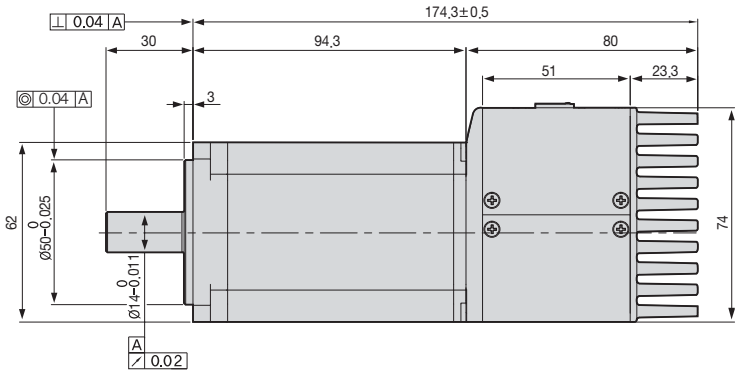
XIP-B03A

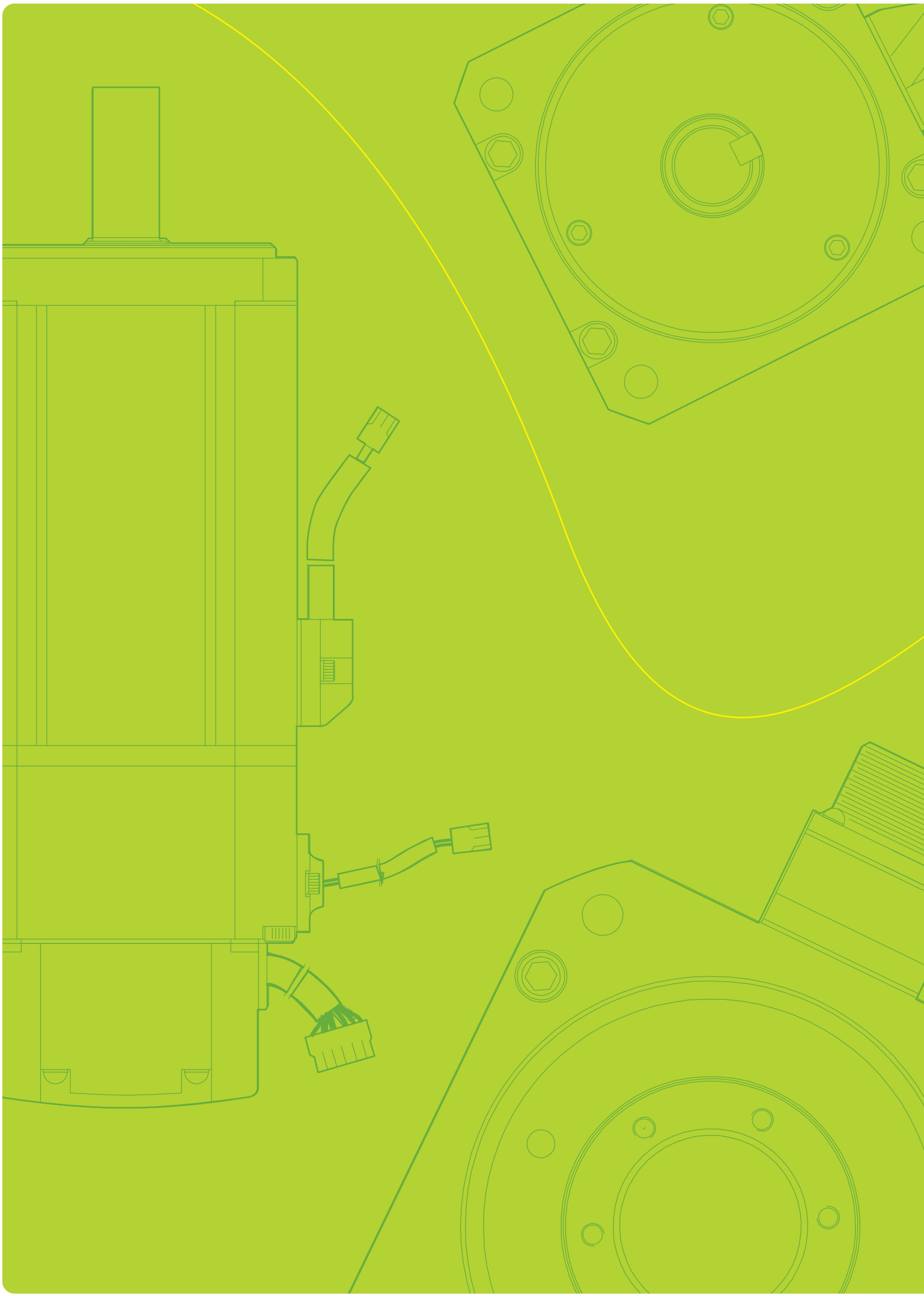
*Unit [mm]













Servo Motor

Contents

S Series

Solid/Hollow Shaft Type Rotating Servo Motor ---------- 60

F Series

Flat Type Rotating Servo Motor ---------- 76

MDM Series

Direct-Drive Motor ---------- 91

XML Servo Motor Designation

Servo Motor Designation



XML - S E P 04 A E K 1

Model Name
XML Series

Motor Shaft
S : Solid Shaft(Standard)
L : Solid Shaft(Low Current)
H : Hollow Shaft

Flange Size
A : 40 Flange
B : 60 Flange
C : 80 Flange
E : 130 Flange
F : 180 Flange
G : 220 Flange
H : 250 Flange
J : 280 Flange

Input Power Supply
None : 200VAC
P : 400VAC

Motor Capacity
R5 : 50[W]
01 : 100[W]
015 : 150[W]
02 : 200[W]
03 : 300[W]
04 : 400[W]
07 : 650[W]
08 : 800[W]
10 : 1.0[kW]
20 : 2.0[kW]
35 : 3.5[kW]
50 : 5.0[kW]
75 : 7.5[kW]
110 : 11[kW]
150 : 15[kW]

Rated Speed
A : 3000[rpm]
D : 2000[rpm]
G : 1500[rpm]
M : 1000[rpm]

Encoder Type
D : Inc. 2500[P/R]
E : Inc. 3000[P/R]
M : 19bit Serial Abs
M8 : 18bit M-Turn Abs [SA Type]

Oil Seal, Brake Type
None : None
1 : Oil Seal Attached
2 : Brake Attached
3 : Oil Seal, Brake Attached

Note 1) In case of 40, 60, 80 Flange product, you can apply 200V drive only.
Note2) If you apply nonstandard Encoder, Please contact our office.
Note3) Refer to brake operating voltage

Shape of Shaft End
N : Straight
K : One side Round key (Standard)

Servo Motor Characteristics

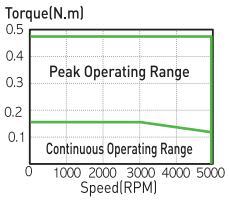
Motor Specifications [Rated 3000r/min]

Servo Motor (XML-□ □ □ □)		SAR5A	SA01A	SA015A	SB01A	SB02A	SB04A	SC04A	SC06A	SC08A	SC10A
Applicable Drive (L7□A□ □)		L7□A001		L7□A002			L7□A004		L7□A008		L7□A010
Flange Size(□)		□40			□60			□80			
Rated Output	[kW]	0.05	0.1	0.15	0.1	0.2	0.4	0.4	0.6	0.8	1
Rated Torque	[N · m]	0.16	0.32	0.48	0.32	0.64	1.27	1.27	1.91	2.55	3.19
	[kgf · cm]	1.62	3.25	4.87	3.25	6.49	12.99	12.99	19.49	25.98	32.48
Max. Instantaneous	[N · m]	0.48	0.96	1.43	0.96	1.91	3.82	3.82	5.73	7.64	9.56
	[kgf · cm]	4.87	9.74	14.62	9.74	19.48	38.96	38.96	58.47	77.95	97.43
Rated Current	[A]	1.2	1.38	1.73	1.65	1.63	2.89	2.82	3.58	4.83	5.37
Max.Current	[A]	3.6	4.14	5.19	4.95	4.89	8.67	8.46	10.74	14.49	16.11
Rated Speed	[r/min]	3000									
Max. Speed	[r/min]	5000									
Inertia	[kg · m^{2}X 10^{-4}]	0.02	0.05	0.06	0.11	0.18	0.32	0.67	1.09	1.51	1.93
	[gf · cm · s^2]	0.02	0.05	0.07	0.12	0.19	0.33	0.69	1.11	1.54	1.97
Allowable Load Inertia Ratio		30 times of motor inertia		20 times of motor inertia				15 times of motor inertia			
Rated Power Rate	[kW/s]	10.55	23.78	35.34	8.89	22.26	50.49	24.05	33.39	43.02	52.57
Speed/Position Detector	Standard Note1)	Quad.Type Incremental 2048[P/R]			Quad.Type Incremental 3000[P/R]						
	Option	Serial Type 18[Bit]			Serial Type 19[Bit]						
Specifications & Features	Structure	Fully closed · Self cooling IP55 Note1)						Fully closed · Self cooling IP65 Note1)			
	Rated Time	Continuous									
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]									
	Ambient Humidity	20 ~ 80[%] (avoid dew-condensation)									
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.									
	E/V	Elevation/vibration 49[m/s2](5G)									
Weight	[kg]	0.38	0.5	0.7	0.82	1.08	1.58	1.88	2.52	3.15	3.80

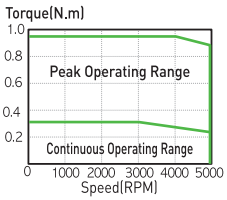
Note1) Except for axis penetration, when you attach reducer to the motor, we don' t guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

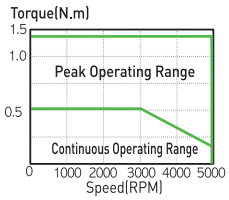
XML-SAR5A



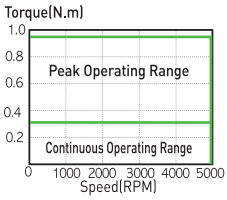
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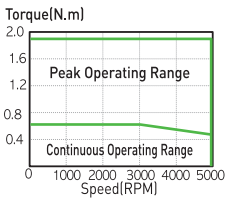
XML-SA015A



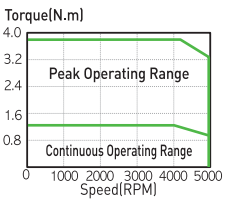
XML-SB01A



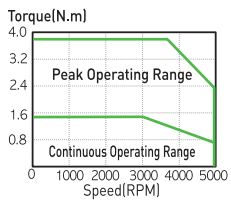
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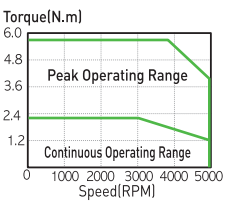
XML-SB04A



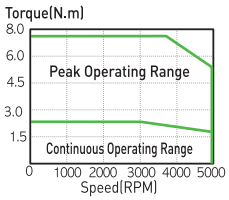
XML-SC04A



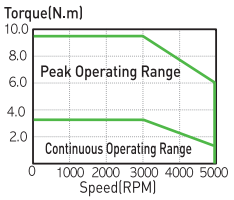
XML-SC06A



XML-SC08A



XML-SC10A



XML Servo Motor Characteristics

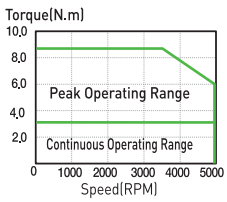
Motor Specifications [Rated 3000r/min]

Servo Motor (XML-□□□□)		SE09A	SE15A	SE22A	SE30A	SF30A	SF50A	HB01A	HB02A	HB04A	HE09A	HE15A	HE30A
Applicable Drive (L7□A□□)		L7□A008	L7□A020		L7□A050	L7□A035	L7□A050	L7□A002		L7□A004	L7□A008	L7□A020	L7□A050
Flange Size(□)		□130				□180		□60			□130		
Rated Output	[kW]	0.9	1.5	2.2	3	3	5	0.1	0.2	0.4	0.9	1.5	3
Rated Torque	[N · m]	2.86	4.77	7	9.55	9.55	15.91	0.32	0.64	1.27	2.86	4.77	9.55
	[kgf · cm]	29.23	48.72	71.45	97.43	97.43	162.38	3.25	6.49	12.99	29.23	48.72	97.43
Max. Instantaneous	[N · m]	8.59	14.32	21.01	28.64	28.64	47.74	0.96	1.91	3.82	8.59	14.32	28.64
	[kgf · cm]	87.69	146.15	214.35	292.29	292.29	487.15	9.74	19.48	38.96	87.69	146.15	292.29
Rated Current	[A]	4.95	8.23	11.98	17.16	16.7	27.4	1.65	1.63	2.89	4.95	8.23	17.16
Max.Current	[A]	14.85	24.69	35.94	51.48	50.1	82.2	4.95	4.89	8.67	14.85	24.69	51.48
Rated Speed	[r/min]	3000											
Max. Speed	[r/min]	5000						3500					
Inertia	[kg · m²X 10⁻⁴]	6.66	12	17.34	22.68	30.74	52.13	0.27	0.33	0.46	19.56	22.27	31.81
	[gf · cm · s²]	6.8	12.24	17.69	23.14	31.37	53.19	0.27	0.34	0.47	19.96	22.72	32.46
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia		20 times of motor inertia			10 times of motor inertia		
Rated Power Rate	[kW/s]	12.32	18.99	28.28	40.20	29.66	48.58	3.34	11.98	34.47	4.10	10.01	22.03
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]						Quad.Type Incremental 1024[P/R]			Quad.Type Incremental 2048[P/R]		
	Option	Serial Type 19[Bit]						X					
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)						Fully closed · Self cooling IP55 Note1)					
	Rated Time	Continuous											
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]											
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)											
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.											
	E/V	Elevation/vibration 49[m/s2](5G)											
Weight	[kg]	5.5	7.5	9.7	11.8	12.4	17.7	0.9	1.2	1.7	5.8	7.4	

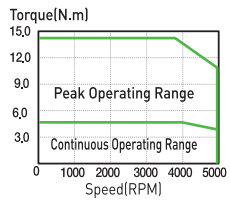
Note1) Except for axis penetration, when you attach reducer to the motor, we don' t guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

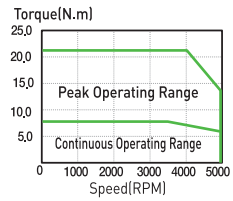
XML-SE09A



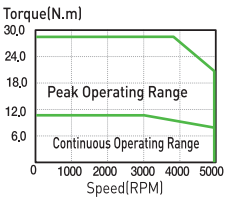
XML-SE15A



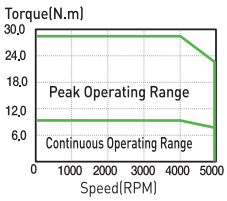
XML-SE22A



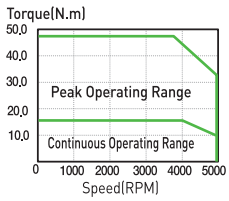
XML-SE30A



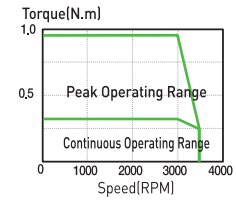
XML-SF30A



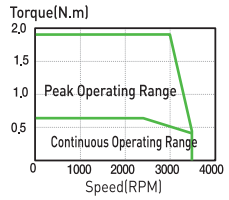
XML-SF50A



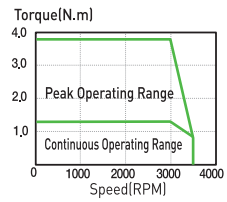
XML-HB01A



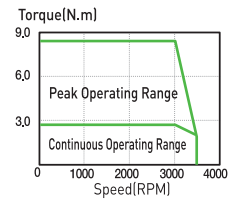
XML-HB02A



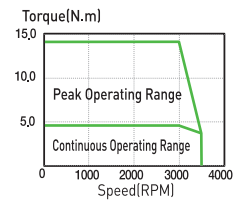
XML-HB04A



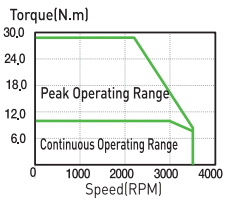
XML-HE09A



XML-HE15A



XML-HE30A



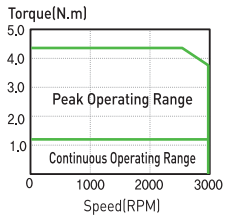
Motor Specifications [Rated 2000r/min]

Servo Motor (XML-□□□□)		SC03D	SC05D	SC06D	SC07D	SE06D	SE11D	SE16D	SE22D
Applicable Drive (L7□A□□)		L7□A004	L7□A008			L7□A008	L7□A010	L7□A020	
Flange Size(□)		□80				□130			
Rated Output	[kW]	0.3	0.45	0.55	0.65	0.6	1.1	1.6	2.2
Rated Torque	[N · m]	1.43	2.15	2.63	3.1	2.86	5.25	7.64	10.5
	[kgf · cm]	14.61	21.92	26.79	31.66	29.23	53.59	77.94	107.17
Max. Instantaneous	[N · m]	4.3	6.45	7.88	9.31	8.59	15.75	22.92	31.51
	[kgf · cm]	43.84	65.77	80.38	94.99	87.69	160.76	233.83	321.52
Rated Current	[A]	2.59	3.23	3.82	4.42	3.97	6.28	9.23	12.37
Max.Current	[A]	7.77	9.69	11.46	13.26	11.91	18.84	27.69	37.11
Rated Speed	[r/min]	2000							
Max. Speed	[r/min]	3000							
Inertia	[kg · m²X10⁻⁴]	0.67	1.09	1.51	1.93	6.66	12	17.34	22.68
	[gf · cm · s²]	0.69	1.11	1.54	1.97	6.8	12.24	17.69	23.14
Allowable Load Inertia Ratio		15 times of motor inertia				10 times of motor inertia			
Rated Power Rate	[kW/s]	30.43	42.27	45.69	49.97	12.32	22.98	33.65	48.64
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]							
	Option	Serial Type 19[Bit]							
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)							
	Rated Time	Continuous							
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]							
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)							
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.							
	E/V	Elevation/vibration 49[m/s2](5G)							
Weight	[kg]	1.9	2.5	3.2	3.9	5.5	7.5	9.7	11.8

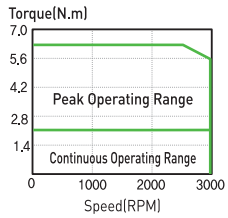
Note1) Except for axis penetration, when you attach reducer to the motor, we don' t guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

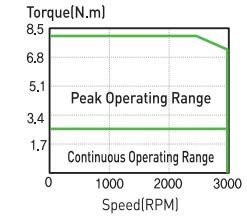
XML-SC03D



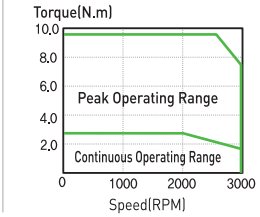
XML-SC05D



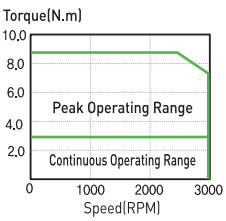
XML-SC06D



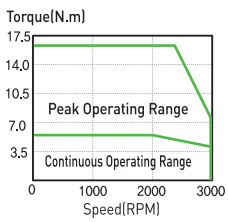
XML-SC07D



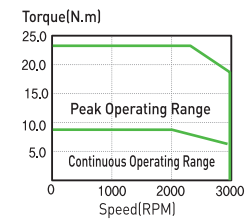
XML-SE06D



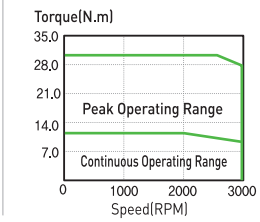
XML-SE11D



XML-SE16D



XML-SE22D



XML Servo Motor Characteristics

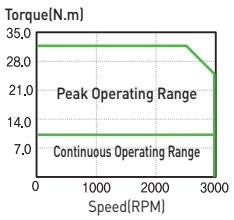
Motor Specifications [Rated 2000r/min]

Servo Motor (XML-□□□□)		SF22D	LF35D	SF55D	SF75D	SG22D	LG35D	SG55D	SG75D
Applicable Drive (L7□A□□)		L7□A020	L7□A035	L7□A050	L7□A075	L7□A020	L7□A035	L7□A050	L7□A075
Flange Size(□)		□180				□220			
Rated Output	[kW]	2.2	3.5	5.5	7.5	2.2	3.5	5.5	7.5
Rated Torque	[N · m]	10.5	16.71	26.26	35.81	10.5	16.71	26.26	35.81
	[kgf · cm]	107.17	170.5	267.93	365.36	107.2	170.52	267.9	365.4
Max. Instantaneous	[N · m]	31.51	50.13	78.77	89.51	31.51	50.13	78.77	89.51
	[kgf · cm]	321.52	511.51	803.8	913.41	321.52	511.51	803.8	913.4
Rated Current	[A]	13.5	15.85	30.25	34.6	12.3	16.05	30.25	38
Max.Current	[A]	40.5	47.55	90.75	86.5	36.9	48.15	90.75	102
Rated Speed	[r/min]	2000							
Max. Speed	[r/min]	3000			2500	3000			2500
Inertia	[kg · m²X 10⁻⁴]	30.74	52.13	83.6	121.35	51.42	80.35	132.41	172.91
	[gf · cm · s²]	31.35	53.16	85.31	123.74	52.47	81.99	135.11	176.44
Allowable Load Inertia Ratio		5 times of motor inertia							
Rated Power Rate	[kW/s]	35.88	53.56	82.56	105.75	21.45	34.75	52.07	74.15
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]							
	Option	Serial Type 19[Bit]							
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)							
	Rated Time	Continuous							
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]							
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)							
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.							
	E/V	Elevation/vibration 49[m/s2](5G)							
Weight	[kg]	12.4	17.7	26.3	35.6	17	22	30.8	37.5

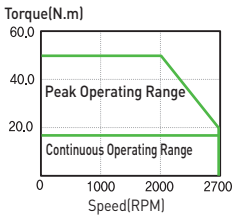
Note1) Except for axis penetration, when you attach reducer to the motor, we don' t guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

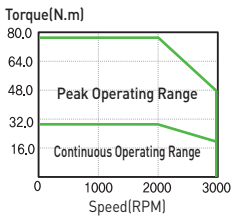
XML-SF22D



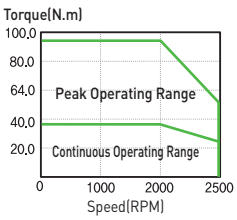
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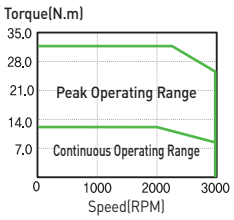
XML-SF55D



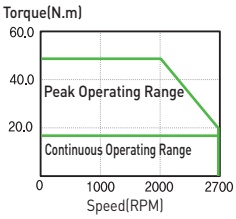
XML-SF75D



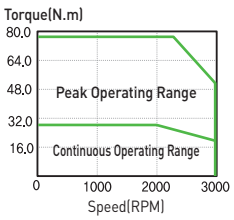
XML-SG22D



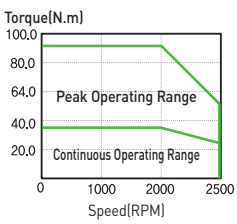
XML-LG35D



XML-SG55D



XML-SG75D



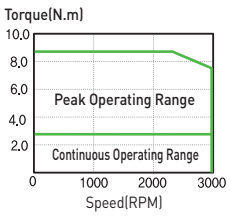
Motor Specifications [Rated 1500r/min]

Servo Motor (XML-□□□□)		SE05G	SE09G	SE13G	SE17G	SF20G	LF30G	SF44G	SF60G	SG20G	LG30G	SG44G	SG60G
Applicable Drive (L7□A□□)		L7□A008	L7□A010	L7□A020		L7□A035		L7□A050	L7□A075	L7□A020	L7□A035	L7□A050	L7□A075
Flange Size(□)		□130				□180				□220			
Rated Output	[kW]	0.45	0.85	1.3	1.7	1.8	2.9	4.4	6	1.8	2.9	4.4	6
Rated Torque	[N · m]	2.86	5.41	8.28	10.82	11.46	18.46	28.01	38.19	11.46	18.46	28.01	38.19
	[kgf · cm]	29.23	55.21	84.44	110.42	116.92	188.37	285.8	389.7	116.92	188.37	285.8	389.7
Max. Instantaneous	[N · m]	8.59	16.23	24.83	32.46	34.37	55.38	84.02	95.48	34.47	55.38	84.02	95.48
	[kgf · cm]	87.69	165.63	253.32	331.26	350.75	565.1	857.39	974.3	350.8	565.1	857.39	974.3
Rated Current	[A]	3.97	6.47	10	12.75	14.7	15.92	31.75	38	13.1	16.19	31.5	38
Max.Current	[A]	11.91	19.41	30	38.25	44.1	47.64	95.25	102	39.3	48.57	94.5	102
Rated Speed	[r/min]	1500											
Max. Speed	[r/min]	3000				3000	2700	3000	2500	3000	2700	3000	2500
Inertia	[kg · m²X 10⁻⁴]	6.66	12	17.34	22.68	30.74	52.13	83.6	121.35	51.42	80.35	132.41	172.91
	[gf · cm · s²]	6.8	12.24	17.69	23.14	31.37	53.19	85.31	123.83	52.47	81.99	135.11	176.44
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia							
Rated Power Rate	[kW/s]	12.32	24.4	39.49	51.63	42.71	65.37	93.83	120.21	25.53	42.41	59.24	84.36
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]											
	Option	Serial Type 19[Bit]											
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)											
	Rated Time	Continuous											
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]											
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)											
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.											
	E/V	Elevation/vibration 49[m/s2](5G)											
Weight	[kg]	5.5	7.5	9.7	11.8	12.4	17.7	26.3	35.6	17	22	30.8	37.52

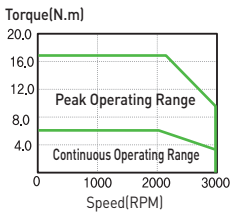
Note1) Except for axis penetration, when you attach reducer to the motor, we don' t guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

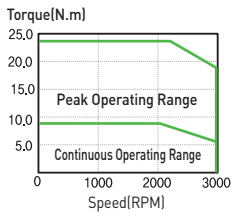
XML-SE05G



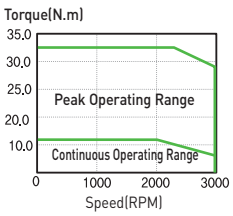
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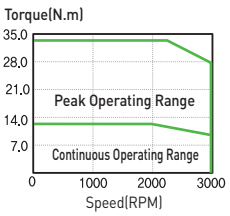
XML-SE13G



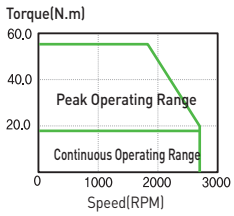
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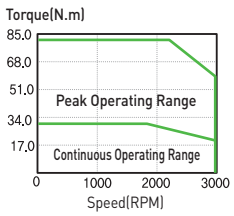
XML-SF20G



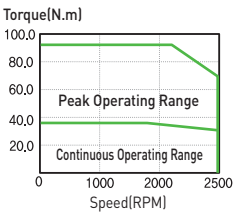
XML-LF30G



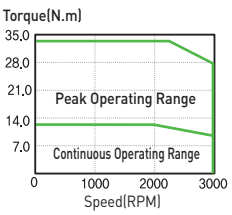
XML-SF44G



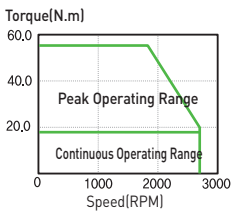
XML-SF60G



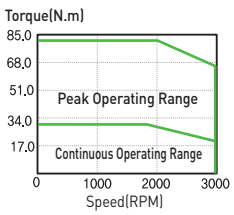
XML-SG20G



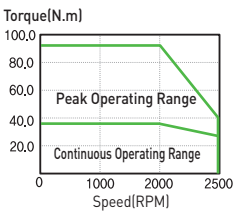
XML-LG30G



XML-SG44G



XML-SG60G



XML Servo Motor Characteristics

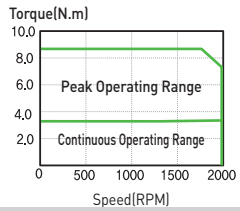
Motor Specifications [Rated 1000r/min]

Servo Motor (XML-□ □ □ □)		SE03M	SE06M	SE09M	SE12M	SF12M	SF20M	LF30M	SF44M	SG12M	SG20M	LG30M	SG44M	SG60M
Applicable Drive (L7□A□ □)		L7□A004	L7□A008	L7□A010	L7□A020		L7□A035		L7□A050	L7□A020	L7□A035		L7□A050	L7□A075
Flange Size(□)		□130				□180				□220				
Rated Output	[kW]	0.3	0.6	0.9	1.2	1.2	2	3	4.4	1.2	2	3	4.4	6
Rated Torque	[N · m]	2.86	5.73	8.59	11.46	11.46	19.1	28.64	42.01	11.46	19.1	28.64	42.01	57.29
	[kgf · cm]	29.23	58.46	87.69	116.92	116.92	194.86	292.29	428.69	116.92	194.86	292.29	428.69	584.6
Max. Instantaneous	[N · m]	8.59	17.19	25.78	34.37	34.37	57.29	85.93	126.04	34.37	57.29	85.93	126.04	171.87
	[kgf · cm]	87.69	175.3	263.06	350.75	350.75	584.58	876.88	1286.08	350.75	584.58	876.88	1286.08	1753.80
Rated Current	[A]	2.51	4.15	5.78	7.63	8.4	14.4	15.99	31.24	8.87	15.02	16.04	31.83	38
Max.Current	[A]	7.53	12.45	17.34	22.89	25.2	43.2	47.97	93.72	26.61	45.06	48.12	95.49	102
Rated Speed	[r/min]	1000												
Max. Speed	[r/min]	2000						1700		2000		1700	2000	
Inertia	[kg · m²X 10⁻⁴]	6.66	12	17.34	22.68	30.74	52.13	83.6	121.35	51.42	80.35	132.41	172.91	291.36
	[gf · cm · s²]	6.8	12.24	17.69	23.14	31.37	53.19	85.31	123.83	52.47	81.99	135.11	176.44	297.31
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia								
Rated Power Rate	[kW/s]	12.32	27.35	42.59	57.89	42.71	69.95	98.15	145.45	25.53	45.39	61.97	102.08	112.65
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]												
	Option	Serial Type 19[Bit]												
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)												
	Rated Time	Continuous												
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]												
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)												
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.												
	E/V	Elevation/vibration 49[m/s2](5G)												
Weight	[kg]	5.5	7.5	9.7	11.8	12.4	17.7	26.3	35.6	17	22	30.8	37.5	66.2

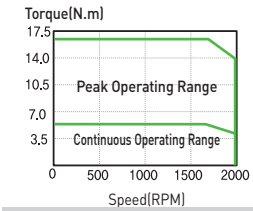
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

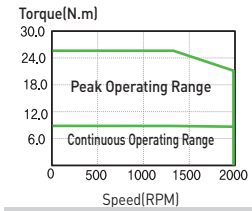
XML-SE03M



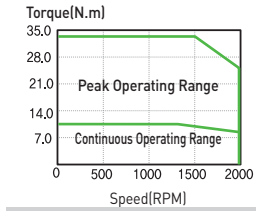
XML-SE06M



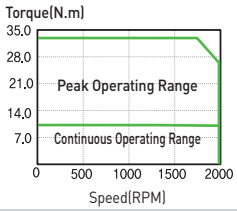
XML-SE09M



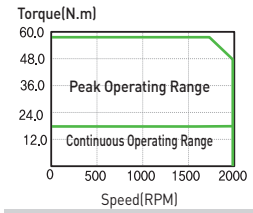
XML-SE12M



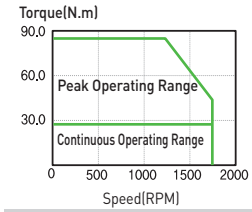
XML-SF12M



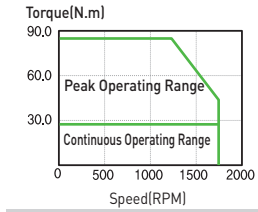
XML-SF20M



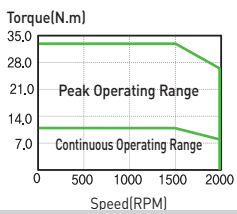
XML-LF30M



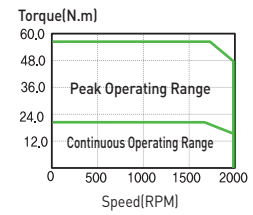
XML-SF44M



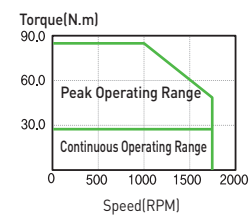
XML-SG12M



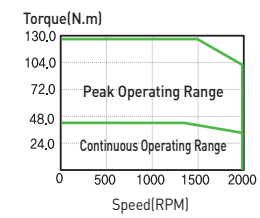
XML-SG20M



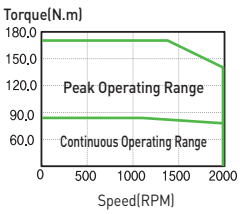
XML-LG30M



XML-SG44M



XML-SG60M



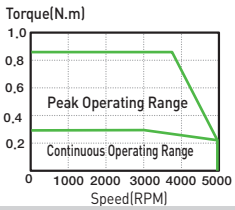
Motor Specifications [Rated 3000r/min]

Servo Motor (XML-□□□□)		SEP09A	SEP15A	SEP22A	SEP30A	SFP30A	SFP50A
Applicable Drive (L7□A□□)		L7□B010	L7□B020		L7□B035		L7□B050
Flange Size(□)		□130				□180	
Rated Output	[kW]	0.9	1.5	2.2	3	3	5
Rated Torque	[N · m]	2.86	4.77	7	9.55	9.55	15.92
	[kgf · cm]	29.23	48.72	71.46	97.44	97.44	162.4
Max. Instantaneous	[N · m]	8.59	14.32	21.01	28.65	28.65	39.79
	[kgf · cm]	87.7	146.16	214.37	292.33	292.33	406.01
Rated Current	[A]	2.97	4.89	7.17	9.78	9.37	15.49
Max.Current	[A]	8.62	14.2	20.84	28.41	27.38	45.27
Rated Speed	[r/min]	3000					
Max. Speed	[r/min]	5000					
Inertia	[kg · m²X10⁻⁴]	6.659	11.999	17.339	22.679	30.74	52.13
	[gf · cm · s²]	6.795	12.244	17.693	23.142	31.367	53.194
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia	
Rated Power Rate	[kW/s]	12.32	19.00	28.28	40.21	42.71	65.37
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]					
	Option	Serial Type 19[Bit]					
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)					
	Rated Time	Continuous					
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]					
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)					
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.					
	E/V	Elevation/vibration 49[m/s2](5G)					
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7

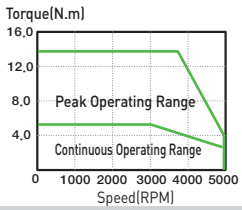
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

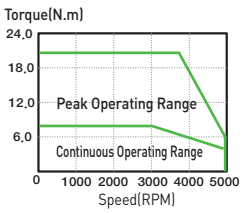
XML-SEP09A



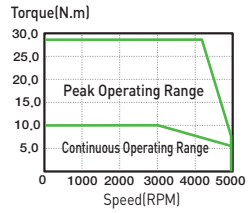
XML-SEP15A



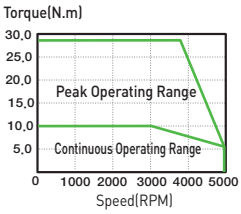
XML-SEP22A



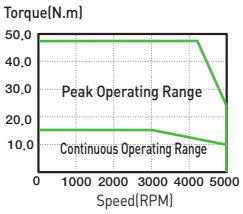
XML-SEP30A



XML-SFP30A



XML-SFP50A



XML Servo Motor Characteristics

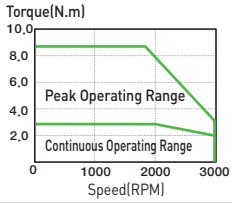
Motor Specifications [Rated 2000r/min]

Servo Motor (XML-□ □ □ □)		SEP06D	SEP11D	SEP16D	SEP22D	SFP22D	SFP35D	SFP55D	SFP75D	SGP22D	SGP35D	SGP55D	SGP75D	SGP110D
Applicable Drive (L7□A□ □)		L7□B010		L7□B020			L7□B035	L7□B050	L7□B075	L7□B020	L7□B035	L7□B050	L7□B075	L7□B150
Flange Size(□)		□130				□180				□220				
Rated Output	[kW]	0.6	1.1	1.6	2.2	2.2	3.5	5.5	7.5	2.2	3.5	5.5	7.5	11
Rated Torque	[N · m]	2.86	5.25	7.64	10.5	10.5	16.71	26.26	35.81	10.50	16.71	26.26	35.81	52.52
	[kgf · cm]	29.23	53.59	77.95	107.19	107.19	170.52	267.96	365.41	107.19	170.52	267.96	365.41	535.93
Max. Instantaneous	[N · m]	8.59	15.76	22.92	31.51	31.51	50.13	65.65	89.52	31.51	50.13	78.78	89.52	131.30
	[kgf · cm]	87.7	160.78	233.86	321.56	321.56	511.57	669.91	913.52	321.56	511.57	803.89	913.52	1339.82
Rated Current	[A]	1.78	3.27	4.79	6.54	6.56	10.07	15.82	21.36	6.27	10.03	15.66	18.42	27.41
Max.Current	[A]	5.18	9.5	13.92	19	19.17	29.43	38.64	52.16	18.43	29.51	46.08	45.25	67.33
Rated Speed	[r/min]	2000												
Max. Speed	[r/min]	3000											2500	
Inertia	[kg · m²X 10⁻⁴]	6.659	11.999	17.339	22.679	30.74	52.13	83.6	121.35	51.42	80.35	132.41	172.91	291.36
	[gf · cm · s²]	6.795	12.244	17.693	23.142	31.367	53.194	85.306	123.827	52.47	81.99	135.11	176.44	297.10
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia								
Rated Power Rate	[kW/s]	12.32	22.99	48.64	91.96	35.89	53.57	82.49	105.67	21.46	34.76	52.08	74.16	94.65
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]												
	Option	Serial Type 19[Bit]												
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)												
	Rated Time	Continuous												
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]												
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)												
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.												
	E/V	Elevation/vibration 49[m/s2](5G)												
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7	26.3	35.6	16.95	21.95	30.8	37.52	66.2

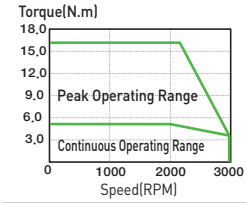
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

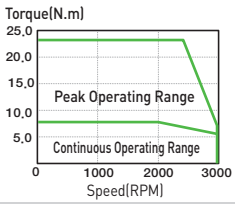
XML-SEP06D



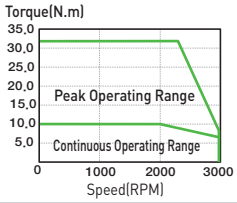
XML-SEP11D



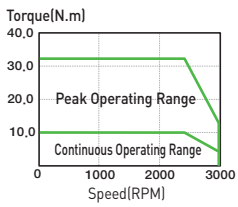
XML-SEP16D



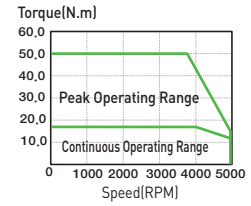
XML-SEP22D



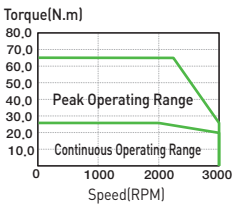
XML-SFP22D



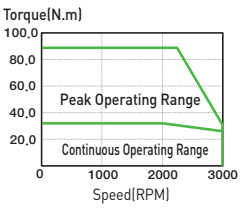
XML-SFP35D



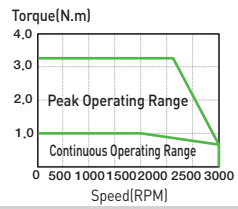
XML-SFP55D



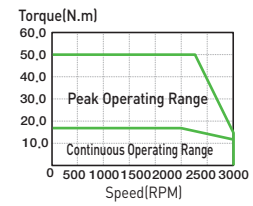
XML-SFP75D



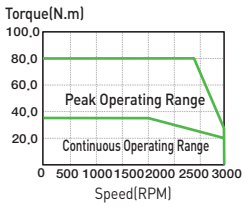
XML-SGP22D



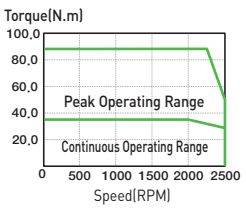
XML-SGP35D



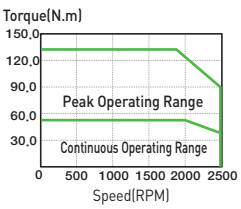
XML-SGP55D



XML-SGP75D



XML-SGP110D



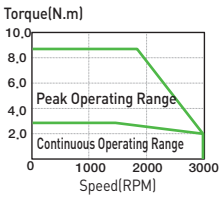
Motor Specifications [Rated 1500r/min]

Servo Motor (XML-□ □ □ □)		SEP05G	SEP09G	SEP13G	SEP17G	SEP20G	SFP30G	SFP44G	SFP60G	SFP75G	SGP20G	SGP30G	SGP44G	SGP60G	SGP85G	SGP110G	SGP150G
Applicable Drive (L7□A□ □)		L7□B010		L7□B020		L7□B020	L7□B050		L7□B075	L7□B150	L7□B020	L7□B050		L7□B075	L7□B150		
Flange Size(□)		□130				□180					□220						
Rated Output	[kW]	0.45	0.85	1.3	1.7	1.8	2.9	4.4	6	7.5	1.8	2.9	4.4	6	8.5	11	15
Rated Torque	[N · m]	2.86	5.41	8.28	10.82	11.46	18.46	28.01	38.2	47.75	11.46	18.46	28.01	38.2	54.11	70.03	95.49
	[kgf · cm]	29.23	55.22	84.45	110.43	116.43	188.39	285.83	389.77	487.21	116.93	188.39	285.83	389.77	552.17	714.57	974.42
Max. Instantaneous	[N · m]	8.59	16.23	24.83	32.47	34.38	55.39	70.03	95.49	119.37	34.38	55.39	70.03	95.49	135.28	175.07	219.6
	[kgf · cm]	87.7	165.65	253.35	331.3	350.79	565.16	714.57	974.42	1218.02	350.79	565.16	714.57	974.42	1380.43	1786.43	22.40
Rated Current	[A]	1.78	3.37	5.19	6.74	7.15	11.12	16.87	22.78	28.13	6.84	11.08	16.71	19.65	28.24	28.28	35.71
Max.Current	[A]	5.18	9.79	15.07	19.58	20.91	165.9	41.21	55.64	65.7	20.11	33	49.15	48.23	69.37	68.83	87.7
Rated Speed	[r/min]	1500															
Max. Speed	[r/min]	3000								2500	3000			2500		2000	
Inertia	[kg · m²X 10⁻⁴]	6.659	11.999	17.339	22.679	30.74	52.13	83.6	121.35	143.82	51.42	80.35	132.41	172.91	291.36	291.36	385.54
	[gf · cm · s²]	6.795	12.244	17.693	23.142	31.367	53.194	85.306	123.827	146.755	52.47	81.99	135.11	176.44	297.31	297.1	393.14
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia											
Rated Power Rate	[kW/s]	12.32	24.4	57.08	97.61	42.72	65.38	93.86	120.23	158.51	25.531	42.41	59.25	84.36	100.5	168.3	214.8
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]															
	Option	Serial Type 19[Bit]															
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)															
	Rated Time	Continuous															
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]															
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)															
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.															
	E/V	Elevation/vibration 49[m/s2](5G)															
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7	26.3	35.6	39.4	16.95	21.95	30.8	37.52	66.2	66.3	92.2

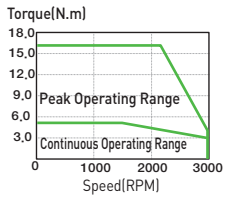
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

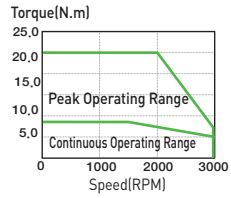
XML-SEP05G



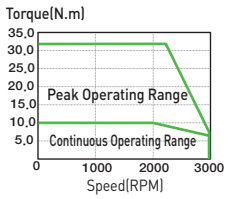
XML-SEP09G



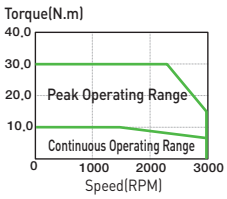
XML-SEP13G



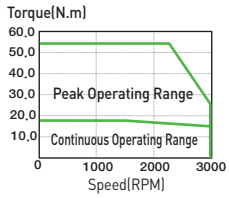
XML-SEP17G



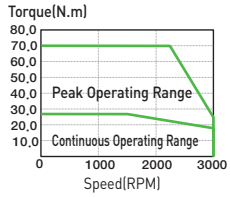
XML-SFP20G



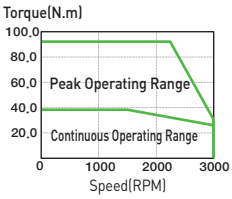
XML-SFP30G



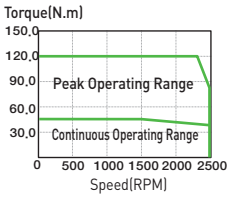
XML-SFP44G



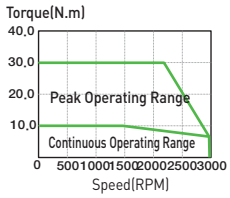
XML-SFP60G



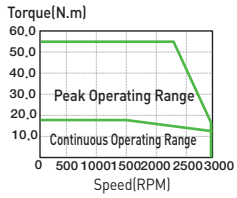
XML-SFP75G



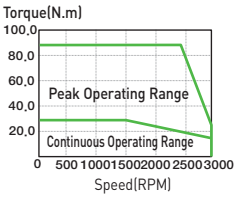
XML-SGP20G



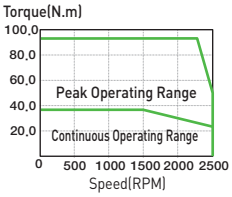
XML-SGP30G



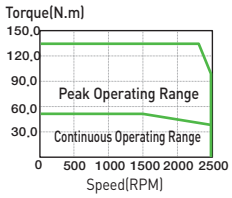
XML-SGP44G



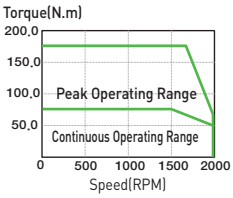
XML-SGP60G



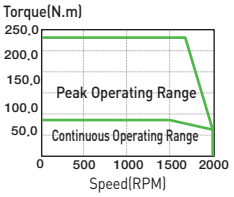
XML-SGP85G



XML-SGP110G



XML-SGP150G



XML Servo Motor Characteristics

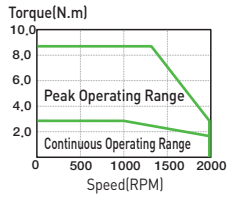
Motor Specifications [Rated 1000r/min]

Servo Motor (XML-□ □ □ □)		SEP03M	SEP06M	SEP09M	SEP12M	SFP12M	SFP20M	SFP30M	SFP44M	SGP12M	SGP20M	SGP30M	SGP44M	SGP60M
Applicable Drive (L7□A□ □)		L7□B010			L7□B035	L7□B020		L7□B050		L7□B020		L7□B050		L7□B150
Flange Size(□)		□130				□180				□220				
Rated Output	[kW]	0.3	0.6	0.9	1.2	1.2	2	3	4.4	1.2	2	3	4.4	6
Rated Torque	[N · m]	2.86	5.73	8.59	11.46	11.46	19.1	28.65	42.02	11.46	19.1	28.65	42.02	57.3
	[kgf · cm]	29.23	58.47	87.7	116.93	116.93	194.88	292.33	428.74	116.93	194.88	292.33	428.74	584.65
Max. Instantaneous	[N · m]	8.59	17.19	25.78	34.38	34.38	57.3	71.62	105.04	34.38	57.3	85.94	105.04	143.24
	[kgf · cm]	87.7	175.4	263.09	350.79	350.79	584.65	730.81	1.074.86	350.79	584.65	876.98	1.071.86	1.461.63
Rated Current	[A]	1.26	2.42	3.62	4.8	4.77	7.88	11.92	17.15	4.72	7.84	11.73	17.29	23.58
Max.Current	[A]	3.65	7.04	10.51	13.95	13.94	23.03	29.12	41.88	13.87	23.06	34.51	50.87	57.92
Rated Speed	[r/min]	1000												
Max. Speed	[r/min]	2000												
Inertia	[kg · m²X 10⁻⁴]	6.659	11.999	17.339	22.679	30.71	52.13	83.6	121.35	51.42	80.35	132.41	172.91	291.36
	[gf · cm · s²]	6.795	12.444	17.693	23.142	31.367	53.194	85.306	123.827	52.47	81.99	135.11	176.44	297.31
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia								
Rated Power Rate	[kW/s]	12.32	27.36	42.6	57.9	42.72	69.97	98.17	145.48	25.53	45.39	61.97	102.08	112.64
Speed/Position Detector	Standard Note1)	Quad. Type Incremental 3000[P/R]												
	Option	Serial Type 19[Bit]												
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)												
	Rated Time	Continuous												
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]												
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)												
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.												
	E/V	Elevation/vibration 49[m/s2](5G)												
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7	26.3	35.6	16.95	21.95	30.8	37.52	66.2

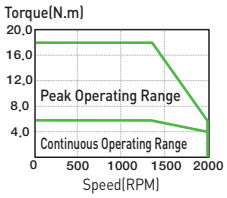
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

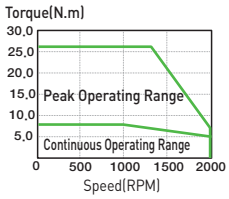
XML-SEP03M



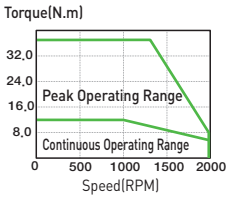
XML-SEP06M



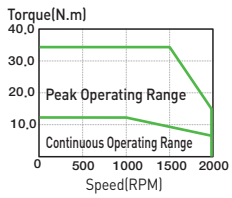
XML-SEP09M



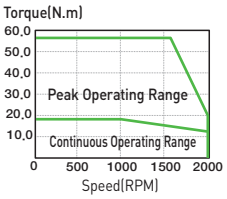
XML-SEP12M



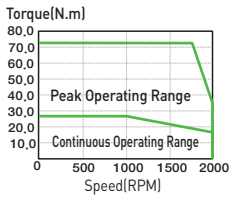
XML-SFP12M



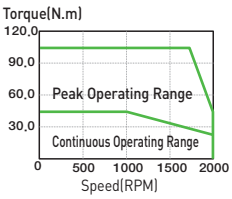
XML-SFP20M



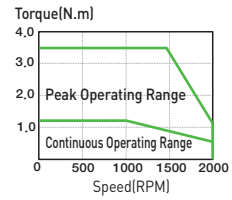
XML-SFP30M



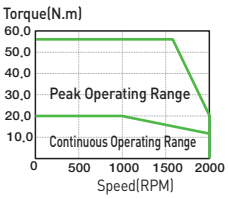
XML-SFP44M



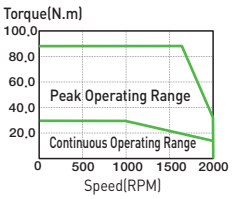
XML-SGP12M



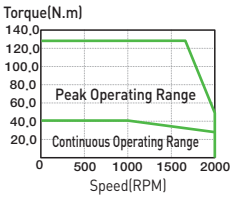
XML-SGP20M



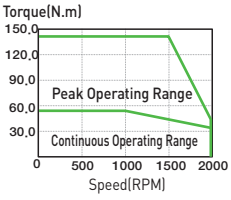
XML-SGP30M



XML-SGP44M



XML-SGP60M



External Dimensions of Servo Motor

SA Series

Plug Specifications



Spec.: 172167-1
(Made by AMP)

Power

Pin No.	Color	Signal
1	Red	U
2	White	V
3	Black	W
4	Green	Ground

(Power Connector Pin Table)

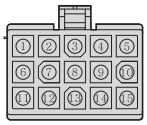


Spec.: 172165-1
(Made by AMP)

Brake

Pin No.	Signal
1	BK+
2	BK-

(Brake Connector Pin Table)

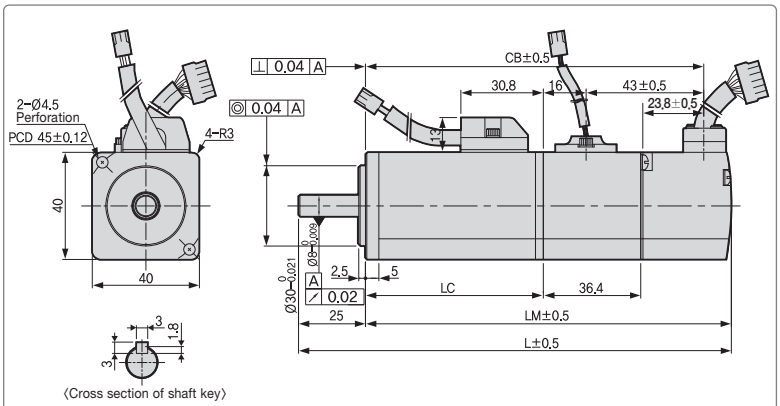


Spec.: 172165-1
(Made by AMP)

Encoder

Pin No.	Signal	Pin No.	Signal
1	A	9	V
2	$\overline{A}$	10	$\overline{V}$
3	B	11	W
4	$\overline{B}$	12	$\overline{W}$
5	Z	13	+5V
6	$\overline{Z}$	14	0V
7	U	15	SHIELD
8	$\overline{U}$		

(Parallel Encoder Connector Pin Table)

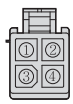


Model	External Dimensions(mm)				Weight(kg)
	L	LM	LC	CB	
SAR3A	101.3(137.6)	76.3(112.6)	42.5(42.4)	66.3(102.3)	0.32(0.67)
SAR5A	108.3(144.6)	83.3(119.6)	49.5(49.4)	73.3(109.3)	0.38(0.73)
SA01A	125.3(161.6)	100.3(136.6)	66.5(66.4)	90.3(126.6)	0.5(0.85)
SA015A	145 .3	120.3	86.5	110.3	0.7

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.
Note4) Refer to page 74 for serial encoder pin table.

SB Series

Plug Specifications



Spec. : 172167-1
(Made by AMP)

Power

Pin No.	Color	Signal
1	Red	U
2	White	V
3	Black	W
4	Green	Ground

(Power Connector Pin Table)

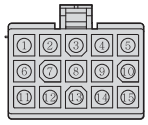


Spec.: 172165-1
(Made by AMP)

Brake

Pin No.	Signal
1	BK+
2	BK-

(Brake Connector Pin Table)

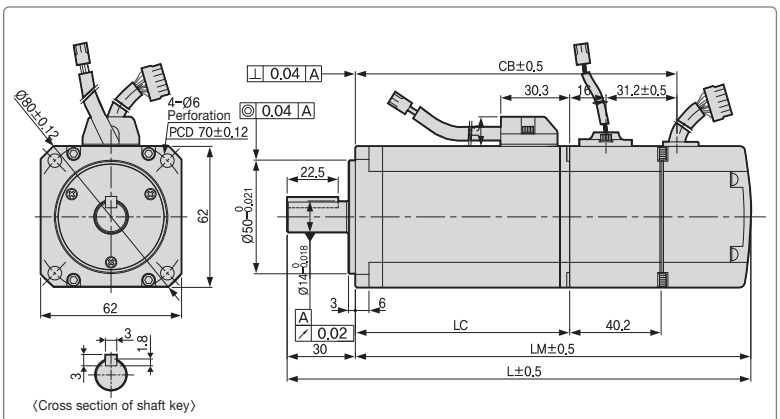


Spec. : 172171-1
(Made by AMP)

Encoder

Pin No.	Signal	Pin No.	Signal
1	A	9	V
2	$\overline{A}$	10	$\overline{V}$
3	B	11	W
4	$\overline{B}$	12	$\overline{W}$
5	Z	13	+5V
6	$\overline{Z}$	14	0V
7	U	15	SHIELD
8	$\overline{U}$		

(Parallel Encoder Connector Pin Table)



Model	External Dimensions(mm)				Weight(kg)
	L	LM	LC	CB	
SB01A	122(162)	92(132)	52.5(52.3)	59.5(99.5)	0.82(1.4)
SB02A	136(176)	106(146)	66.5(66.3)	73.5(113.5)	1.08(1.66)
SB04A	164(204)	134(174)	94.5(94.3)	101.5(141.5)	1.58(2.16)

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.
Note4) Refer to page 74 for serial encoder pin table.

External Dimensions of Servo Motor

SC Series

Plug Specifications



Spec.: 172167-1
(Made by AMP)

Power

Pin No.	Color	Signal
1	Red	U
2	White	V
3	Black	W
4	Green	Ground

(Power Connector Pin Table)

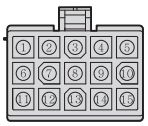


Spec.: 172165-1
(Made by AMP)

Brake

Pin No.	Signal
1	BK+
2	BK-

(Brake Connector Pin Table)

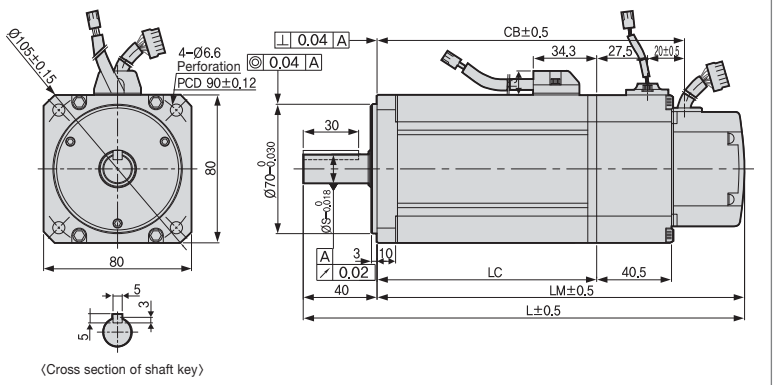


Spec. : 172171-1
(Made by AMP)

Encoder

Pin No.	Signal	Pin No.	Signal
1	A	9	V
2	$\overline{A}$	10	$\overline{V}$
3	B	11	W
4	$\overline{B}$	12	$\overline{W}$
5	Z	13	+5V
6	$\overline{Z}$	14	0V
7	U	15	SHIELD
8	$\overline{U}$		

(Parallel Encoder Connector Pin Table)



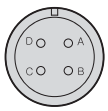
〈Cross section of shaft key〉

Model	External Dimensions(mm)					Weight(kg)
	L	LM	LC	CB	S	
SC04A, SC03D	158.5(198.8)	118.5(158.8)	79(78.8)	86(126.3)	14	1.88(2.92)
SC06A, SC05D	178.5(218.8)	138.5(178.8)	99(98.8)	106(146.3)	16	2.52(3.56)
SC08A, SC06D	198.5(238.8)	158.5(198.8)	119(118.8)	126(166.3)	16	3.15(4.22)
SC10A, SC07D	218.5(258.8)	178.5(218.8)	139(138.8)	146(186.3)	16	3.80(4.94)

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.
Note4) Refer to page 74 for serial encoder pin table.

SE, SEP Series

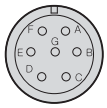
Plug Specifications



Spec. : MS3102A20-4P
(Standard)

Power

Pin No.	Signal
A	U
B	V
C	W
D	Ground

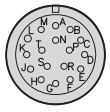


Spec. : MS3102A20-15P
(Brake-attached type)

Brake

Pin No.	Signal	Pin No.	Signal
A	U	D	Ground
B	V	E	BK+
C	W	F	BK-

1. Incremental type

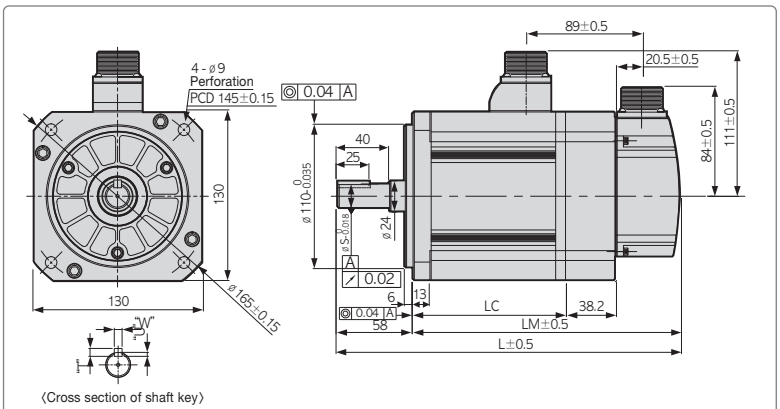


Spec.: MS3102A20-29P

Encoder

Pin No.	Signal	Pin No.	Signal
A	A	M	V
B	$\overline{A}$	N	$\overline{V}$
C	B	P	W
D	$\overline{B}$	R	$\overline{W}$
E	Z	H	+5V
F	$\overline{Z}$	G	0V
K	U	J	SHIELD
L	$\overline{U}$		

(Parallel Encoder Connector Pin Table)



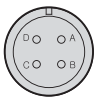
〈Cross section of shaft key〉

Model	External Dimensions(mm)				Key			Weight(kg)
	L	LM	LC	S	T	W	U	
SE09A, SE06D, SE05G, SE03M, SEP09A, SEP06D, SEP05G, SEP03M	201.3(239.3)	143.3(181.3)	93.8(93.6)	19	5	5	3	5.5(7.04)
SE15A, SE11D, SE09G, SE06M, SEP15A, SEP11D, SEP09G, SEP06M	225.3(263.3)	167.3(205.3)	117.8(117.6)					7.54(9.08)
SE22A, SE16D, SE13G, SE09M, SEP22A, SEP16D, SEP13G, SEP09M	249.3(287.3)	191.3(229.3)	141.8(141.6)	22	6	6	3.5	9.68(11.22)
SE30A, SE22D, SE17G, SE12M, SEP30A, SEP22D, SEP17G, SEP12M	273.3(311.3)	215.3(253.3)	165.8(165.6)					11.78(13.32)

Note1) Use DC[24V] for brake input power supply.
Note2) The ( ) is for brake-attached type.
Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.
Note4) Refer to page 74 for serial encoder pin table.

SF, LF, SFP Series

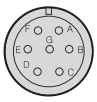
Plug Specifications



Spec.: MS3102A22-22P
(Standard)

Power

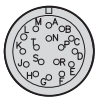
Pin No.	Signal
A	U
B	V
C	W
D	Ground



Spec.: MS3102A24-10P
(Brake-attached type)

Pin No.	Signal	Pin No.	Signal
A	U	D	Ground
B	V	E	BK+
C	W	F	BK-

1. Incremental type



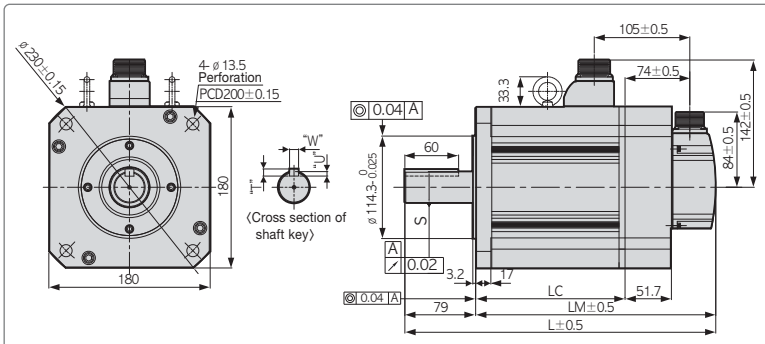
Spec.: MS3102A20-29P

Encoder

Pin No.	Signal	Pin No.	Signal
A	A	M	V
B	$\overline{A}$	N	$\overline{V}$
C	B	P	W
D	$\overline{B}$	R	$\overline{W}$
E	Z	H	+5V
F	$\overline{Z}$	G	0V
K	U	J	SHIELD
L	$\overline{U}$		

(Parallel Encoder Connector Pin Table)

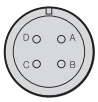
Note1) Use DC[24V] for brake input power supply.
Note2) The ( ) is for brake-attached type.
Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.
Note4) Refer to page 74 for serial encoder pin table.
Note5) Use MS3102A32-17 for SF75G Power connector



Model	External Dimensions(mm)				Key					Weight(kg)
	L	LM	LC	LR	S	QW	T	W	U	
SF30A, SF22D, SF20G, SF12M, SFP30A, SFP22D, SFP20G, SFP12M	261.5 (312.9)	182.5 (233.9)	133(132.7)	79	$35^{+0.01}_{0}$	60	8	10	5	12.4(19.2)
SF50A, LF35D, LF30G, SF20M, SFP50A, SFP20M	295.5 (346.9)	216.5 (267.9)	167(166.7)							17.7(24.9)
SF55D, SF44G, LF30M SFP55D, SFP44G	345.5 (396.9)	266.5 (317.9)	277(216.7)							26.3(33.4)
SF75D, SF60G, SF44M SFP75D, SFP60G, SFP44M	405.5 (456.9)	326.5 (377.9)	277 (276.7)							35.6(42.8)
SF75G,SFP75G	457.5	344.5	295	113	$42^{0}_{-0.016}$	96	8	12	5	39.4

SG, LG, SGP Series

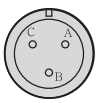
Plug Specifications



Spec. : MS3102A22-22P
(Standard)

Power

Pin No.	Signal
A	U
B	V
C	W
D	Ground



Spec.: MS3102A14S-7P
(Brake-attached type)

Brake

Pin No.	Signal
A	BK+
B	BK-
C	NC

1. Incremental type



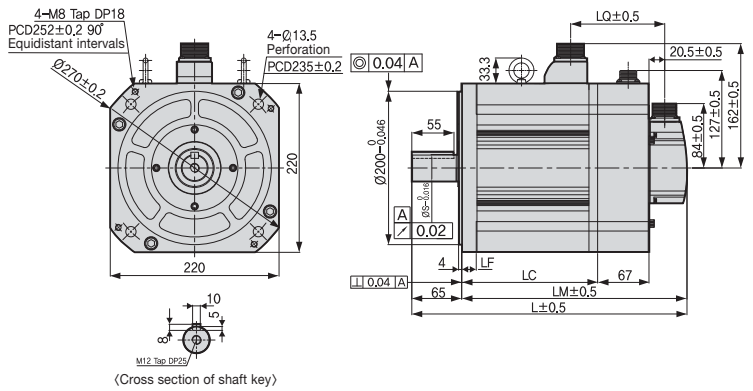
Spec.: MS3102A20-29P

Encoder

Pin No.	Signal	Pin No.	Signal
A	A	M	V
B	$\overline{A}$	N	V
C	B	P	W
D	$\overline{B}$	R	W
E	Z	H	+5V
F	$\overline{Z}$	G	0V
K	U	J	SHIELD
L	$\overline{U}$		

(Parallel Encoder Connector Pin Table)

Note1) In case of SG, use DC[90V] for brake input power supply.
Note2) The ( ) is for brake-attached type.
Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.
Note4) Refer to page 74 for serial encoder pin table.
Note5) Use MS3102A32-17 for SG60M Power connector.



Model	External Dimensions(mm)						Key					Weight (kg)	Power Connector
	L	LM	LC	LR	LF	LQ	S	QK	T	W	U		
SG22D, SG20G, SG12M SGP22D, SGP20G, SGP12M	236.5 (302.7)	171.5 (237.7)	122 (121.2)	65	19	56.4 (122.6)	$35^{0}_{-0.016}$	55	8	10	5	16.95 (30.76)	MS 3102A22 -22P
LG35D, LG30G, SG20M SGP20M	256.5 (322.7)	191.5 (257.7)	142 (141.2)									21.95 (35.7)	
SG55D, SG44G, LG30M SGP55D, SGP44G	292.5 (358.7)	227.5 (293.7)	178 (177.2)									30.8 (44.94)	
SG75D, SG60G, SG44M SGP75D, SGP60G, SGP44M	320.5 (386.7)	255.5 (321.7)	206 (205.2)									37.52 (50.94)	
SG110D,SG85G,SG60M SGP110D, SGP85G,SGP60M	418.5 (484.7)	353.5 (419.7)	304 (303.2)	65	21	66 (132.2)	$45^{0}_{-0.016}$					66.2 (82.6)	MS 3102A32 -17P
SG110G, SG110G	469	354	304	115	21		$42^{0}_{-0.016}$	96	10	12	5	66.3	
SG150G, SG150G	575	459	409	115	35		$55^{+0.000}_{-0.016}$	96	10	16	6	92.2	

HB Series [Hollow Shaft type]

Plug Specifications



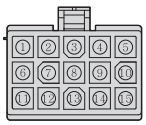
Spec.: 172167-1
(Made by AMP)

Power

Pin No.	Color	Signal
1	Red	U
2	White	V
3	Black	W
4	Green	Ground

(Power Connector Pin Table)

1. Incremental type

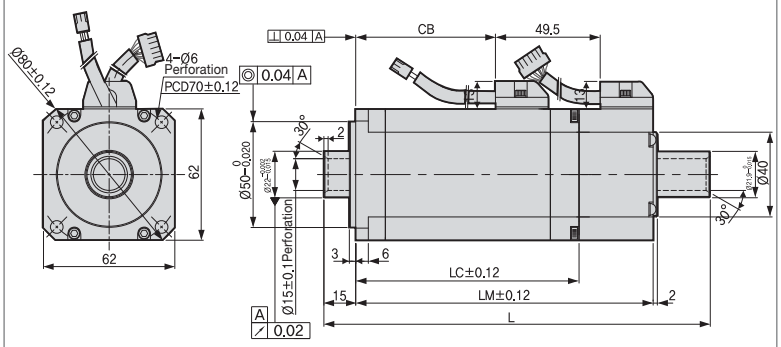


Spec. : 172171-1
(Made by AMP)

Encoder

Pin No.	Signal	Pin No.	Signal
1	A	9	V
2	$\overline{A}$	10	$\overline{V}$
3	B	11	W
4	$\overline{B}$	12	$\overline{W}$
5	Z	13	+5V
6	$\overline{Z}$	14	0V
7	U	15	SHIELD
8	$\overline{U}$		

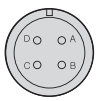
(Parallel Encoder Connector Pin Table)



Model	External Dimensions(mm)					Weight(kg)
	L	LM	LC	CB	Hollow Shaft	
HB01A	140.5	103.5	68.5	24	15	0.89
HB02A	154.5	117.5	82.5	38	15	1.16
HB04A	182.5	140.5	105.5	66	15	1.69

HE Series [Hollow Shaft type]

Plug Specifications

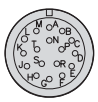


Spec.: MS3102A20-4P
(Standard)

Power

Pin No.	Signal
A	U
B	V
C	W
D	Ground

(Power Connector Pin Table)

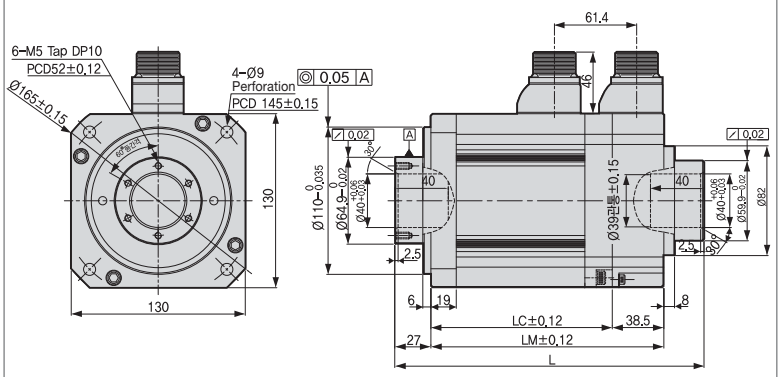


Spec.: MS3102A20-29P

Encoder

Pin No.	Signal	Pin No.	Signal
A	A	M	V
B	$\overline{A}$	N	$\overline{V}$
C	B	P	W
D	$\overline{B}$	R	$\overline{W}$
E	Z	H	+5V
F	$\overline{Z}$	G	0V
K	U	J	SHIELD
L	$\overline{U}$		

(Parallel Encoder Connector Pin Table)



Model	External Dimensions(mm)				Weight(kg)
	L	LM	LC	Hollow Shaft	
HE09A	207	150	111.5	40	5.82
HE15A	231	174	135.5	40	7.43
HE30A	279	222	183.5	40	

Brake and Heat Sink Specification

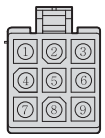
E lectric Brake Specifications

Applicable Motor Series	XML-SA,FAL	XML-SB,FB,FBL	XML-SC,FC,FCL	XML-SE,SEP,FE,FEP	XML-SE,SEP,FF,FFP	XML-SG,SGP,FG,FGP
Purpose	Maintenance					
Input voltage [V]	DC 24V	DC 24V	DC 24V	DC 24V	DC 24V	DC 90V
Static friction torque [N • m]	0.32	1.47	3.23	10.4	40	74
Capacity [W]	6	6.5	9	19.4	25	32
Coil resistance [Ω]	96	89	64	29.6	23	327
Rated current [A]	0.25	0.27	0.38	0.81	1.04	0.28
Braking mechanism	Spring brake					
Insulation grade	GraDde F					

Note1) For the Electronic Brake that is attached to our Servo Motor, the same specifications are to be applied as per the series.
Note2) Do not use it for braking purpose because the electronic brake is only for maintaining the stopped condition.
Note3) The characteristics of electronic brake is measured at 20℃
Note4) Please make sure to always check the voltage specification on the motor because indicated brake specifications are subject to change.

S Series Encoder Pin Map

SA, SB, SC Series

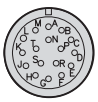


Plug Specification :
172169-1(AMP)

Single Turn (N)		Multi Turn (M)	
핀번호	신호명	핀번호	신호명
1	MA	1	MA
2	$\overline{MA}$	2	$\overline{MA}$
3	SLO	3	SLO
4	$\overline{SLO}$	4	$\overline{SLO}$
5	-	5	VDD_B
6	-	6	GND_B
7	+5V	7	+5V
8	OV	8	OV
9	SHIELD	9	SHIELD

(Serial Encoder Connector Pin Table)

SE, SF, SG Series



17 Pole Plug
(MS3102A20-29P)

Single Turn (N)			
Pin No.	Signal	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	-	H	+5V
F	-	G	0V
K	-	J	MA
L	-		

(Serial Encoder Connector Pin Table)

Multi Turn (M)			
Pin No.	신호명	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	VDD_B	H	+5V
F	GND_B	G	0V
K	-	J	MA
L	-		

Heat Sink Specifications

Flange	Dimensions(mm)	Materials
AP04	250X250X6	Aluminum
AP06	250X250X6	
AP08	250X250X12	
AP13	350X350X20	
AP18	550X550X30	
AP22	650X650X35	

Note1) The data on the product features is measured when those heat sinks are applied.

Servo Motor Designation



XML - F B L P 04 A E K 1

Model Name
XML Series

Motor Shaft
F : Flat Type

Flange Size
A : 40 Flange
B : 60 Flange
C : 80 Flange
E : 130 Flange
F : 180 Flange
G : 220 Flange
H : 250 Flange
J : 280 Flange

Series Classification
None : General Flat Series (200VAC)
L : L Series(200VAC)

Input Voltage
None : 200VAC
P : 400VAC

Motor Capacity
R5 : 50[W]
01 : 100[W]
015 : 150[W]
02 : 200[W]
03 : 300[W]
04 : 400[W]
07 : 650[W]
08 : 800[W]
10 : 1.0[kW]
20 : 2.0[kW]
35 : 3.5[kW]
50 : 5.0[kW]
75 : 7.5[kW]
110 : 11[kW]
150 : 15[kW]

Rated Speed
A : 3000[rpm]
D : 2000[rpm]
G : 1500[rpm]
M : 1000[rpm]

Encoders Type
M : 19bit M-Turn Abs
M8 : 18bit M-Turn Abs [SA Type]

Shape of Shaft End
N : Straight
K : One side Round key (Standard)

Oil Seal, Brake Type
None : None
1 : Oil Seal Attached
2 : Brake Attached
3 : Oil Seal, Brake Attached

Note 1) In case of 40, 60, 80 Flange product, you can apply 200V drive only.
Note2) If you apply nonstandard Encoder, Please contact our office.
Note3) Refer to brake operating voltage

Servo Motor Characteristics

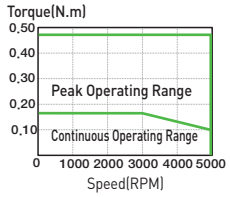
Motor Specifications [Rated 3000r/min, 2000r/min]

Servo Motor (XML-□□□□)		FALR5A	FAL01A	FAL015A	FBL01A	FBL02A	FBL04A	FCL04A	FCL06A	FCL08A	FCL10A	FCL03D	FCL05D	FCL06D	FCL07D
Applicable Drive		L7□A001		L7□A002	L7□A001	L7□A002	L7□A004	L7□A004	L7□A008		L7□A010	L7□A004	L7□A008		
Flange Size(□)		□40			□60			□80							
Rated Output	[kW]	0.05	0.1	0.15	0.1	0.2	0.4	0.4	0.6	0.75	1	0.3	0.45	0.55	0.65
Rated Torque	[N · m]	0.16	0.32	0.48	0.32	0.64	1.27	1.27	1.91	2.39	3.18	1.43	2.15	2.63	3.1
	[kgf · cm]	1.62	3.25	4.87	3.25	6.49	12.99	12.99	19.49	24.36	32.48	14.62	21.92	26.8	31.67
Max. Instantaneous	[N · m]	0.48	0.96	1.43	0.96	1.91	3.82	3.82	5.73	7.16	9.55	4.3	6.45	7.88	9.31
	[kgf · cm]	4.87	9.74	14.62	9.74	19.48	38.96	38.98	58.47	73.08	97.44	43.85	65.77	80.39	95.01
Rated Current	[A]	0.95	1.25	1.76	0.95	1.45	2.6	2.58	3.81	5.02	5.83	2.5	3.05	3.06	3.83
Max.Current	[A]	2.85	3.75	5.28	2.85	4.35	7.8	7.75	11.42	15.07	17.5	7.51	9.16	9.18	11.5
Rated Speed	[r/min]	3000										2000			
Max. Speed	[r/min]	5000										3000			
Inertia	[kg · m²X 10⁻⁴]	0.023	0.042	0.063	0.091	0.147	0.248	0.53	0.897	1.264	1.632	0.53	0.897	1.264	1.63
	[gf · cm · s²]	0.024	0.043	0.065	0.093	0.15	0.253	0.541	0.915	1.29	1.665	0.541	0.915	1.29	1.66
Allowable Load Inertia Ratio		30 times of motor inertia		20 times of motor inertia				15 times of motor inertia							
Rated Power Rate	[kW/s]	10.55	23.78	35.34	11.09	27.6	27.07	30.6	40.66	45.09	62.08	38.73	51.47	54.56	59.03
Speed/Position Detector	Standard Note1)	Serial Multi-Turn Built-in Type(18bit)			Serial Multi-Turn Built-in Type(19bit)										
	Option	×													
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)													
	Rated Time	Continuous													
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]													
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)													
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.													
	E/V	Elevation/vibration 49[m/s2](5G)													
Weight	[kg]	0.31	0.45	0.61	0.56	0.74	1.06	1.52	2.14	2.68	3.3	1.26	2.12	2.66	2.78

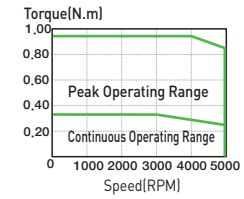
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

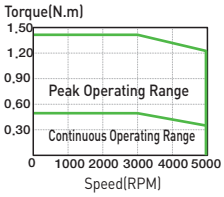
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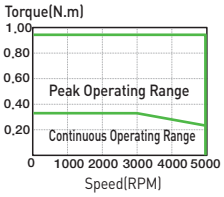
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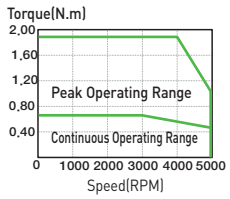
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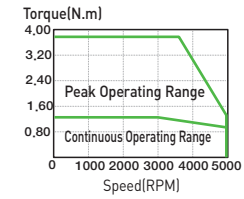
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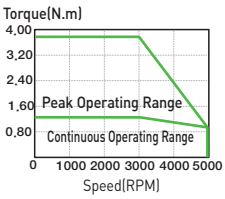
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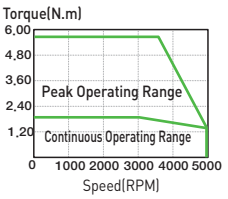
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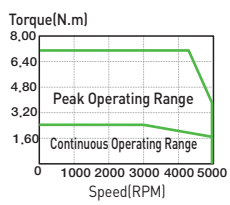
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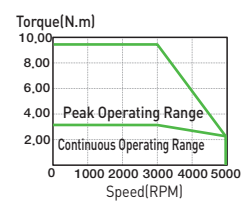
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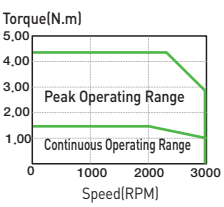
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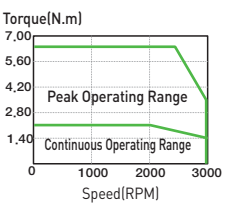
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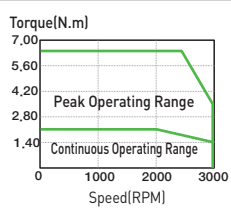
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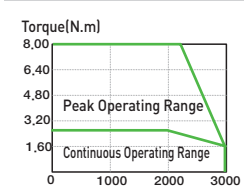
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XML-FCL06D



XML-FCL07D



XML Servo Motor Characteristics

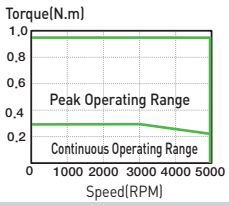
Motor Specifications [Rated 3000r/min]

Servo Motor (XML-□ □ □ □)		FB01A	FB02A	FB04A	FC04A	FC06A	FC08A	FC10A	FE09A	FE15A	FE22A	FE30A	FF30A	FF50A
Applicable Drive		L7□A001	L7□A002	L7□A004	L7□A004	L7□A008			L7□A010	L7□A020		L7□A035	L7□A035	L7□A050
Flange Size(□)		□60			□80					□130			□180	
Rated Output	[kW]	0.1	0.2	0.4	0.4	0.6	0.75	1	0.9	1.5	2.2	3	3	5
Rated Torque	[N · m]	0.32	0.64	1.27	1.27	1.91	2.39	3.18	2.86	4.77	7	9.55	9.55	15.91
	[kgf · cm]	3.25	6.5	12.99	13	19.5	24.36	32.5	29.2	48.7	71.4	97.4	97.4	162.3
Max. Instantaneous	[N · m]	0.96	1.91	3.82	3.82	5.73	7.16	9.55	8.59	14.32	21.01	28.65	28.65	47.74
	[kgf · cm]	9.74	19.49	38.98	38.98	58.47	73.08	97.44	87.7	146.1	214.3	292.2	292.3	487
Rated Current	[A]	0.95	1.45	2.6	2.58	3.81	5.02	6.7	6.45	9.15	13.24	16.09	15.26	26.47
Max.Current	[A]	2.86	4.35	7.79	7.75	11.42	15.07	20.09	19.35	27.45	39.72	48.27	45.78	79.41
Rated Speed	[r/min]	3000												
Max. Speed	[r/min]	5000												
Inertia	[kg · m²X 10⁻⁴]	0.09	0.15	0.25	0.5	0.88	1.25	1.62	5.66	10.18	14.62	19.04	27.96	46.56
	[gf · cm · s²]	0.09	0.15	0.25	0.51	0.89	1.27	1.65	5.77	10.39	14.92	19.43	28.53	47.51
Allowable Load Inertia Ratio		20 times of motor inertia			15 times of motor inertia				10 times of motor inertia				5 times of motor inertia	
Rated Power Rate	[kW/s]	11.38	27.95	65.9	32.62	41.69	45.78	62.74	14.47	22.38	33.59	47.85	32.59	54.33
Speed/Position Detector	Standard Note1)	Serial Type 19[Bit]												
	Option	×												
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)												
	Rated Time	Continuous												
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]												
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)												
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.												
	E/V	Elevation/vibration 49[m/s2](5G)												
Weight	[kg]	0.7	0.9	1.3	1.6	2.2	2.7	3.8	5	6.7	8.5	10.1	12.5	17.4

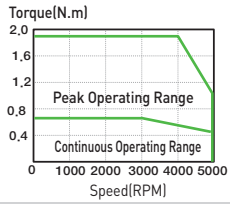
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

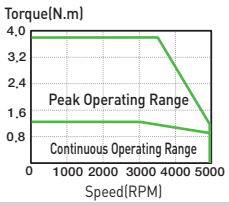
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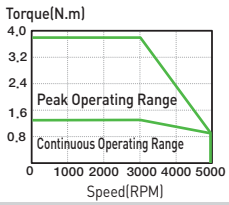
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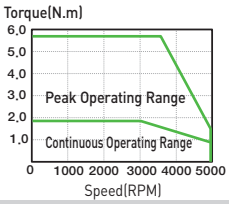
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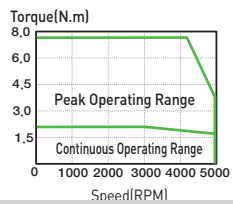
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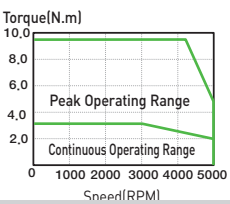
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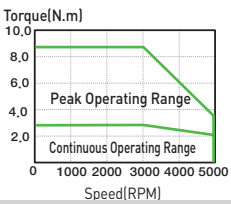
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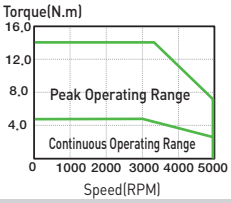
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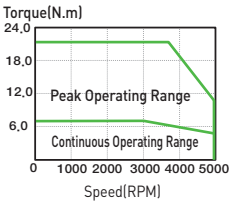
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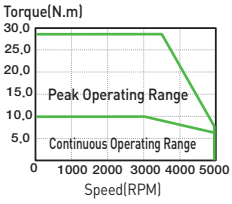
XML-FE15A



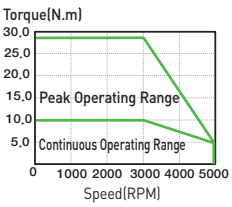
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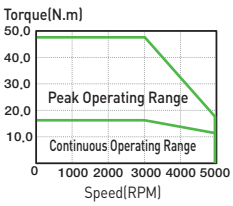
XML-FE30A



XML-FF30A



XML-FF50A



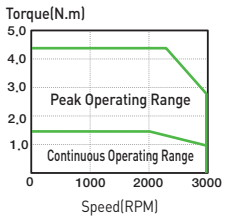
Motor Specifications [Rated 2000r/min]

Servo Motor (XML-□ □ □ □)		FC03D	FC05D	FC06D	FC07D	FE06D	FE11D	FE16D	FE22D
Applicable Drive		L7□A004	L7□A008				L7□A010	L7□A020	
Flange Size(□)		□80				□130			
Rated Output	[kW]	0.3	0.45	0.55	0.65	0.6	1.1	1.6	2.2
Rated Torque	[N · m]	1.43	2.15	2.6	3.1	2.86	5.25	7.63	10.5
	[kgf · cm]	14.6	21.9	26.8	31.7	29.20	53.6	77.9	107.1
Max. Instantaneous	[N · m]	4.3	6.45	7.88	9.31	8.59	15.75	22.92	31.51
	[kgf · cm]	43.8	65.8	80.4	95	87.7	160.7	233.8	321.4
Rated Current	[A]	2.5	3.05	3.06	3.83	4.56	6.47	10.98	12.97
Max.Current	[A]	7.51	9.16	9.18	11.5	13.68	19.41	32.94	38.91
Rated Speed	[r/min]	2000							
Max. Speed	[r/min]	3000							
Inertia	[kg · m²X 10⁻⁴]	0.5	0.88	1.25	1.62	5.66	10.18	14.62	19.04
	[gf · cm · s²]	0.51	0.89	1.27	1.65	5.77	10.39	14.92	19.43
Allowable Load Inertia Ratio		15 times of motor inertia				10 times of motor inertia			
Rated Power Rate	[kW/s]	41.28	52.76	55.39	59.64	14.49	27.08	39.89	57.9
Speed/Position Detector	Standard Note1)	Serial Multi-Turn Built-in Type(19bit)							
	Option	×							
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)							
	Rated Time	Continuous							
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]							
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)							
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.							
	E/V	Elevation/vibration 49[m/s2](5G)							
Weight	[kg]	1.6	2.2	2.7	3.8	5	6.7	8.5	10.1

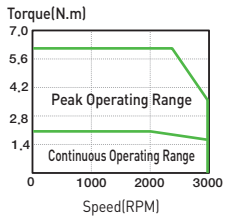
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

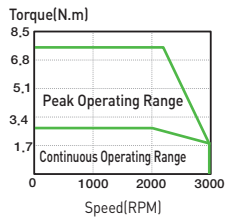
XML-FC03D



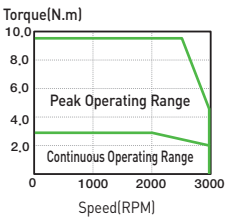
XML-FC05D



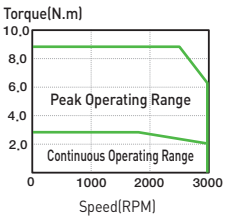
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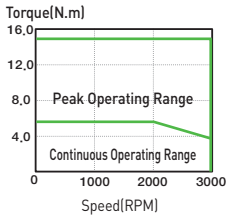
XML-FC07D



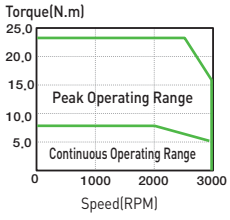
XML-FE06D



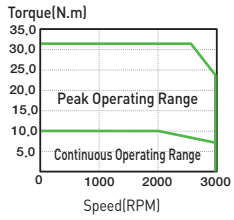
XML-FE11D



XML-FE16D



XML-FE22D



XML Servo Motor Characteristics

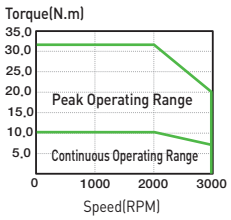
Motor Specifications [Rated 2000r/min]

Servo Motor (XML-□ □ □ □)		FF22D	FF35D	FF55D	FF75D	FG22D	FG35D	FG55D	FG75D
Applicable Drive		L7□A020	L7□A035	L7□A050	L7□A075	L7□A020	L7□A035	L7□A050	L7□A075
Flange Size(□)		□180				□220			
Rated Output	[kW]	2.2	3.5	5.5	7.5	2.2	3.5	5.5	7.5
Rated Torque	[N · m]	10.5	16.7	26.25	35.81	10.5	16.71	26.25	35.81
	[kgf · cm]	107.1	170.4	267.8	365.4	107.1	170.4	267.8	365.4
Max. Instantaneous	[N · m]	31.5	50.1	78.76	89.53	31.51	50.12	78.76	89.53
	[kgf · cm]	321.3	511.4	803.4	931.5	321.3	511.3	803.4	913.5
Rated Current	[A]	13.07	16.48	28.78	32.95	10.25	14.67	29.74	30.17
Max.Current	[A]	39.21	49.44	86.34	98.85	30.75	44.01	89.22	90.51
Rated Speed	[r/min]	2000							
Max. Speed	[r/min]	3000			2500	3000	2700	3000	2500
Inertia	[kg · m²X 10⁻⁴]	27.96	45.56	73.85	106.7	41.13	71.53	117.52	149.4
	[gf · cm · s²]	28.53	47.51	75.36	108.9	41.97	72.99	120.12	152.45
Allowable Load Inertia Ratio		5 times of motor inertia							
Rated Power Rate	[kW/s]	39.43	59.89	93.27	120.15	26.78	38.99	58.51	85.83
Speed/Position Detector	Standard Note1)	Serial Type(19bit)							
	Option	×							
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)							
	Rated Time	Continuous							
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]							
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)							
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.							
	E/V	Elevation/vibration 49[m/s2](5G)							
Weight	[kg]	12.5	17.4	25.12	33.8	15.4	20.2	28.12	33.45

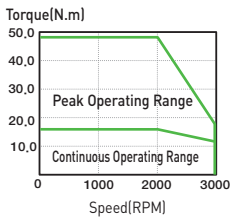
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

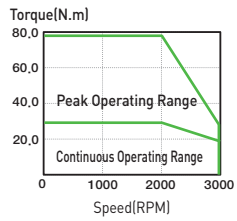
XML-FF22D



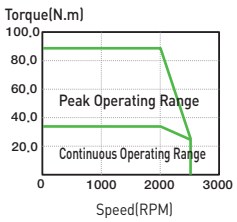
XML-FF35D



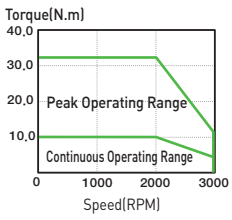
XML-FF55D



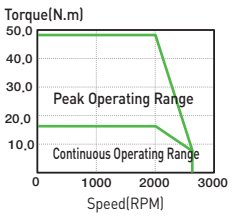
XML-FF75D



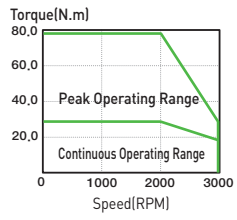
XML-FG22D



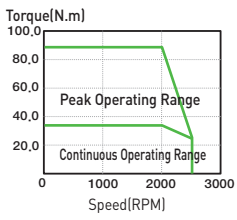
XML-FG35D



XML-FG55D



XML-FG75D



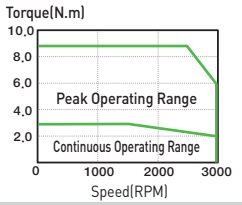
Motor Specifications [Rated1500r/min]

Servo Motor (XML-□□□□)		FE05G	FE09G	FE13G	FE17G	FF20G	FF30G	FF44G	FF60G	FF75G	FG20G	FG30G	FG44G	FG60G
Applicable Drive		L7□A008	L7□A010	L7□A020		L7□A020	L7□A035	L7□A050	L7□A075	L7□A075	L7□A020	L7□A035	L7□A050	L7□A075
Flange Size(□)		□130				□180					□220			
Rated Output	[kW]	0.45	0.85	1.3	1.7	1.8	2.9	4.4	6	7.5	1.8	2.9	4.4	6
Rated Torque	[N · m]	2.86	5.41	8.27	10.82	11.45	18.46	28	38.2	47.7	11.5	18.5	28	38.2
	[kgf · cm]	29.22	55.19	84.41	110.38	116.9	188.3	285.7	389.8	487.2	116.9	188.4	285.8	389.7
Max. Instantaneous	[N · m]	8.59	16.23	24.82	32.46	34.35	55.38	84.03	95.5	143.2	34.4	55.4	84	95.5
	[kgf · cm]	87.66	165.57	253.23	331.14	350.6	564.9	851.1	974.9	1462	350.8	565.1	857.4	974.3
Rated Current	[A]	4.56	6.67	11.9	13.36	12.16	15.98	30.7	35.14	35.26	11.18	16.21	31.72	32.18
Max.Current	[A]	13.68	20.01	35.7	40.08	36.48	47.94	92.1	105.42	105.78	33.54	48.63	95.16	96.54
Rated Speed	[r/min]	1500												
Max. Speed	[r/min]	3000				3000	2700	3000	2500	2200	3000	2700	3000	2500
Inertia	[kg · m²X 10⁻⁴]	5.66	10.18	14.62	19.04	27.96	46.56	73.85	106.7	131.3	14.13	71.53	117.72	149.4
	[gf · cm · s²]	5.77	10.39	14.92	19.43	28.53	47.51	75.36	108.9	134	41.97	72.99	120.12	152.45
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia								
Rated Power Rate	[kW/s]	14.49	28.74	46.81	61.46	46.92	73.14	106.15	136.73	173.63	31.91	47.66	66.64	97.63
Speed/Position Detector	Standard Note1)	Serial Type 19[Bit]												
	Option	×												
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)												
	Rated Time	Continuous												
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]												
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)												
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.												
	E/V	Elevation/vibration 49[m/s2](5G)												
Weight	[kg]	5.0	6.7	8.5	10.1	12.5	17.4	25.2	33.8	38.5	15.4	20.2	28	33.45

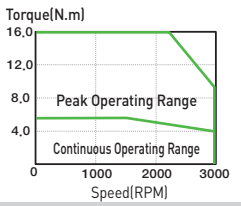
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

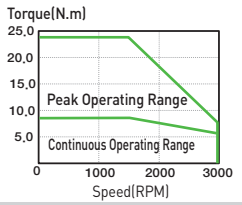
XML-FE05G



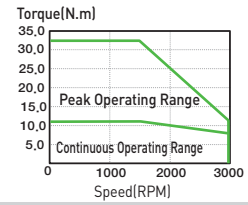
XML-FE09G



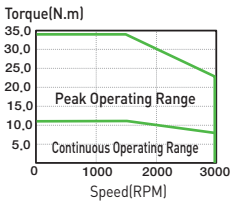
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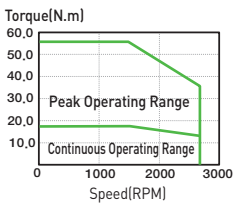
XML-FE17G



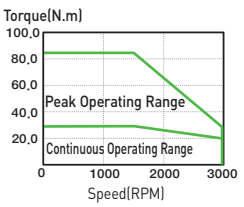
XML-FF20G



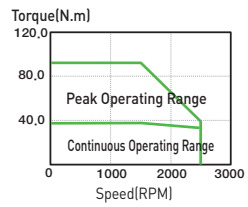
XML-FF30G



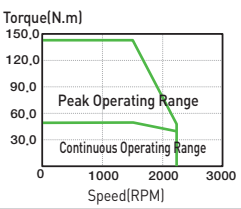
XML-FF44G



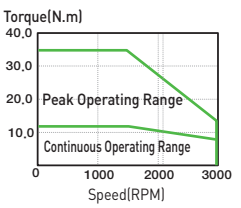
XML-FF60G



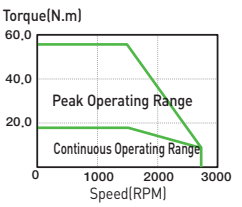
XML-FF75G



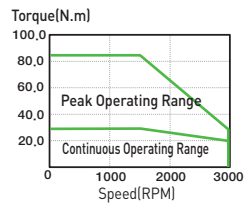
XML-FG20G



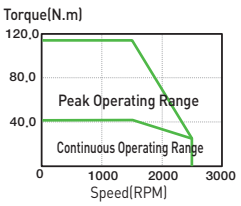
XML-FG30G



XML-FG44G



XML-FG60G



XML Servo Motor Characteristics

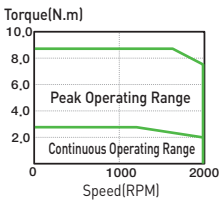
Motor Specifications [Rated 1000r/min]

Servo Motor (XML-□□□□)		FE03M	FE06M	FE09M	FE12M	FF12M	FF20M	FF30M	FF44M	FG12M	FG20M	FG30M	FG44M
Applicable Drive		L7□A004	L7□A008	L7□A010	L7□A020	L7□A020		L7□A035	L7□A050	L7□A020		L7□A035	L7□A050
Flange Size(□)		□130				□180				□220			
Rated Output	[kW]	0.3	0.6	0.9	1.2	1.2	2	3	4.4	1.2	2	3	4.4
Rated Torque	[N · m]	2.86	5.72	8.59	11.46	11.46	19.09	28.64	42.02	11.5	19.1	28.6	42
	[kgf · cm]	29.22	58.4	87.7	116.9	116.9	194.8	292.2	428.7	116.9	194.9	292.3	428.7
Max. Instantaneous	[N · m]	8.59	17.18	25.77	34.22	34.38	57.29	85.94	126.1	34.4	57.3	85.9	126
	[kgf · cm]	87.66	175.3	262.9	349.1	350.7	584.4	876.6	128.6	350.8	584.6	876.9	128.61
Rated Current	[A]	2.73	4.56	6.18	10.67	11.1	12.96	16.58	30.6	11.28	13.1	15.52	27.26
Max.Current	[A]	8.19	13.68	18.54	32.01	33.03	38.88	49.74	91.8	33.84	39.3	46.56	81.78
Rated Speed	[r/min]	1000											
Max. Speed	[r/min]	2000						1700	2000			1700	2000
Inertia	[kg · m²X 10⁻⁴]	5.66	10.18	14.62	19.04	27.96	46.56	73.85	106.7	41.13	71.53	117.72	149.4
	[gf · cm · s²]	5.77	10.39	14.92	19.43	28.53	47.51	75.36	108.9	41.97	72.99	120.12	152.45
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia							
Rated Power Rate	[kW/s]	14.49	32.33	50.48	68.91	46.94	78.27	111.04	165.38	31.91	51	69.7	118.14
Speed/Position Detector	Standard Note1)	Serial Type 19[Bit]											
	Option	×											
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)											
	Rated Time	Continuous											
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]											
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)											
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.											
	E/V	Elevation/vibration 49[m/s2](5G)											
Weight	[kg]	5	6.7	8.5	10.1	12.5	17.4	25.2	33.8	15.4	20.2	28	33.5

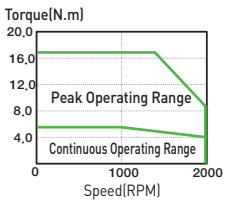
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

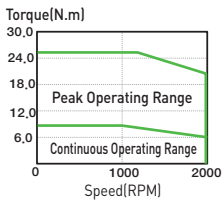
XML-FE03M



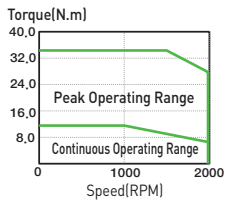
XML-FE06M



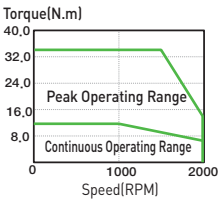
XML-FE09M



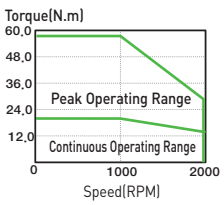
XML-FE12M



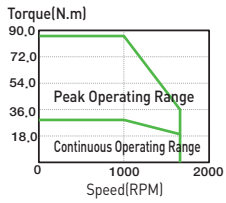
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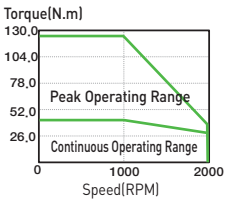
XML-FF20M



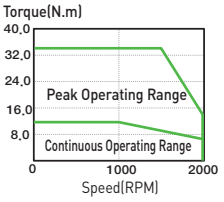
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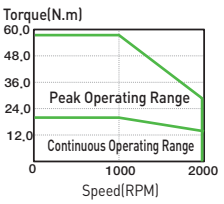
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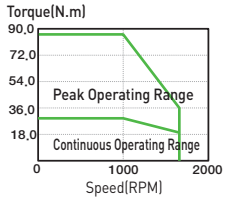
XML-FG12M



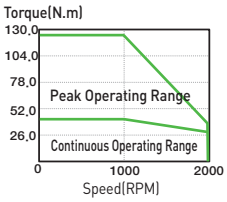
XML-FG20M



XML-FG30M



XML-FG44M



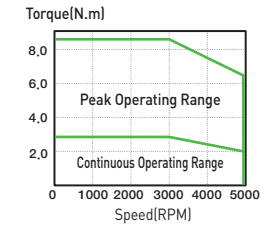
Motor Specifications [Rated 3000r/min]

Servo Motor (XML-□□□□)		FEP09A	FEP15A	FEP22A	FEP30A	FFP30A	FFP50A
Applicable Drive		L7□B010□	L7□B020□	L7□B035□			L7□B050□
Flange Size(□)		□130				□180	
Rated Output	[kW]	0.9	1.5	2.2	3	3	5
Rated Torque	[N · m]	2.86	4.77	7	9.55	9.55	15.92
	[kgf · cm]	29.33	48.72	71.46	97.44	97.44	162.4
Max. Instantaneous	[N · m]	8.59	14.32	20.01	28.65	28.65	38.79
	[kgf · cm]	87.7	146.16	214.37	292.33	292.33	406.01
Rated Current	[A]	3.47	6.68	9.12	9.94	9.79	16.07
Max.Current	[A]	10.4	20.03	27.35	29.81	29.38	48.22
Rated Speed	[r/min]	3000					
Max. Speed	[r/min]	5000					
Inertia	[kg · m²X10⁻⁴]	5.659	10.179	14.619	19.04	27.96	46.56
	[gf · cm · s²]	5.774	10.387	14.917	19.429	28.531	47.51
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia	
Rated Power Rate	[kW/s]	14.5	22.4	33.55	47.89	32.61	54.4
Speed/Position Detector	Standard Note1)	Serial Type 19[Bit]					
	Option	×					
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)					
	Rated Time	Continuous					
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]					
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)					
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.					
	E/V	Elevation/vibration 49[m/s2](5G)					
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7

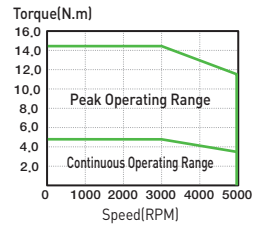
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

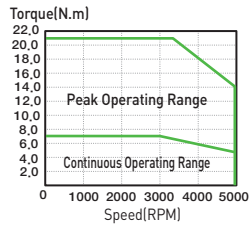
XML-FEP09A



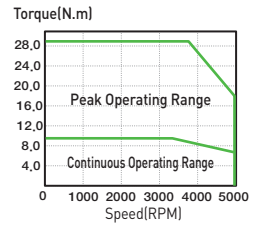
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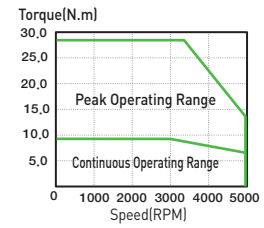
XML-FEP22A



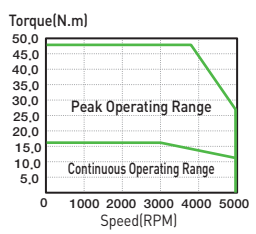
XML-FEP30A



XML-FFP30A



XML-FFP50A



XML Servo Motor Characteristics

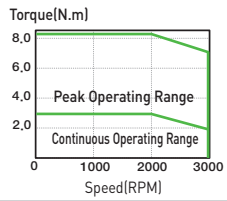
Motor Specifications [Rated 2000r/min]

Servo Motor (XML-□□□□)		FEP06D	FEP11D	FEP16D	FEP22D	FFP22D	FFP35D	FFP55D	FFP75D	FGP22D	FGP35D	FGP55D	FGP75D	FGP110D
Applicable Drive		L7□B010□		L7□B020□			L7□B035□	L7□B050□	L7□B075□	L7□B020□	L7□B035□	L7□B050□	L7□B075□	L7□B150□
Flange Size(□)		□130				□180					□220			
Rated Output	[kW]	0.6	1.1	1.6	2.2	2.2	3.5	5.5	7.5	2.2	3.5	5.5	7.5	11
Rated Torque	[N · m]	2.86	5.25	7.64	10.5	10.5	16.71	26.26	35.81	10.5	16.71	26.26	35.81	52.52
	[kgf · cm]	29.23	53.59	77.95	107.19	107.19	170.52	267.96	365.41	107.19	170.52	267.96	365.41	535.93
Max. Instantaneous	[N · m]	8.59	15.76	22.92	31.51	31.51	50.13	65.65	89.52	31.51	50.13	78.78	89.52	131.30
	[kgf · cm]	87.7	160.78	233.86	321.56	321.56	511.57	669.91	913.52	321.56	511.57	803.89	913.52	1339.82
Rated Current	[A]	3.28	3.4	4.97	6.80	6.93	9.09	14.70	18.97	7.12	8.73	16.04	19.10	27.41
Max.Current	[A]	9.83	10.19	14.92	20.4	20.8	27.26	44.1	47.42	21.35	26.2	48.11	47.76	67.33
Rated Speed	[r/min]	2000												
Max. Speed	[r/min]	2000							2500	3000	2700	3000	2500	
Inertia	[kg · m²X 10⁻⁴]	5.659	10.179	14.619	19.04	27.96	46.56	73.85	106.73	41.13	71.53	117.72	149.4	291.36
	[gf · cm · s²]	5.774	10.387	14.917	19.429	28.531	47.51	75.357	108.908	41.67	72.99	120.12	152.45	297.31
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia								
Rated Power Rate	[kW/s]	14.5	27.1	39.92	57.95	39.46	59.98	93.38	120.15	26.83	39.04	58.58	85.83	94.65
Speed/Position Detector	Standard Note1)	Serial Type 19[Bit]												
	Option	×												
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)												
	Rated Time	Continuous												
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]												
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)												
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.												
	E/V	Elevation/vibration 49[m/s2](5G)												
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7	26.3	35.6	16.95	21.95	30.8	37.52	66.2

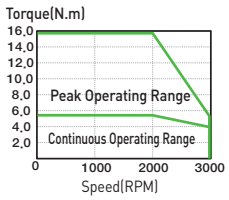
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

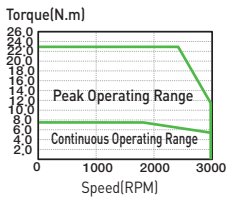
XML-FEP06D



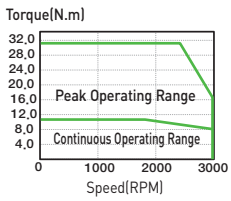
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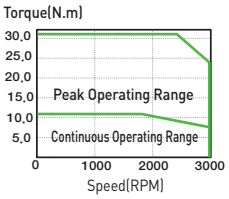
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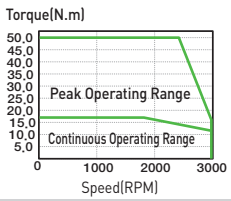
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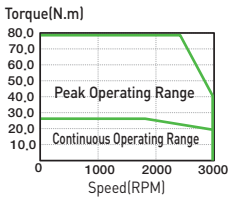
XML-FFP22D



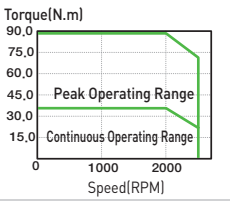
XML-FFP35D



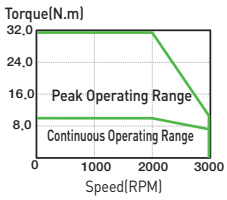
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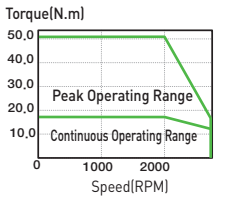
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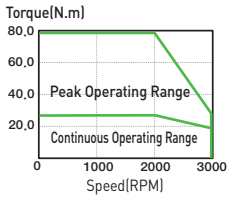
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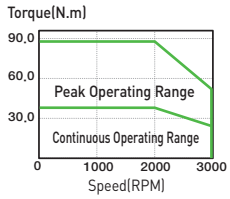
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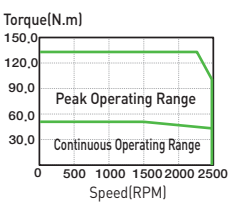
XML-FGP55D



XML-FGP75D



XML-FGP110D



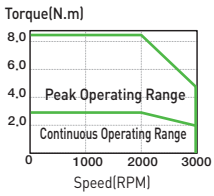
Motor Specifications [Rated 1500r/min]

Servo Motor (XML-□□□□)		FEP05G	FEP09G	FEP13G	FEP17G	FFP20G	FFP30G	FFP44G	FFP60G	FFP75G	FGP20G	FGP30G	FGP44G	FGP60G	FGP85G	FGP110G	FGP150G
Applicable Drive		L7□B010□		L7□B020□			L7□B035□	L7□B050□	L7□B075□		L7□B020□	L7□B035□	L7□B050□	L7□B075□	L7□B150□		
Flange Size(□)		□130				□180					□220						
Rated Output	[kW]	0.45	0.85	1.3	1.7	1.8	2.9	4.4	6	7.5	1.8	2.9	4.4	6	8.5	11	15
Rated Torque	[N · m]	2.86	5.41	8.28	10.82	11.46	18.46	28.01	38.2	47.75	11.46	18.46	28.01	38.2	54.11	70.03	95.49
	[kgf · cm]	29.23	55.22	84.45	110.43	116.93	188.39	285.83	389.77	487.21	116.93	188.39	285.83	389.77	552.17	714.57	974.42
Max. Instantaneous	[N · m]	8.59	16.23	24.83	32.47	34.38	55.39	84.03	95.49	119.37	34.38	55.39	84.03	95.49	135.28	175.07	238.73
	[kgf · cm]	87.7	166.65	253.35	331.3	350.79	565.16	857.49	974.42	1,218.02	350.79	565.16	857.49	974.42	1,380.43	1,786.43	2,436.05
Rated Current	[A]	3.28	3.50	5.39	7.01	7.56	10.14	15.68	20.23	20.01	7.76	9.65	17.11	20.38	28.24	28.28	35.71
Max.Current	[A]	9.83	10.5	16.16	21.02	22.69	30.12	47.04	50.58	50.03	23.29	28.95	51.32	50.95	69.37	68.83	87.7
Rated Speed	[r/min]	1500															
Max. Speed	[r/min]	3000					2700	3000	2500	2200	3000	2700	3000	2500		2000	
Inertia	[kg · m²X 10⁻⁴]	5.659	10.179	14.619	19.04	27.96	46.56	73.85	106.73	131.29	51.42	80.35	132.41	172.91	291.36	51.42	424.5
	[gf · cm · s²]	5.774	10.387	14.917	19.429	28.531	47.51	75.357	108.908	133.969	52.47	81.99	135.11	176.44	297.31	52.47	433.2
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia											
Rated Power Rate	[kW/s]	14.5	28.77	46.85	61.52	46.96	73.21	106.25	136.7	173.64	25.53	45.39	61.97	102.08	100.5	168.3	214.8
Speed/Position Detector	Standard Note1]	Serial Type 19[Bit]															
	Option	×															
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1]															
	Rated Time	Continuous															
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]															
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)															
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.															
	E/V	Elevation/vibration 49[m/s2](5G)															
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7	26.3	35.6	39.4	16.95	21.95	30.8	37.52	66.2	66.3	92.2

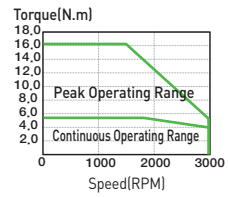
Note1] Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

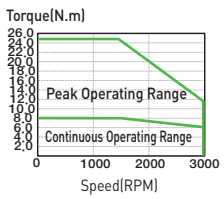
XML-FEP05G



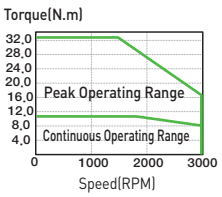
XML-FEP09G



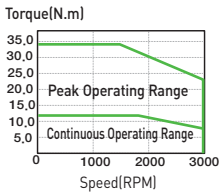
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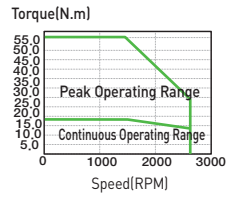
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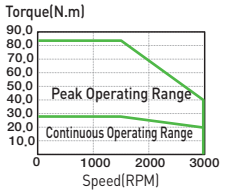
XML-FFP20G



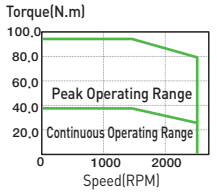
XML-FFP30G



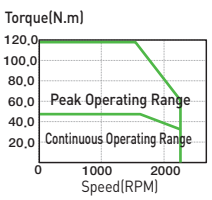
XML-FFP44G



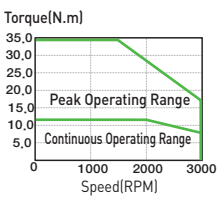
XML-FFP60G



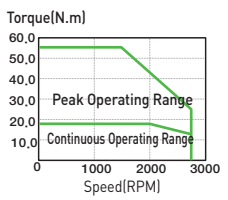
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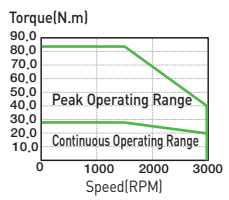
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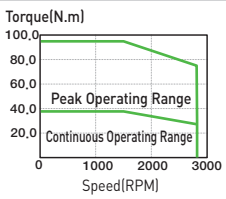
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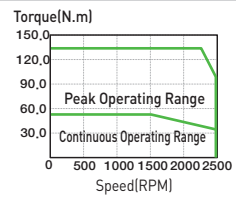
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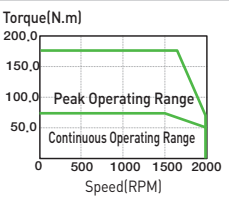
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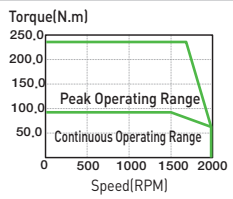
XML-FGP85G



XML-FGP110G



XML-FGP150G



XML Servo Motor Characteristics

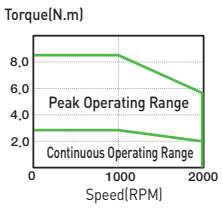
Motor Specifications [Rated 1000r/min]

Servo Motor (XML-□□□□)		FEP03M	FEP06M	FEP09M	FEP12M	FFP12M	FFP20M	FFP30M	FFP44M	FGP12M	FGP20M	FGP30M	FGP44M
Applicable Drive		L7□B010□			L7□B020□			L7□B050□		L7□B020□		L7□B050□	
Flange Size(□)		□130				□180				□220			
Rated Output	[kW]	0.3	0.6	0.9	1.2	1.2	2	3	4.4	1.2	2	3	4.4
Rated Torque	[N · m]	2.86	5.73	8.59	11.46	11.46	19.1	28.65	42.02	11.46	19.1	28.65	42.02
	[kgf · cm]	29.23	58.47	87.7	116.93	116.93	194.88	292.33	428.74	116.93	194.88	292.33	428.74
Max. Instantaneous	[N · m]	8.59	17.19	25.78	34.38	34.38	57.3	85.94	126.05	34.38	57.3	85.94	126.05
	[kgf · cm]	87.7	175.4	263.09	350.79	350.79	584.65	876.98	1286.23	350.79	584.65	876.98	1.071.86
Rated Current	[A]	3.28	3.28	3.33	4.87	4.83	7.94	11.9	16.69	4.75	7..88	11.74	17.39
Max.Current	[A]	9.83	9.83	9.99	14.6	14.5	23.83	35.7	50.08	14.24	235.64	35.22	52.18
Rated Speed	[r/min]	1000											
Max. Speed	[r/min]	2000						1700	2000				
Inertia	[kg · m²X 10⁻⁴]	5.659	10.179	14.619	19.04	27.96	46.56	73.85	106.73	51.42	80.35	132.41	172.91
	[gf · cm · s²]	5.774	10.387	14.917	19.429	28.53	47.51	75.357	108.908	52.47	81.99	135.11	176.44
Allowable Load Inertia Ratio		10 times of motor inertia				5 times of motor inertia							
Rated Power Rate	[kW/s]	14.5	32.25	50.53	68.97	46.96	78.38	111.13	165.41	25.53	45.39	61.97	102.08
Speed/Position Detector	Standard Note1)	Serial Type 19[Bit]											
	Option	×											
Specifications & Features	Structure	Fully closed · Self cooling IP65 Note1)											
	Rated Time	Continuous											
	Ambient Temp	Operating : 0 ~ 40[℃] Storage : -10 ~ 60[℃]											
	Ambient Humidity	90[%]RH Below (avoid dew-condensation)											
	Atmosphere	Avoid direct sunlight, no corrosive gas, inflammable gas, oil mist, or dust.											
	E/V	Elevation/vibration 49[m/s2](5G)											
Weight	[kg]	5.5	7.54	9.68	11.78	12.4	17.7	26.3	35.6	16.95	21.95	30.8	37.52

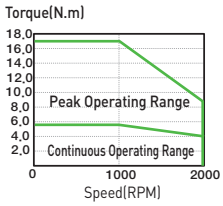
Note1) Except for axis penetration, when you attach reducer to the motor, we don't guarantee IP for reducer. If you bend over specification designated in cable standard, it is difficult to guarantee IP marked It can be satisfied protection grade when you use private cable only.

Speed-Torque Characteristics

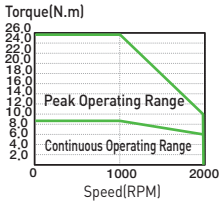
XML-FEP03M



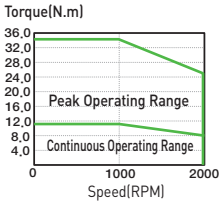
XML-FEP06M



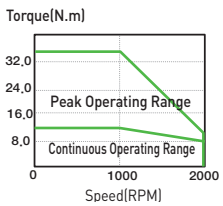
XML-FEP09M



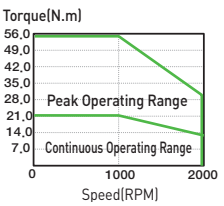
XML-FEP12M



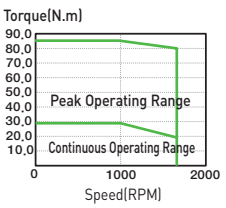
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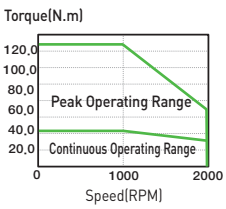
XML-FFP20M



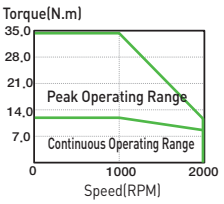
XML-FFP30M



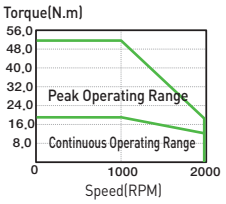
XML-FFP44M



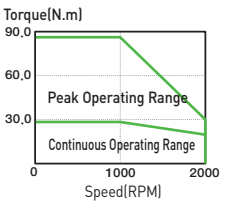
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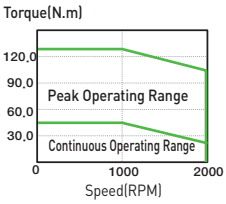
XML-FGP20M



XML-FGP30M



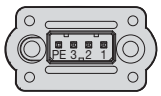
XML-FGP44M



External Dimensions of Servo Motor

FAL Series

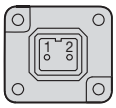
Plug Specifications



Power

Pin No.	Color	Signal
1	Red	U
2	White	V
3	Black	W
4	Green	Ground

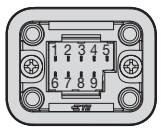
(Power Connector Pin Table)



Brake

Pin No.	Signal
1	BK+
2	BK-

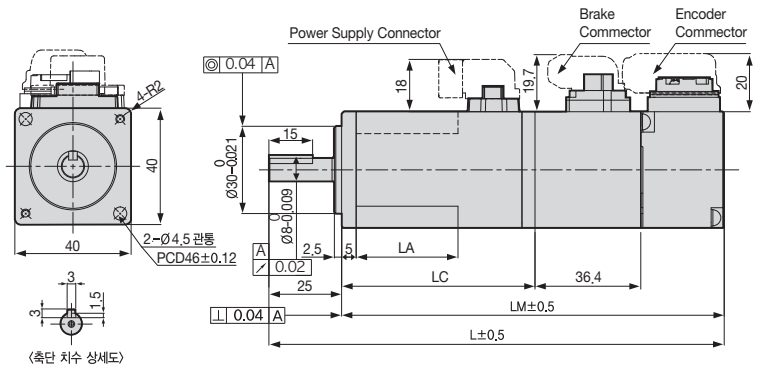
(Brake Connector Pin Table)



Encoder

Multi Turn (M)	
Pin No.	Signal
1	MA
2	SLO
3	-
4	0V
5	SHIELD
6	$\overline{MA}$
7	$\overline{SLO}$
8	-
9	+5V

(Encoder Connector Pin Table)

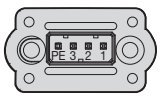


Model	External Dimensions(mm)				Weight(kg)
	L	LM	LC	LA	
FALR5A	103.2(139.6)	78.2(114.6)	49.5	23	0.31(0.66)
FAL01A	120.2(156.6)	95.2(131.6)	66.5	35	0.45(0.80)
FAL015A	140.2	115.2	86.5	35	0.61

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

FBL Series

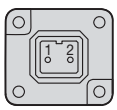
Plug Specifications



Power

Pin No.	Color	Signal
1	Red	U
2	White	V
3	Black	W
4	Green	Ground

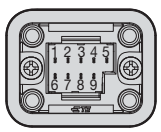
(Power Connector Pin Table)



Brake

Pin No.	Signal
1	BK+
2	BK-

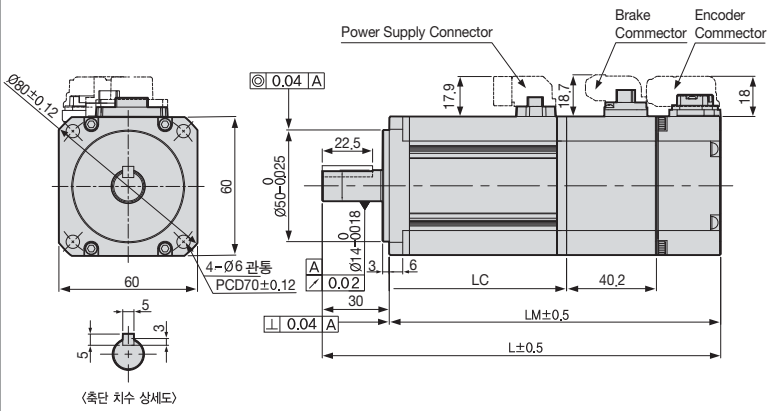
(Brake Connector Pin Table)



Encoder

Multi Turn (M)	
Pin No.	Signal
1	MA
2	SLO
3	GND_B
4	0V
5	SHIELD
6	$\overline{MA}$
7	$\overline{SLO}$
8	VDD_B
9	+5V

(Encoder Connector Pin Table)



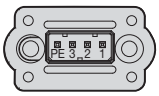
Model	External Dimensions(mm)					Key			Weight (kg)
	L	LM	LC	S	H	T	W	U	
FBL01A	107.2(147.2)	77.2(117.2)	48.5(48.3)	14	-0.018	5	5	3	0.56(1.3)
FBL02A	118.2(158.2)	88.2(128.2)	59.5(59.3)	14	-0.018	5	5	3	0.74(1.48)
FBL04A	138.2(178.2)	108.2(148.2)	79.5(79.3)	14	-0.018	5	5	3	1.06(1.8)

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

External Dimensions of Servo Motor

FCL Series

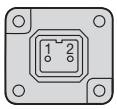
Plug Specifications



Power

Pin No.	Color	Signal
1	Black	U
2	White	V
3	Red	W
PE	Green	Ground

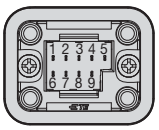
(Power Connector Pin Table)



Brake

Pin No.	Signal
1	BK+
2	BK-

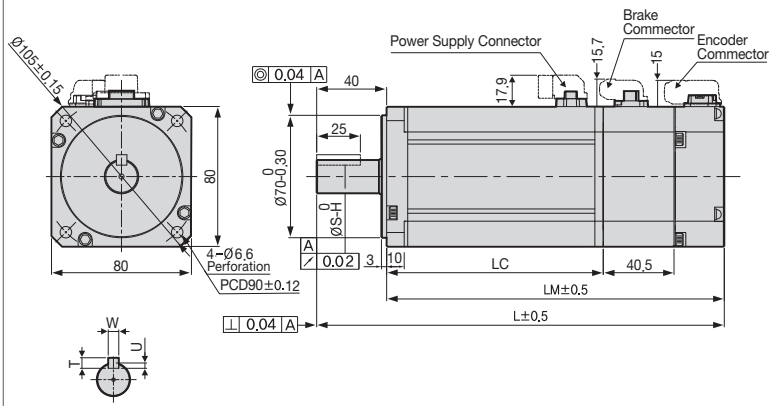
(Brake Connector Pin Table)



Encoder

Multi Turn (M)	
Pin No.	Signal
1	MA
2	SLO
3	GND_B
4	0V
5	SHIELD
6	$\overline{MA}$
7	$\overline{SLO}$
8	VDD_B
9	+5V

(Encoder Connector Pin Table)



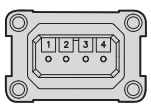
〈Cross section of shaft key〉

Model	External Dimensions(mm)								Weight(kg)
	L	LM	LC	S	H	T	W	U	
FCL04A, FCL03D	138.7(179.5)	98.7(139.5)	70(69.8)	14	-0.018	5	5	3	1.52(2.32)/1.26(2.06)
FCL06A, FCL05D	156.7(197.5)	116.7(157.5)	88(87.8)	19	-0.021	6	6	3.5	2.14(2.94)/2.12(2.92)
FCL08A, FCL06D	174.7(215.5)	134.7(175.5)	106(105.8)	19	-0.021	6	6	3.5	2.68(3.48)/2.66(3.46)
FCL10A, FCL07D	192.7(233.5)	152.7(193.5)	124(123.8)	19	-0.021	6	6	3.5	3.30(4.10)/2.78(3.58)

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

FB Series

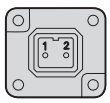
Plug Specifications



Power

Pin No.	Color	Signal
1	Black	W
2	White	V
3	Red	U
4	Green	Ground

(Power Connector Pin Table)



Brake

Pin No.	Signal
1	BK+
2	BK-

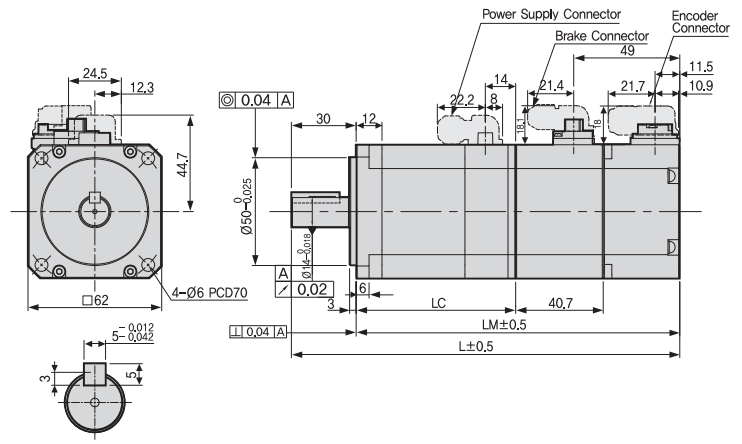
(Brake Connector Pin Table)



Encoder

Multi Turn (M)	
Pin No.	Signal
1	MA
2	SLO
3	GND_B
4	0V
5	SHIELD
6	$\overline{MA}$
7	$\overline{SLO}$
8	VDD_B
9	+5V

(Encoder Connector Pin Table)



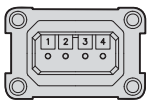
〈Cross section of shaft key S/C 2:1〉

Model	External Dimensions(mm)			Weight(kg)
	L	LM	LC	
FB01A	109(149.2)	79(119.2)	43.5(43)	0.72(1.27)
FB02A	120(160.2)	90(130.2)	54.5(54)	0.94(1.49)
FB04A	140(180.2)	110(150.2)	74.5(74)	1.32(1.87)

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

FC Series

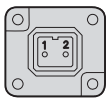
Plug Specifications



Power

Pin No.	Color	Signal
1	Black	W
2	White	V
3	Red	U
4	Green	Ground

(Power Connector Pin Table)



Brake

Pin No.	Signal
1	BK+
2	BK-

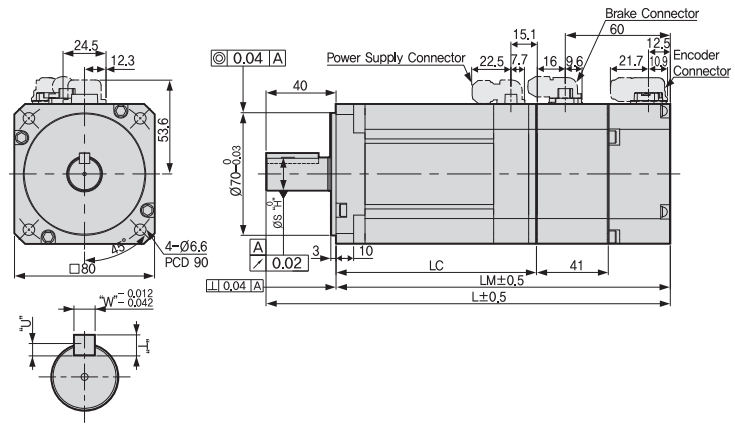
(Brake Connector Pin Table)



Encoder

Single Turn (N)		Multi Turn (M)	
Pin No.	Signal	Pin No.	Signal
1	MA	1	MA
2	SLO	2	SLO
3	-	3	GND_B
4	0V	4	0V
5	SHIELD	5	SHIELD
6	$\overline{MA}$	6	$\overline{MA}$
7	$\overline{SLO}$	7	$\overline{SLO}$
8	-	8	VDD_B
9	+5V	9	+5V

(Encoder Connector Pin Table)



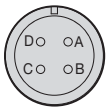
〈Cross section of shaft key S/C 2:1〉

Model	External Dimensions(mm)								Weight(kg)
	L	LM	LC	S	H	T	W	U	
FC04A, FC03D	136.5(177)	96.5(137)	61(60.5)	14	-0.018	5	5	3	1.56(2.6)
FC06A, FC05D	154.5(195)	114.5(155)	79(78.5)	19	-0.021	6	6	3.5	2.18(3.22)
FC08A, FC06D	172.5(213)	132.5(173)	97(96.5)	19	-0.021	6	6	3.5	2.72(3.76)
FC10A, FC07D	190.5(231)	150.5(191)	115(114.5)	19	-0.021	6	6	3.5	3.80(4.34)

Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type. Note3) For external dimensions for oil-sealed type. Please kindly contact us separately.

FE, FEP Series

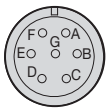
Plug Specifications



Spec.: MS3102A20-4P
(Standard)

Power

Pin No.	Signal
A	U
B	V
C	W
D	Ground



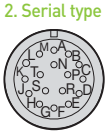
Spec.: MS3102A20-15P
(Brake-attached type)

Pin No.	Signal	Pin No.	Signal
A	U	D	Ground
B	V	E	BK+
C	W	F	BKPin

Pin No.	Signal	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	-	H	+5V
F	-	G	0V
K	-	J	SHIELD
L	-		

(Single Turn Encoder Connector Pin Table)

2. Serial type

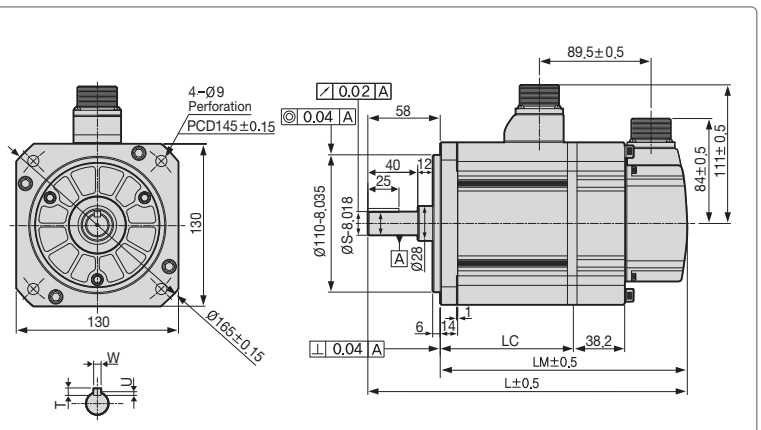


Spec.: MS3102A20-29P

Encoder

Pin No.	Signal	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	VOD_B	H	+5V
F	GND_B	G	$\overline{0V}$
K	-	J	$\overline{SHIELD}$
L	-		

(Multi Turn Encoder Connector Pin Table)



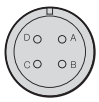
〈Cross section of shaft key〉

Model	External Dimensions(mm)				Key			Weight(kg)
	L	LM	LC	S	T	W	U	
FE09A, FE06D, FE05G, FE03M, FEP09A, FEP06D, FEP05G,FEP03M	197.3(235.3)	139.3(177.3)	89.8(89.6)	19	5	5	3	5.04(6.58)
FE15A, FE11D, FE09G, FE06M, FEP15A, FEP11D, FEP09G, FEP06M	217.3(255.3)	159.3(197.3)	109.8(109.6)	19	5	5	3	6.74(8.28)
FE22A, FE16D, FE13G, FE09M, FEP22A, FEP16D, FEP13G, FEP09M	237.3(275.3)	179.3(217.3)	129.8(129.6)	22	6	6	3.5	8.48(10.02)
FE30A, FE22D, FE17G, FE12M, FEP30A, FEP22D, FEP17G, FEP12M	255.3(293.3)	197.3(235.3)	147.8(147.6)	24	7	8	4	10.05(11.59)

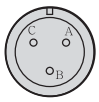
Note1) Use DC[24V] for brake input power supply. Note2) The ( ) is for brake-attached type.

FF, FFP Series

Plug Specifications

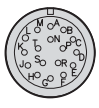


Spec. : MS3102A22-22P
(Standard)



Spec. : MS3102A24-10P
(Brake-attached type)

2. Serial type



Spec. : MS3102A20-29P

Power

Pin No.	Signal
A	U
B	V
C	W
D	Ground

Pin No.	Signal	Pin No.	Signal
A	U	D	Ground
B	V	E	BK+
C	W	F	BK-

Encoder

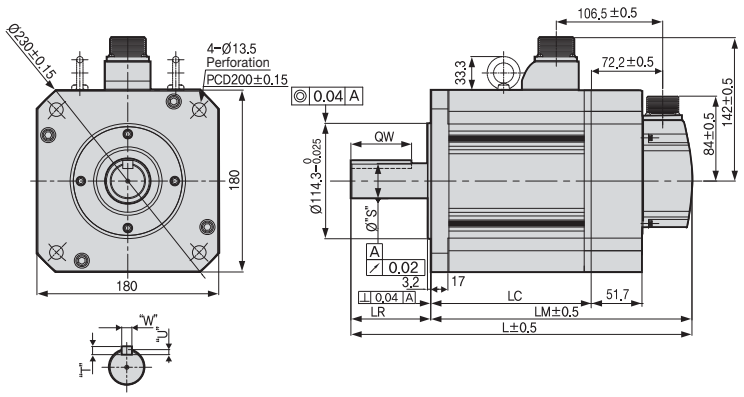
Pin No.	Signal	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	-	H	+5V
F	-	G	0V
K	-	J	SHIELD
L	-		

(Single Turn Encoder Connector Pin Table)

Pin No.	Signal	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	VDD_B	H	+5V
F	GND_B	G	0V
K	-	J	SHIELD
L	-		

(Multi Turn Encoder Connector Pin Table)

Note1] FF30M or above models have eye bolts.
Note2] Use DC[24V] for brake input power supply.
Note3] The ( ) is for brake-attached type.
Note4] Use MS3102A32-17 for FF75G Power connector.

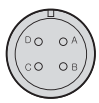


〈Cross section of shaft key〉

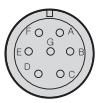
Model	External Dimensions(mm)				Key					Weight(kg)
	L	LM	LC	LR	S	QW	T	W	U	
FF30A, FF22D, FF20G, FF12M FFP30A, FFP22D, FFP20G, FFP12M	257.5(308.9)	178.5(229.9)	129(128.7)	79	$35^{+0.01}_{0}$	60	8	10	5	12.5(19.7)
FF50A, FF35D, FF30G, FF20M FFP50A, FFP35D, FFP30G, FFP20M	287.5(338.9)	208.5(259.9)	159(158.7)							17.4(24.6)
FF55D, FF44G, FF30M FFP55D, FFP44G, FFP30M	331.5(382.9)	252.5(303.9)	203(202.7)							25.2(32.4)
FF75D, FF60G, FF44M FFP75D, FFP60G, FFP44M	384.5(435.9)	305.5(356.9)	256(255.7)		$42^{0}_{-0.016}$			12		33.8(41.0)
FF75G, FFP75G	439.5	326.5	277	113		96				38.5(45.7)

FG, FGP Series

Plug Specifications

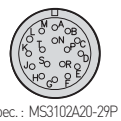


Spec. : MS3102A22-22P
(Standard)



Spec. : 3102A14-7P
(Brake-attached type)

2. Serial type



Spec. : MS3102A20-29P

Power

Pin No.	Signal
A	U
B	V
C	W
D	Ground

Pin No.	Signal
A	BK+
B	BK-
C	NC

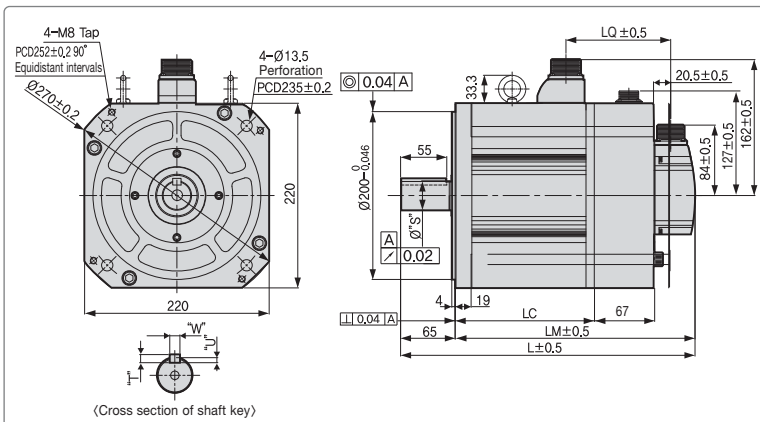
Encoder

Pin No.	Signal	Pin No.	Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	-	H	+5V
F	-	G	0V
K	-	J	SHIELD
L	-		

(Single Turn Encoder Connector Pin Table)

Pin No.	Signal	Pin No.	Signal
A	$\overline{MA}$	M	-
B	MA	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	VDD_B	H	+5V
F	GND_B	G	0V
K	-	J	SHIELD
L	-		

(Multi Turn Encoder Connector Pin Table)



〈Cross section of shaft key〉

Model	External Dimensions(mm)			Key				Weight(kg)
	L	LM	LC	S	T	W	U	
FG22D, FG20G, FG12M FGP22D, FGP20G, FGP12M	229.5(295.7)	164.5(230.7)	115(114.2)	$35^{+0.01}_{0}$	8	10	5	15.42(29.23)
FG35D, FG30G, FG20M FGP35D, FGP30G, FGP20M	250.5(316.7)	185.5(251.7)	136(135.2)					20.22(34.03)
FG55D, FG44G, FG30M FGP55D, FGP44G, FGP30M	282.5(348.7)	217.5(283.7)	168(167.2)					28.02(41.83)
FG75D, FG60G, FG44M FGP75D, FGP60G, FGP44M	304.5(370.7)	239.5(305.7)	190(189.2)	$42^{0}_{-0.016}$		12		33.45(47.26)

Note1] In case of SG, use DC[90V] for brake input power supply. Note2] The ( ) is for brake-attached type.

DD Motor Designation

DD Motor Designation



MDM – D D None 34 D NO H

Motor Type
D : DD MOTOR

Input Power Supply
None : 220VAC

Rated Speed
A : 300rpm
D : 200rpm
G : 150rpm
M : 100rpm

Shape of Shaft End
H : Hollow Type

External Diameter
B : 135mm
C : 175mm
D : 230mm
E : 290mm
F : 360mm

Rated Troque
03 : 3Nm Output
06 : 6Nm Output
09 : 9Nm Output
...
60 : 60Nm Output
...
A6 : 160Nm Output

Encoder Type

	135	175	230	290	360	Remark
NO	20Bit					Single Turn Abs, Biss communication

XML Features of Direct-Drive Motor

Using the own technologies to produce motors, drives and encoders domestically

Optimized for low-speed, high-torque and high-precision operation

- Providing Power connection for the connection of DC-Link Terminal
- Compact Size and Easy Wring (Compared with 3 phase AC Reactor)
- Providing Connection for DC Input (PI, N)

Reduced cogging torque and optimized torque design

- Optimal ratio of the permanent magnet and coil / slot selected through electromagnetic analysis
- Using multiple permanent magnets to reduce torque ripple and to maximize torque
- Using a permanent magnet of high-energy rare earth elements (Nd-Fe-B)

Using the high-performance rotary optical encoder that adopts the Biss protocol

- Resolution of 1,048,576 CPR (Single turn Absolute)
- Using our own encoder technology to reduce the cost and shorten the delivery time

Compatible with our L7 Series AC Servo Drive (3phase AC 220V)

- Both standard I/O type (serial communication supported) and network type (EtherCAT) applicable

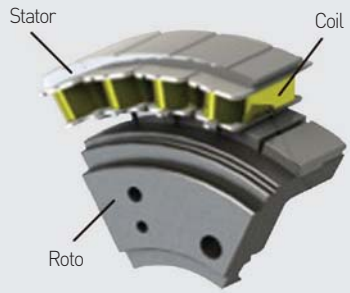
Direct Drive Structure

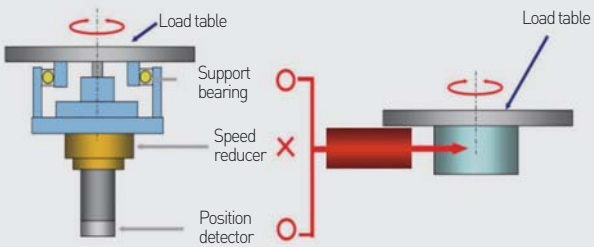
- No backlash impact
- High-precision operation and shortened installation time
- Smooth rotary motion
- Reduced noise

Hollow type that is efficient for wiring and piping

A wide range of products

- Rated output: 63W-.25kW
- Rated torque: 3.0N.m-160N.m (the instantaneous maximum torque should be 3 times the rated torque)
- Rated speed: 150RPM-200RPM
- Frame diameter: 135mm,175mm,230mm,290mm, and 360mm (13 models)





[Speed Reducer + Servo Motor] [DD Motor]

DD Motor Specifications

Ratings and Specifications

- Insulation class : Class B
- Protection class: IP 40
- Cooling type : Fully enclosed self-cooling
- Vibration class : V15
- Insulation resistance : 500 VDC, 10[M Ω] or higher
- Insulation internal voltage: 1800 VAC, 1 second
- Operating voltage: 200 VAC
- Operating temperature : 0 - 40[℃] / Storage temperature: -10~60[℃]
- Ambient humidity : 20 - 80% RH (no condensation)
- Installation location : Place with no toxic substances, such as corrosive and combustible gasses, cutting oil, metal dust, grease or direct sunlight

Line-up Table

Maximum Torque[Nm]			9	18	27	36	54	66	102	120	180	330	480	
Rated speed 200[rpm]	Maximum speed 500[rpm]	Ø135	DB03D	DB06D		DB09D								
		Ø175		DC06D		DC12D								
		Ø230				DD12D								
	Maximum speed 400[rpm]	Ø175					DC18D							
		Ø230					DD22D		DD34D					
	Maximum speed 300[rpm]	Ø290								DE40D	DE60D			
Rated speed 150[rpm]	Maximum speed 250[rpm]	Ø360										DFA1D	DFA6D	

Drive Combination Table

Applicable Drive to Motor

Rated Speed (RPM)	Maximum Speed (RPM)	External Diameter of Motor(Ø)	Applicable Motor	Applicable Drive	Standard Encoders	Encoders Cable (Serial)	Power Cable (Power)
200	500	135	DB03D	L7PA001U	* 20Bit Serial	XLCS-E □ □□ZS	XLCS-PN □ □YS
			DB06D	L7PA001U			
			DB09D	L7PA001U			
		175	DC06D	L7PA002U			
			DC12D	L7PA002U			
	400		DC18D	L7PA002U			
	500	230	DD12D	L7PA004U			
	400		DD22D	L7PA004U			
			DD34D	L7PA008U			
	300	290	DE40D	L7PA008U			
			DE60D	L7PA010U			
150	250	360	DFA1G	L7PA008U			XLCS-PN □ □YS
			DFA6G	L7PA020U			

Appearances of Motor

MDM-DB06DN0H	MDM-DC12DN0H	MDM-DD22DN0H	MDM-DE40DN0H	MDM-DFA6GN0H
				
				
				

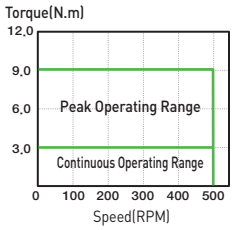
Motor Characteristics

Motor Designation		MDM-DB□ □D□ □H			MDM-DC□ □D□ □H		
		03	06	09	06	12	18
Applicable Drive		L7□A001□	L7□A002□	L7□A004□	L7□A002□	L7□A004□	L7□A008□
Flange Size	mm	Ø135			Ø175		
Rated Output	W	63	126	188	126	251	377
Rated Torque	N-m	3	6	9	6	12	18
Max Torque	N-m	9	18	27	18	36	54
Rated Current	Arms	1.12	1.46	2.63	1.48	2.41	3.0
Max Current	Arms	3.36	4.38	7.89	4.44	7.23	9.0
Rated Speed	rpm	200			200		
Max Speed	rpm	500	500	500	500	500	400
Constant of Torque	N-m/Arms	2.76	4.25	3.57	4.18	5.13	6.12
Inertia	kg-m^2 ×10^{-4}	5.74	8.67	11.5	27.32	38.9	50.48
Rated Power Rate	kW/S	15.68	42.35	70.43	13.18	52.71	118.59
Angular acceleration	rad/s^2	191.2	141.6	127.7	455.03	323.9	280.3
Positioning accuracy	arc-sec	±30					
Positioning repeatability	arc-sec	±1.3					
Axial run-out	mm	0.015					
Radial run-out	mm	0.03					
Allowable Thrust Load	N	1500			3300		
Max. Instantaneous	N-m	40			70		
Encoder Type		20-bit single turn serial encoder (Biss/Absolute					
Weight(Approx.)	kg	6.3	7.2	9.2	8.7	10.6	12.6
Working Environment	Ambient Temp	operating : 0~40[℃] / storage : -20~60[℃]					
	Ambient Humidity	20~80[%] RH(avoid dew-condensation)					
	Atmosphere	Avoid direct sunlight, No corrosive gas, Inflammable gas, Oil mist, or Dust					

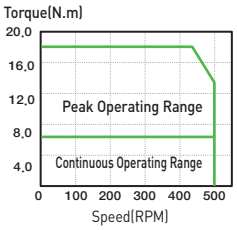
* In case of allowable load inertia ratio, please apply within 30 times of rotator inertia

Speed-Torque Characteristics

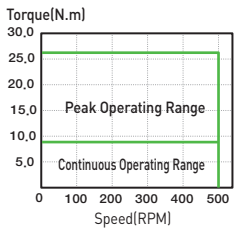
MDM-DB03D



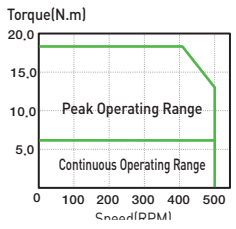
MDM-DB06D



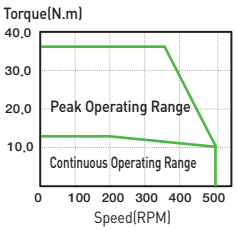
MDM-DB09D



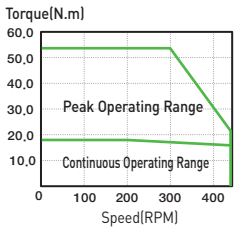
MDM-DC06D



MDM-DC12D



MDM-DC18D

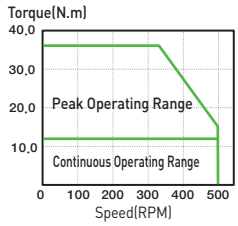


Motor Designation		MDM-DD□ □D□ □H			MDM-DE□ □D□ □H		MDM-DF□ □G□ □H	
		12	22	34	40	60	A1	A6
Applicable Drive		L7□A004□	L7□A008□	L7□A010□	L7□A010□	L7□A020□	L7□A020□	L7□A035□
Flange Size	mm	Ø230			Ø290		Ø360	
Rated Output	W	251	461	712	838	1,257	1,728	2,513
Rated Torque	N-m	12	22	34	40	60	110	160
Max Torque	N-m	36	66	102	120	180	330	480
Rated Current	Arms	2.58	3.33	5.72	5.3	8.33	9.48	14.6
Max Current	Arms	7.74	9.99	17.16	15.9	24.99	28.44	43.8
Rated Speed	rpm	200			200		150	
Max Speed	rpm	500	400	400	300	300	250	250
Constant of Torque	N-m/Arms	4.8	6.81	6.13	7.77	7.42	11.95	11.29
Inertia	kg-m^2 × 10^{-4}	54.14	68.15	82.16	311.55	371.71	1410.2	1763.4
Rated Power Rate	kW/S	26.6	71.02	140.7	51.36	96.68	85.9	145.4
Angular acceleration	rad/s^2	450.9	309.6	241.5	778.35	619.1	1281.13	1101.4
Positioning accuracy	arc-sec	±30						
Positioning repeatability	arc-sec	±1.3						
Axial run-out	mm	0.015						
Radial run-out	mm	0.03						
Allowable Thrust Load	N	4000		1100			15000	
Max. Instantaneous	N-m	93		250			350	
Encoder Type		20-bit single turn serial encoder (Biss/Absolute						
Weight(Approx.)	kg	17.3	19.6	21.9	28.2	35	54	70.3
Working Environment	Ambient Temp	operating : 0~40[℃] / storage : -20~60[℃]						
	Ambient Humidity	20~80[%] RH(avoid dew-condenation)						
	Atmosphere	Avoid direct sunlight, No corrosive gas, Inflammable gas, Oil mist, or Dust						

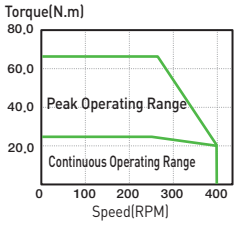
* In case of allowable load inertia ratio, please apply within 30 times of rotator inertia

Speed-Torque Characteristics

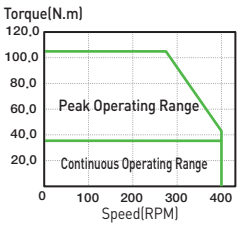
MDM-DD12D



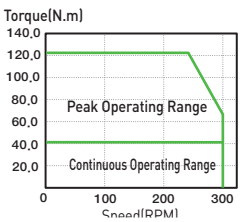
MDM-DD22D



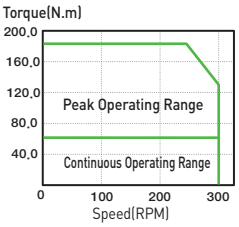
MDM-DD34D



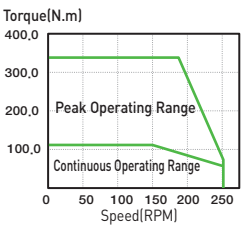
MDM-DE40D



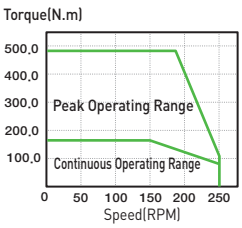
MDM-DE60D



MDM-DFA1G

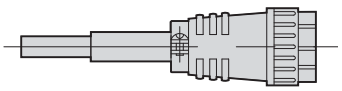


MDM-DFA6G



External Dimensions

MDM-DB03D, MDM-DB06D, MDM-DB09D

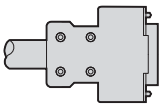


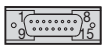


NJC-24-4-PM

Signal		Line color	Pin No.
LEAD WIRE	U	Red	A
	V	White	B
	W	Black	C
FG		Green	D

POWER CONNECTOR

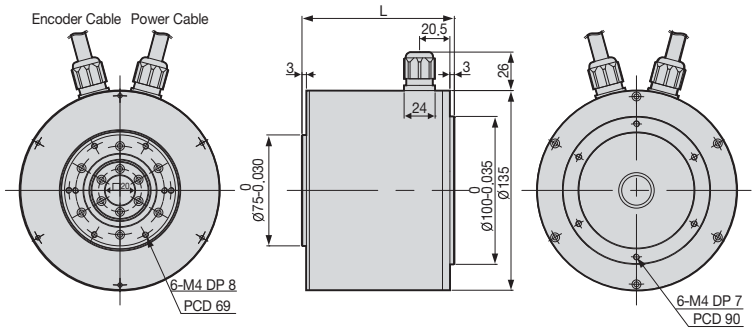




D- Sub Connector (15pin)

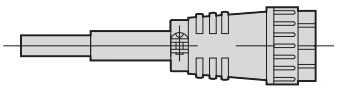
D.D SERVO ENCODER CABLE			
NO	Encoder Signal	NO	Encoder Signal
1	MA	9	+5V
2	SLO	10	-
3	-	11	-
4	OV	12	-
5	SHIELD	13	-
6	$\overline{MA}$	14	-
7	$\overline{SLO}$	15	-
8	-		

ENCODER CONNECTOR



Model Series	External Dimensions(mm)	Weight(kg)
	L	
MDM-DB03D	78	6.3
MDM-DB06D	100	7.2
MDM-DB09D	124	9.2

MDM-DC06D, MDM-DC12D, MDM-DC18D

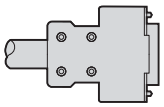


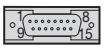


NJC-24-4-PM

Signal		Line color	Pin No.
LEAD WIRE	U	Red	A
	V	White	B
	W	Black	C
FG		Green	D

POWER CONNECTOR

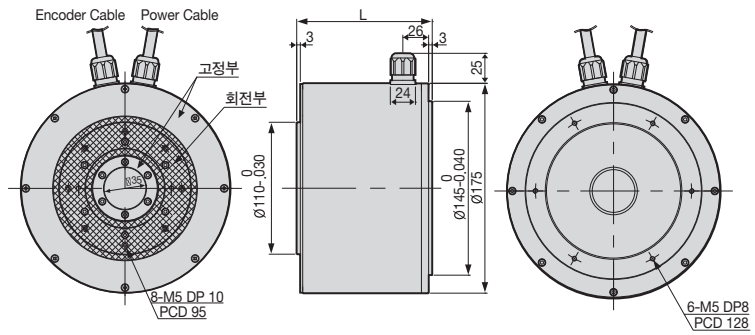




D- Sub Connector (15pin)

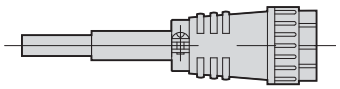
D.D SERVO ENCODER CABLE			
NO	Encoder Signal	NO	Encoder Signal
1	MA	9	+5V
2	SLO	10	-
3	-	11	-
4	OV	12	-
5	SHIELD	13	-
6	$\overline{MA}$	14	-
7	$\overline{SLO}$	15	-
8	-		

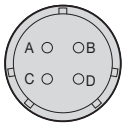
ENCODER CONNECTOR



Model Series	External Dimensions(mm)	Weight(kg)
	L	
MDM-DC06D	77	8.7
MDM-DC12D	95	10.6
MDM-DC18D	113	12.6

MDM-DD12D, MDM-DD22D, MDM-DD34D

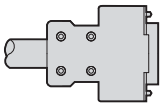


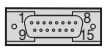


NJC-24-4-PM

Signal		Line color	Pin No.
LEAD WIRE	U	Red	A
	V	White	B
	W	Black	C
FG		Green	D

POWER CONNECTOR

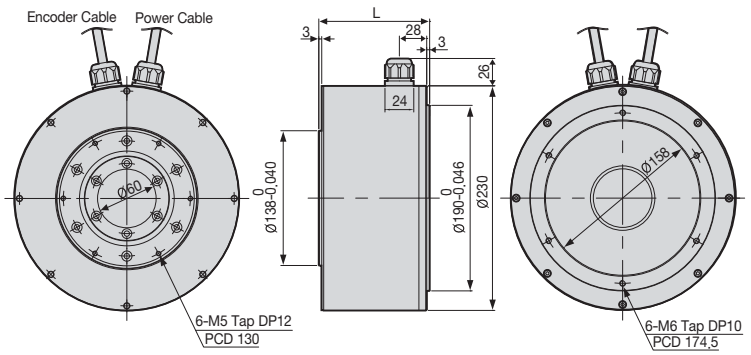




D- Sub Connector (15pin)

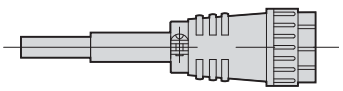
D.D SERVO ENCODER CABLE			
NO	Encoder Signal	NO	Encoder Signal
1	MA	9	+5V
2	SLO	10	-
3	-	11	-
4	0V	12	-
5	SHIELD	13	-
6	$\overline{MA}$	14	-
7	$\overline{SLO}$	15	-
8	-		

ENCODER CONNECTOR



Model Series	External Dimensions(mm)	Weight(kg)
	L	
MDM-DD12D	82.5	17.3
MDM-DD22D	100.5	19.6
MDM-DD34D	118.5	21.9

MDM-DE40D, MDM-DE60D

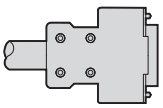


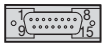


NJC-24-4-PM

내용		Line color	Pin No.
LEAD WIRE	U	Red	A
	V	White	B
	W	Black	C
FG		Green	D

POWER CONNECTOR

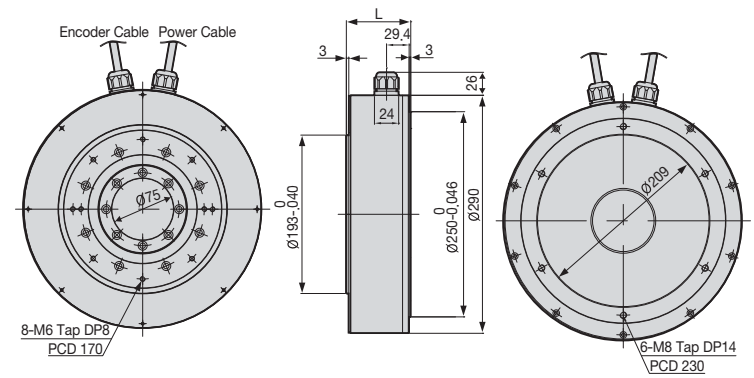




D- Sub Connector (15pin)

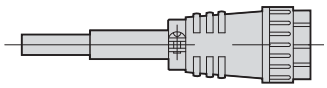
D.D SERVO ENCODER CABLE			
NO	Encoder Signal	NO	Encoder Signal
1	MA	9	+5V
2	SLO	10	-
3	-	11	-
4	0V	12	-
5	SHIELD	13	-
6	$\overline{MA}$	14	-
7	$\overline{SLO}$	15	-
8	-		

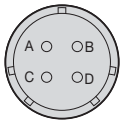
ENCODER CONNECTOR



Model Series	External Dimensions(mm)	Weight(kg)
	L	
MDM-DE40D	95.4	28.2
MDM-DE60D	113.4	35

MDM-DFA1G, MDM-DFA6G

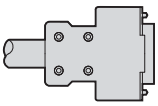


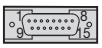


제작사: Nanaboshi Electronic
NJC-24-4-PM

Signal		Line color	Pin No.
LEAD WIRE	U	Red	A
	V	White	B
	W	Black	C
FG		Green	D

POWER CONNECTOR

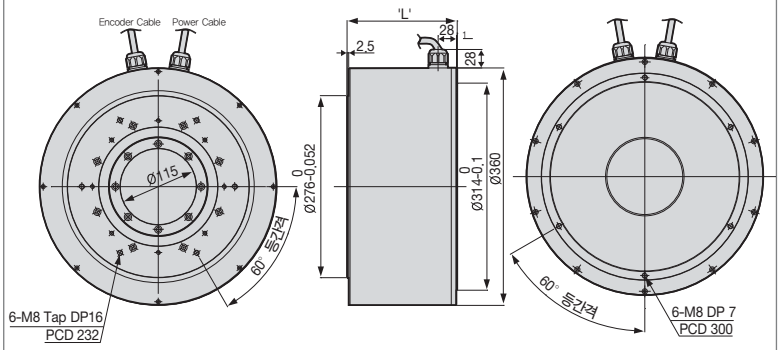




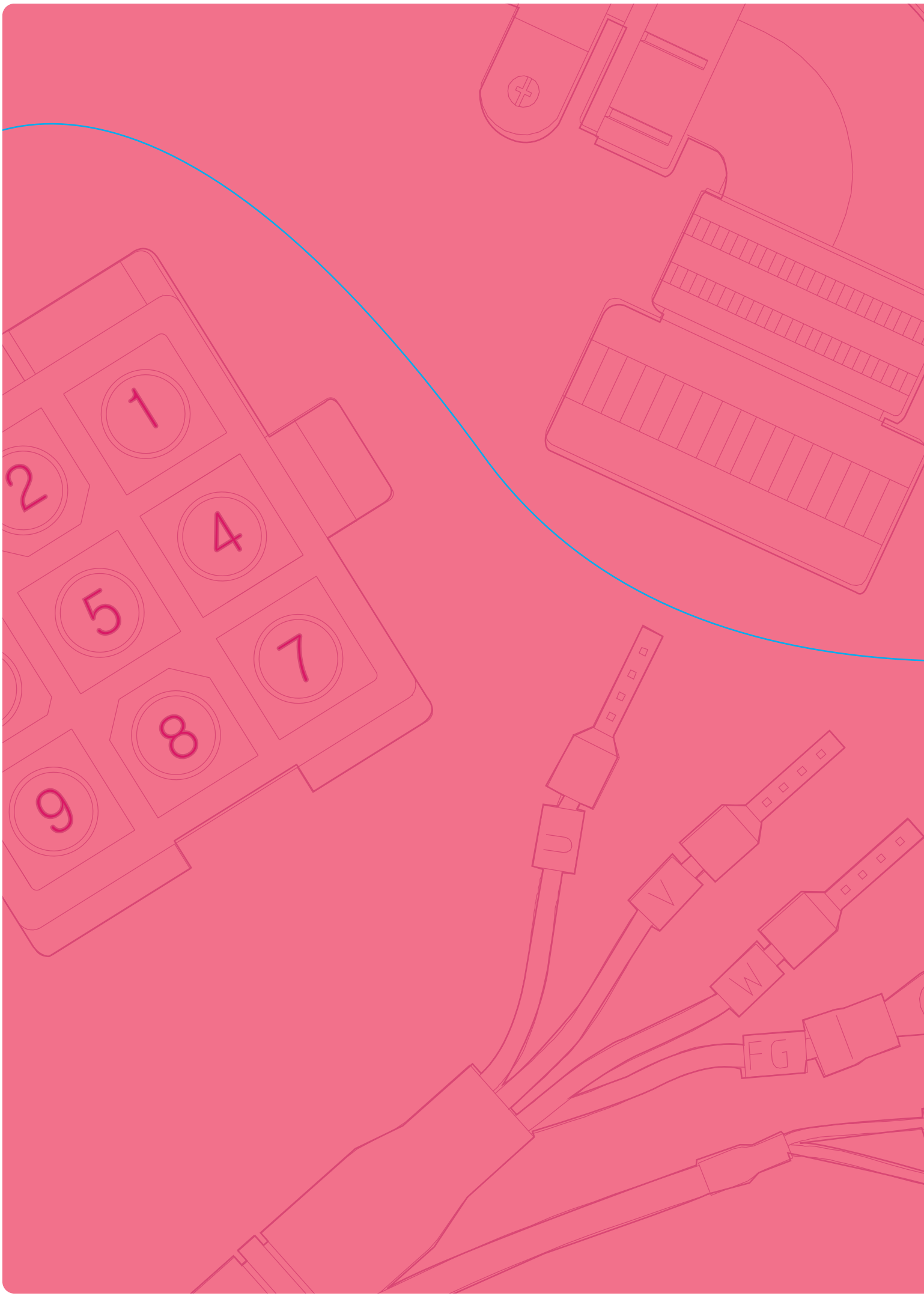
D- Sub Connector (15pin)

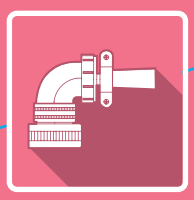
D.D SERVO ENCODER CABLE			
NO	Encoder Signal	NO	Encoder Signal
1	MA	9	+5V
2	SLO	10	-
3	-	11	-
4	OV	12	-
5	SHIELD	13	-
6	$\overline{MA}$	14	-
7	$\overline{SLO}$	15	-
8	-		

ENCODER CONNECTOR



Model Series	External Dimensions(mm)	Weight(kg)
	L	
MDM-DFA1G	131	54
MDM-DFA6G	167	70.3


1
2
4
5
7
8
9
U
V
W
FG

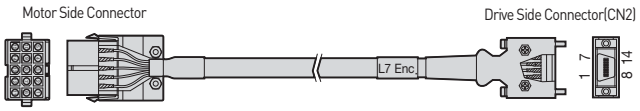


Options and Accessories

Contents

Signal cable 102
Power cable 106
DD Motor Signal cable 113
Other options [Signal cable] 114
Other options [Connector] 115
200V Braking Resistor 116
400V Braking Resistor 117

Signal Cable [Incremental]

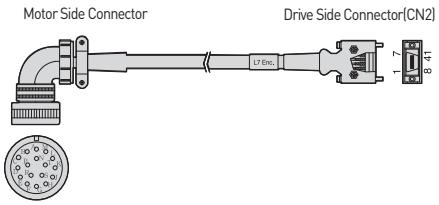
Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	Parallel Encoder Cable (Small Capacity)	XLCS-E□□□AS	XDL-L7SA□□□A L7NHA□□□U L7PA□□□U	All Models of XML- SA SB SC HB SERIES	

PIN No.	Encoder Signal	PIN No.	Encoder Signal	PIN No.	Encoder Signal	PIN No.	Encoder Signal
1	A	9	V	1	W	8	$\overline{Z}$
2	$\overline{A}$	10	$\overline{V}$	2	$\overline{W}$	9	Z
3	B	11	W	3	V	10	$\overline{B}$
4	$\overline{B}$	12	$\overline{W}$	4	$\overline{V}$	11	B
5	Z	13	+5V	5	U	12	$\overline{A}$
6	$\overline{Z}$	14	0V	6	$\overline{U}$	13	A
7	U	15	SHIELD	7	0V	14	+5V
8	$\overline{U}$			PLATE		SHIELD	
[Motor Side Connector]				[Driver Side Connector]			

1. Motor Side Connector
- Cap Spec.(15 Position) : 172163-1(AMP)
- Socket Spec. : 170361-1(AMP)

2. Driver Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

3. Cable Spec. : 7P×0.2SQ or 7P×AWG24

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	Parallel Encoder Cable (Middle Capacity)	XLCS-E□□□BS	XDL-L7SA□□□A L7NHA□□□U L7PA□□□U	All Models of XML- SE/SEP SF/SFP SG/SGP LF LG HE SERIES	

PIN No.	Encoder Signal	PIN No.	Encoder Signal	PIN No.	Encoder Signal	PIN No.	Encoder Signal
A	A	M	V	1	W	8	$\overline{Z}$
B	$\overline{A}$	N	$\overline{V}$	2	$\overline{W}$	9	Z
C	B	P	W	3	V	10	$\overline{B}$
D	$\overline{B}$	R	$\overline{W}$	4	$\overline{V}$	11	B
E	Z	H	+5V	5	U	12	$\overline{A}$
F	$\overline{Z}$	G	0V	6	$\overline{U}$	13	A
K	U	J	SHIELD	7	0V	14	+5V
L	$\overline{U}$			PLATE		SHIELD	
[Motor Side Connector]				[Driver Side Connector]			

1. Motor Side Connector(MS : Military Standard)
- Plug Spec. : MS3108B20-29S

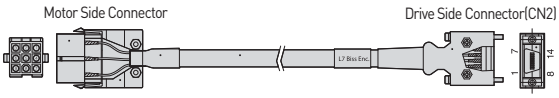
2. Drive Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

3. Cable Spec. : 7P×0.2SQ or 7P×AWG24

Note1] □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

Cable Length(m)	3	5	10	20
General Cable(N)	N03	N05	N10	N20
Robotic Cable(F)	F03	F05	F10	F20

Signal Cable [Serial]

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	S Series Motor S-turn Encoder Cable (Small Capacity	XLCS-E□□□CS	XDL-L7S□□□B L7NA□□□B L7NH□□□□U L7PA□□□U	All Models of XML-SA SB SC SERIES	

[Motor Side Connector]

PIN No.	Encoder Signal
1	MA
2	MA
3	SLO
4	SLO
5	-
6	-
7	+5V
8	0V
9	SHIELD

[Driver Side Connector]

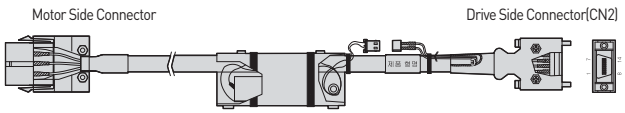
PIN No.	Encoder Signal
1	-
2	-
3	MA
4	$\overline{MA}$
5	SLO
6	$\overline{SLO}$
7	0V
PLATE	

PIN No.	Encoder Signal
8	-
9	-
10	-
11	-
12	-
13	-
14	+5V
SHIELD	

1. Motor Side Connector
- Cap Spec.(9 Position) : 172161-1(AMP)
- Socket Spec. : 170361-1(AMP)

2. Drive Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M)or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M)or SM-14J(Suntone)

3. Cable Spec. : 3P×0.2SQ or 3P×24AWG

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	S Series Motor M-turn Encoder Cable (Small Capacity	XLCS-E□□□CS1	XDL-L7S□□□B L7NA□□□B L7NH□□□□U L7PA□□□U	All Models of XML-SA SB SC SERIES	

AMP 172161-1 CAP (9Circuits)

PIN No.	Encoder Signal
1	MA
2	$\overline{MA}$
3	SL
4	$\overline{SL}$
5	VOD_B
6	GND_B
7	+5V
8	0V
9	SHELD

[Motor Side Connector]

PIN No.	Encoder Signal
1	-
2	-
3	MA
4	$\overline{MA}$
5	SLO
6	$\overline{SLO}$
7	0V
PLATE	

[Driver Side Connector]

PIN No.	Encoder Signal
8	-
9	-
10	-
11	-
12	-
13	-
14	+5V
SHIELD	

PIN No.	Encoder Signal
1	BATTERY(VDD_B)
2	BATTERY 0V(GND_B)

[Battery Connector]

1. Motor Side Connector
- CAP Spec.(9 Position) : 172161-1(AMP)
- Socket Spec. : 170361-1(AMP)

2. Drive Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

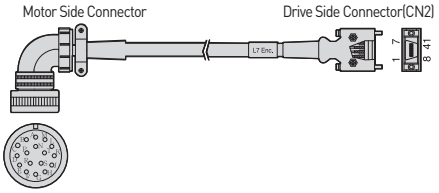
3. Cable Spec. : 4P ×0.2SQ or 4P ×24AWG

4. Cable Spec. : 3P×0.2SQ or 3P×24AWG

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

Cable Length(m)	3	5	10	20
General Cable(N)	N03	N05	N10	N20
Robotic Cable(F)	F03	F05	F10	F20

Signal Cable [Serial]

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	S/F Series Motor S-turn Encoder Cable (Middle Capacity)	XLCS-E□□□DS	XDL-L7S□□□B L7NA□□□B L7NH□□□□U L7PA□□□U	All Models of XML-SE FE/SEP/FEP SF/FF SFP/FFP SG/FG SGP/FGP LF LG SERIES	

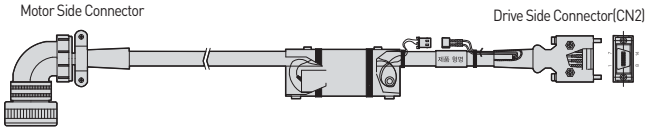
PIN No.	Encoder Signal	PIN No.	Encoder Signal	PIN No.	Encoder Signal	PIN No.	Encoder Signal
A	MA	M	-	1	-	8	-
B	$\overline{MA}$	N	-	2	$\overline{-}$	9	-
C	SLO	P	-	3	MA	10	-
D	$\overline{SLO}$	R	-	4	$\overline{MA}$	11	-
E	-	H	+5V	5	SLO	12	-
F	-	G	0V	6	$\overline{SLO}$	13	-
K	-	J	SHIELD	7	0V	14	+5V
L	-			PLATE		SHIELD	

(Motor Side Connector) (Drive Side Connector)

1. Motor Side Connector(MS : Military Standard)
- Plug Spec. : MS3108B20-29S

2. Drive Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

3. Cable Spec. : 3P×0.2SQ or 3P×24AWG

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	S/F Series Motor M-turn Encoder Cable (Middle Capacity)	XLCS-E□□□DS1	XDL-L7S□□□B L7NA□□□B L7NH□□□□U L7PA□□□U	All Models of XML-SE/FE SEP/FEP SF/FF SFP/FFP SG/FG/ SGP/FGP LF LG SERIES	



PIN No.	Encoder Signal	PIN No.	Encoder Signal
A	MA	M	-
B	$\overline{MA}$	N	-
C	SLO	P	-
D	$\overline{SLO}$	R	-
E	VDD_B	H	+5V
F	GND_B	G	0V
G	-	J	SHELD
L	-		

(Motor Side Connector)



PIN No.	Encoder Signal	PIN No.	Encoder Signal
1	-	8	-
2	-	9	-
3	MA	10	-
4	$\overline{MA}$	11	-
5	SLO	12	-
6	$\overline{SLO}$	13	-
7	0V	14	+5V
PLATE		SHIELD	

(Drive Side Connector)



PIN No.	Encoder Signal
1	BATTERY (VDD_B)
2	BATTERY 0V (GND_B)

(Driver Side Connector)

1. Motor Side Connector(MS : Military Standard)
- Plug Spec. : MS3108B20-29S

2. Drive Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

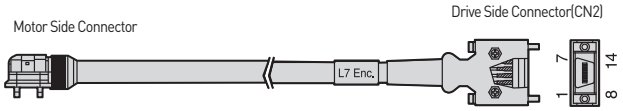
3. Cable Spec. : 4P×0.2SQ or 4P×24AWG

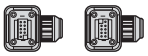
4. Battery Connector Spec. : 5267-02A(MOLEX)

Note1] □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

Cable Length(m)	3	5	10	20
General Cable(N)	N03	N05	N10	N20
Robotic Cable(F)	F03	F05	F10	F20

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	F Series Motor S-turn Encoder Cable (Small Capacity)	XLCS-E□□□ES-□	XDL-L7S□□□B L7NA□□□B L7NH□□□□U L7PA□□□U	All Models of XML-FAL FB/FBL FC/FCL SERIES	





Tyco Connector (7Circuits)

PIN No.	Encoder Signal
1	MA
2	SLO
3	-
4	0V
5	SHIELD
6	$\overline{MA}$
7	$\overline{SLO}$
8	-
9	+5V

(Motor Side Connector)



PIN No.	Encoder Signal	PIN No.	Encoder Signal
1	-	8	-
2	-	9	-
3	MA	10	-
4	$\overline{MA}$	11	-
5	SLO	12	-
6	$\overline{SLO}$	13	-
7	0V	14	+5V
PLATE		SHIELD	

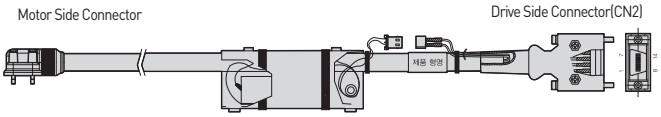
(Drive Side Connector)

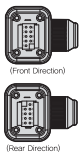
1. Motor Side Connector
- Cap Spec. : 2201825-1(Tyco)
- Socket Spec. : 2174065-4(Tyco)

2. Drive Side Connector(CN2)
- Case Spec. : 10314-52A0-008(3M) or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

3. Cable Spec. : 3P×0.2SQ or 3P×24AWG

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Signal	F Series Motor M-turn Encoder Cable (Small Capacity)	XLCS-E□□□ES1-□	XDL-L7S□□□B L7NA□□□B L7NH□□□□U L7PA□□□U	All Models of XML-FAL FB/FBL FC/FCL SERIES	





PIN No.	Encoder Signal
1	MA
2	SLO
3	GND_B
4	0V
5	SHELD
6	$\overline{MA}$
7	$\overline{SLO}$
8	VOD_B
9	+5V

(Motor Side Connector)



PIN No.	Encoder Signal	PIN No.	Encoder Signal
1	-	8	-
2	-	9	-
3	MA	10	-
4	$\overline{MA}$	11	-
5	SLO	12	-
6	$\overline{SLO}$	13	-
7	0V	14	+5V
PLATE		SHIELD	

(Driver Side Connector)



PIN No.	Encoder Signal
1	BATTERY (VDD_B)
2	BATTERY 0V (GND_B)

(Battery Connector)

1. Motor Side Connector
- Cap Spec. : 2201825-1(Tyco)
- Socket Spec. : 2174065-4(Tyco)

2. Drive Side Connector(CN2)
- Cap Spec. : 10314-52A0-008(3M) or SM-14J(Suntone)
- Connector Spec. : 10114-3000VE(3M) or SM-14J(Suntone)

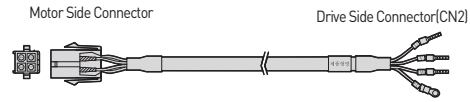
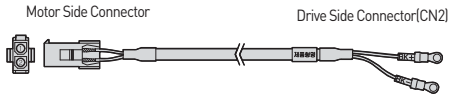
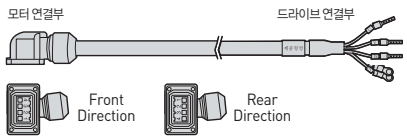
3. Cable Spec. : 4P×0.2SQ or 4P×24AWG

4. Battery Connector Spec. : 5267-02A(MOLEX)

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.
Note2) In case of □ marked product, the connector can draw in a direction of Front(load) / Rear(half load).(Front Type : No mark, Rear Type : -R)

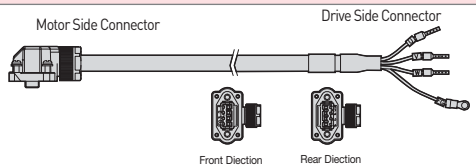
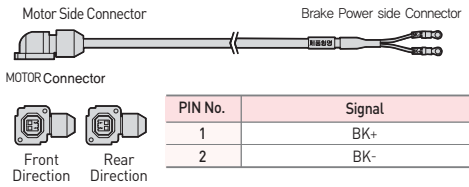
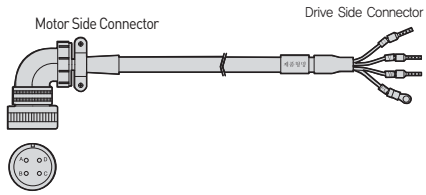
Cable Length(m)	3	5	10	20
General Cable(N)	N03	N05	N10	N20
Robotic Cable(F)	F03	F05	F10	F20

Power Cable [200V]

Type	Product Type	Model Name (Note1)	Applicable Drive	Applicable Motor	Specifications
For Power	S Series Power Cable (Small Capacity)	XLCS-P □□□GS	XDL- L7SA□□□A L7NHA□□□U L7PA□□□U	All Models of XML- SA SB SC HB SERIES	 PIN No. / Signal 1 / U 2 / V 3 / W 4 / Ground **1. Motor Side Connector** • Cap Spec.(4 Position) : 172159-1(AMP) • Socket Spec. : 170362-1(AMP) **2. Drive Side Connector(U, V, W, FG)** • U, V, W Pin Spec. : 1512 • FG Pin Spec. : 1.54x4(Ring Terminal) **3. Cable Spec. : 4C×0.75SQ or 4C×18AWG**
For Power	S Series Brake Cable (Small Capacity)	XLCS-P □□□KB	XDL- L7SA□□□A L7NHA□□□U L7PA□□□U	All Models of XML- SA SB SC HB SERIES	 PIN No. / Signal 1 / BK+ 2 / BK- **1. Motor Side Connector** • Cap Spec.(2 Position) : 172157-1(AMP) • Socket Spec. : 170362-1(AMP) **2. Drive Side Connector(U, V, W, FG)** • Connecting terminal Spec. : 1.5x3(Ring Terminal) **3. Cable Spec. : 2C×0.75SQ or 2C×18AWG**
For Power	F Series Power Cable (Small Capacity)	XLCS-P □□□FS-□	XDL- L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of XML- FB FC SERIES	 PIN No. / Signal 1 / W 2 / V 3 / U 4 / Ground **1. Motor Side Connector** • Plug Spec. : KN5FT04SJ1(JAE) • Socket Spec. : ST-KN-S-C1B-3500(JAE) **2. Drive Side Connector(U, V, W, FG)** • U, V, W Pin Spec. : 1512 • FG Pin Spec. : 1.5x4(Ring Terminal) **3. Cable Spec. : 4C×0.75SQ or 4C×18AWG**

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.
Note2) In case of □ marked product, the connector can draw in a direction of Front(load) / Rear(half load).(Front Type : No mark, Rear Type : -R)

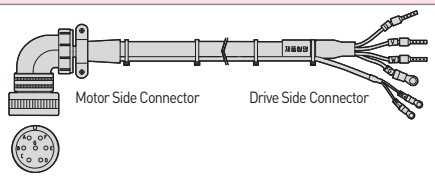
Cable Length(m)	3	5	10	20
General Cable(N)	F03	F05	F10	F20
Robotic Cable(F)	N03	N05	N10	N20

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Power	L Series Power Cable (Small Capacity)	XLCS-P □□□LS-□	XDL- L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of XML- FAL FBL FCL SERIES	 PIN No. / Signal A – U B – V C – W D – Ground **1. Motor Side Connector** • Plug Spec. : SM-JN8FT04(Suntone) • Socket Spec. : SMS-201(Suntone) **2. Drive Side Connector (U,V,W,FG)** • U, V, W Pin Spec. : 1512(Ferrule) • FG Pin Spec. : 1.5x4 (Ring Terminal) **3. Cable Spec. : 4C×0.75SQ or 4C×18AWG** **4. In case of FAL products,Please install Power Cable first before connecting Encoder Cable**
For Power	Brake Cable for Flat Motor (Small Capacity)	XLCS-B □□□QS-□	XDL- L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of XML- FAL FB/FBL FC/FCL SERIES	 PIN No. / Signal 1 – BK+ 2 – BK- **1. Motor Side Connector** • Plug Spec. : KN5FT02SJ1 • Socket Spec. : ST-KN-S-C1B-3500 **2. Drive Side Connector (U,V,W,FG)** • Connecting terminal Spec. : 1.5x3(Ring Terminal) **3. Cable Spec. : 2C×0.75SQ or 2C×18AWG**
For Power	Power Cable (Middle Capacity)	XLCS-P □□□HS	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of XML- SE FE HE SERIES	 PIN No. / Signal A – U B – V C – W D – Ground **1. Motor Side Connector** • Plug Spec. : MS3108B20-4S(MS) **2. Drive Side Connector (U,V,W,FG)** • U, V, W Pin Spec. : 2512 • FG Pin Spec. : 2.5x4(Ring Terminal) **3. Cable Spec. : 4C×2.5SQ or 4C×14AWG**

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.
Note2) In case of □ marked product, the connector can draw in a direction of Front(load) / Rear(half load).(Front Type : No mark, Rear Type : -R)

Cable Length(m)	3	5	10	20
General Cable(N)	F03	F05	F10	F20
Robotic Cable(F)	N03	N05	N10	N20

Power Cable [200V]

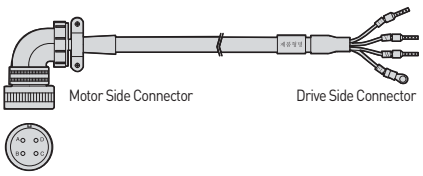
Type	Product Type	Model Name (Note1)	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable (Brake Type)	XLCS-P □□□NB	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of XML- SE FE SERIES	

PIN No.	Signal	PIN No.	Signal
A	U	D	Ground
B	V	E	BK+
C	W	F	BK-

1. Motor Side Connector
- Plug Spec. : MS3108B20-15S(MS)

2. Drive Side Connector
- U, V, W Pin Spec. : 2012
- Cable Spec. : 4Cx2.5SQ or 4Cx41AWG
- FG Pin Spec. : 2.5x4(Ring Terminal

3. Brake Power side Connector
- BK Pin Spec. : 1.5x3(Ring Terminal)
- Cable Spec. : 2Cx07.5SQ or 2Cx18AWG

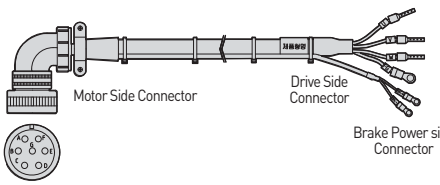
Type	Product Type	Model Name (Note1)	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable (Middle Capacity)	XLCS-P □□□IS	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML- SF30A SF22D/LF35D SF20G/LF30G SF12M/SF20M LF30M/SG22D LG35D/SG20G LG30G/SG12M SG20M/LG30M FF30A/FF22D FF35D/FF20G FF30G/FF12M FF20M/FF30M FG22D/FG35D FG20G/FG30G FG12M/FG20M FG30M	

PIN No.	Signal
1	U
2	V
3	W
4	Ground

1. Motor Side Connector
- Plug Spec. : MS3108B22-22S(MS)

2. Drive Side Connector
- U, V, W Pin Spec. : 2512
- FG Pin Spec. : 2.5x4(Ring Terminal)

3. Cable Spec. : 4C×2.5SQ or 4C14AWG

Type	Product Type	Model Name (Note1)	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable (Brake Type)	XLCS-P □□□PB	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML- SF30A SF22D/LF35D SF20G/LF30G SF12M/SF20M LF30M/FF30A FF22D/FF35D FF20G/FF30G FF12M/FF20M FF30M	

1. Motor Side Connector
- PLUG Spec. : MS3108B24-10S(MS)

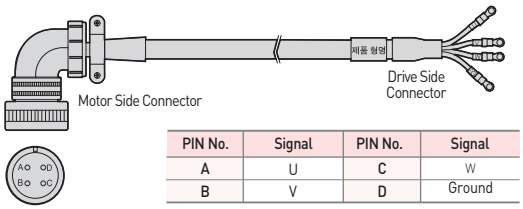
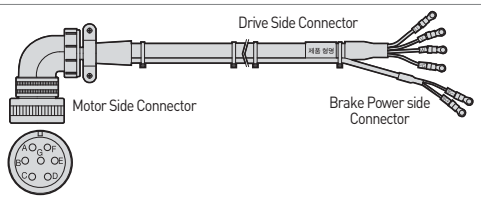
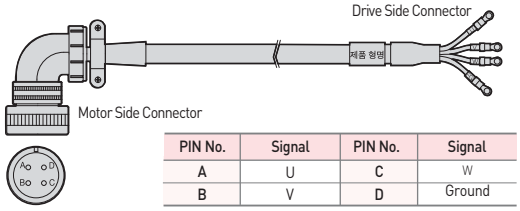
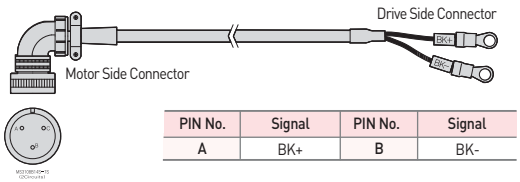
2. Drive Side Connector
- U, V, W Pin Spec. : 2512
- Cable Spec. : 4Cx2.5SQ or 4Cx52AWG
- FG Pin Spec. : 2.5x4(Ring Terminal)

3. Brake Power side Connector
- BK Pin Spec. : 1.5x3(Ring Terminal)
- Cable Spec. : 2Cx075. S or 2Cx18AWG

PIN No.	Signal
A	U
B	V
C	W
D	Ground
E	BK+
F	BK-

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

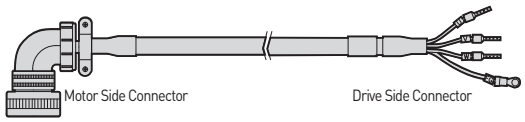
Cable Length(m)	3	5	10	20
General Cable(N)	N03	N05	N10	N20
Robotic Cable(F)	F03	F05	F10	F20

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable (Middle Capacity)	XLCS-P □□□JS	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML- SF50A SF55D/SF75D SF44G/SF60G SF44M/SG55D SG75D/SG44G SG60G/SG44M FF50A/FF55D FF75D/FF44G FF60G/FF44M FG55D/FG75D FG44G/FG60G FG44M	 PIN No. / Signal / PIN No. / Signal A / U / C / W B / V / D / Ground **1. Motor Side Connector** **3. Cable Spec:** 4Cx6SQ or 4Cx10AWG • Plug Spec. : MS3108B22-22S(MS) **2. Drive Side Connector** • Connecting terminal Spec. : 6x5(Ring Terminal)
For Power	Power Cable (Brake Type)	XLCS-P □□□LB	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML- SF50A SF55D/SF75D SF44G/SF60G SF44M/FF50A FF50D/FF75D FF44G/FF60G FF40M	 **1. Motor Side Connector** • Plug Spec. : MS3108A24-10S(MS) **2. Drive Side Connector** • Connecting terminal Spec. : 6x5(Ring Terminal • 4Cx6SQ or 4Cx10AWG **3. Brake Power side Connector** • Connecting terminal Spec. : 1.25x3(Ring Terminal) • Cable Spec. : 2Cx0.75SQ or 2Cx8AWG
For Power	Power Cable (Middle Capacity)	XLCS-P □□□MS	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML- SG60M SF75G/FF75G	 PIN No. / Signal / PIN No. / Signal A / U / C / W B / V / D / Ground **1. Motor Side Connector** **3. Cable Spec:** 4Cx10SQ or 4Cx8AWG • Plug Spec. : MS3108B32-17S(MS) **2. Drive Side Connector** • Connecting terminal Spec. : 10x8(Ring Terminal)
For Power	Brake Cable	XLCS-P □□□SB	XDL- L7SA□□□A L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of XML- SG LG FG SERIES	 PIN No. / Signal / PIN No. / Signal A / BK+ / B / BK- **1. Motor Side Connector** **3. Cable Spec:** 2Cx0.75SQ or 2Cx19AWG • Plug Spec. : MS3108B 14S-7S(MS) **2. Drive Side Connector** • Connecting terminal Spec. : 1.5x3(Ring Terminal)

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

Cable Length(m)	3	5	10	20
General Cable(N)	N03	N05	N10	N20
Robotic Cable(F)	F03	F05	F10	F20

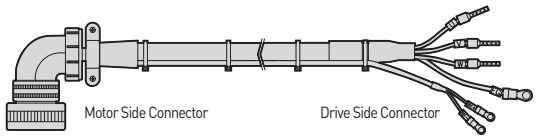
Power Cable [400V]

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable	XLCS-P □□□HS	XDL- L7SB□□□B L7NHB□□□U	All Models of XML- SEP FEP SERIES	

PIN No.	Signal	PIN No.	Signal
A	U	C	W
B	V	D	Ground

1. Motor Side Connector **3. Cable Spec:** 4Cx1.5SQ or 4Cx15AWG
- Plug Spec. : MS3108A 20-4S(MS)

2. Drive Side Connector(U,V,W,FG)
- U, V, W Pin Spec. : 1512(Ferrule)
- FG Pin Spec. : 1.5x4(Ring Terminal)

For Power	Power Cable (Brake Type)	XLCS-P □□□NB	XDL- L7SB□□□B L7NHB□□□U	All Models of XML- SEP FEP SERIES	

PIN No.	Signal
A	U
B	V
C	W
D	Ground
E	BK+
F	BK-

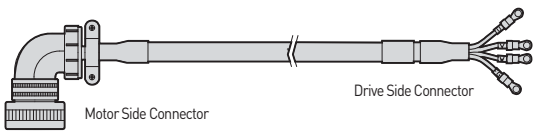
1. Motor Side Connector
- Plug Spec. : MS3108A 20-15S(MS)

2. Drive Side Connector (U,V,W,FG)
- U, V, W Pin Spec. : 1512(Ferrule)
- FG Pin Spec. : 1.5 x 4(Ring Terminal)

3. Power Cable Spec. : 4Cx1.5SQ or 4Cx15AWG

4. Brake Power side Connector
- Connecting terminal Spec. : 1.5 x 3(Ring Terminal)

5.Brake Cable Spec. : 2Cx0.75SQ or 2Cx19AWG

For Power	Power Cable	XLCS-P □□□IS	XDL- L7SB□□□B L7NHB□□□U	XML- [S/F]FP30A [S/F]FP22D/ [S/F]FP35D/ [S/F]FP20G/ FFP30G/ [S/F]FP12M/ [S/F]FP20M/ [S/F]GP22D/ [S/F]GP35D/ [S/F]GP20G/ FGP30G/ [S/F]GP12M/ [S/F]GP20M	

PIN No.	Signal
A	U
B	V
C	W
D	Ground

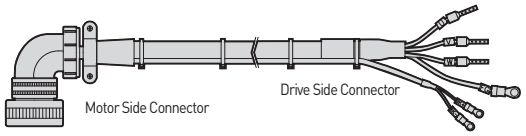
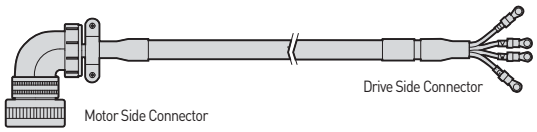
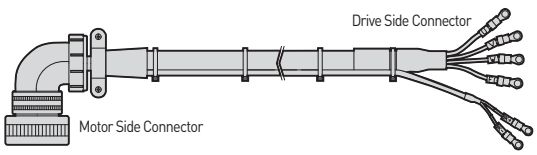
1. Motor Side Connector
- Plug Spec. : MS3108A 22-22S(MS)

2. Drive Side Connector (U,V,W,FG)
- U, V, W Pin Spec : 2512(Ferrule)
- FG Pin Spec. : 2.5x4 (Ring Terminal)

3. Cable Spec. : 4Cx2.5SQ or 4Cx14AWG

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.
Note2) In case of 400V products, you can use Robotic Cable only.

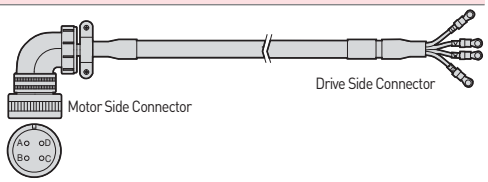
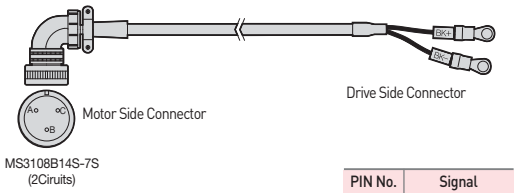
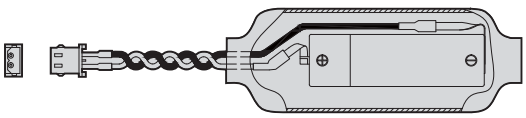
Cable Length(m)	3	5	10	20
Robotic Cable(F)	F03	F05	F10	F20

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable (Brake Type)	XLCS-P □□□PB	XDL- L7SB□□□B L7NHB□□□U	XML- [S/F]FP30A/ [S/F]FP22D/ [S/F]FP35D/ [S/F]FP20G/ FFP30G/ [S/F]FP12M/ [S/F]FP20M/ [S/F]GP22D/ [S/F]GP35D/ [S/F]GP20G/ FGP30G/ [S/F]GP12M/ [S/F]GP20M	  PIN No. / Signal: A U; B V; C W; D Ground; E BK+; F BK- **1. Motor Side Connector** • Plug Spec. : MS3108A 24-10S(MS) **2. Drive Side Connector** • U, V, W Pin Spec. : 2512(Ferrule) • FG Pin Spec. : 2.5 x 4(Ring Terminal) **3. Power Cable Spec. : 4Cx2.5SQ or 4Cx14AWG** **4. Brake Power side Connector** • Connecting terminal Spec. : 1.5 x 3(Ring Terminal) **5.Brake Cable Spec. : 2Cx0.75SQ or 2Cx19AWG**
For Power	Power Cable (Middle Capacity)	XLCS-P □□□JS	XDL- L7SB□□□B L7NHB□□□U	XML- [S/F]FP50A/ [S/F]FP55D/ [S/F]FP75D/ SFP30G/ [S/F]FP44G/ [S/F]FP60G/ [S/F]FP30M/ [S/F]FP44M/ [S/F]GP55D [S/F]GP75D/ SGP30G/ [S/F]GP44G/ [S/F]GP60G/ [S/F]GP30M/ [S/F]GP44M	  PIN No. / Signal: A U; B V; C W; D Ground **1. Motor Side Connector** • Plug Spec. : MS3108A 22-22S(MS) **2. Drive Side Connector (U,V,W,FG)** • U, V, W Pin Spec. : 4.0x 5(Ring Terminal) **3. Cable Spec. : 4Cx4.0SQ or 4Cx11AWG**
For Power	Power Cable (Brake Type)	XLCS-P □□□LB	XDL- L7SB□□□B L7NHB□□□U	XML- [S/F]FP50A/ [S/F]FP55D/ [S/F]FP75D/ SFP30G/ [S/F]FP44G/ [S/F]FP60G/ [S/F]FP30M/ [S/F]FP44M/	  PIN 번호 / 신호: A U; B V; C W; D Ground; E BK+; F BK- **1. Motor Side Connector** • Plug Spec. : MS3108A 24-10S(MS) **2. Drive Side Connector** • U, V, W Pin Spec. : 4.0X5(Ring Terminal) **3. Power Cable Spec. :** **4Cx4.0SQ or 4Cx11AWG** **4. Brake Power side Connector** • Connecting terminal Spec. : 1.5 x 3(Ring Terminal) **5.Brake Cable Spec. : 2Cx0.75SQ or 2Cx19AWG**

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.
Note2) In case of 400V products, you can use Robotic Cable only.

Cable Length(m)	3	5	10	20
Robotic Cable(F)	F03	F05	F10	F20

Power Cable [400V]

Type	Product Type	Model Name [Note1]	Applicable Drive	Applicable Motor	Specifications
For Power	Power Cable (Middle Capacity)	XLCS-P □□□ MS	XDL-L7SB□□□B L7NHB□□□U	XML-[S/F]FP75G/ [S/F]GP110D/ [S/F]GP85G/ [S/F]GP110G/ [S/FGP150G/ [S/F]GP60M/	
For Power	Brake Cable (same with 200V)	XLCS-P □□□ SB	XDL-L7SB□□□B L7NHB□□□U	All Models of XML-SGP FGP SERIES	
Battery For Encoder	Battery Ass'y	XLCS-BATT36	All L7 Drives for M-turn	All Model of XML-F Series	

PIN No.	Signal	PIN No.	Signal
A	U	C	W
B	V	D	Ground

1. Motor Side Connector
- Plug Spec. : MS3108A 32-17S(MS)

2. Drive Side Connector(U,V,W,FG)
- U, V, W Pin Spec. : 10x5(Ring Terminal)

3. Cable Spec: 4Cx10SQ or 4Cx7AWG

PIN No.	Signal
1	BK+
2	BK-

1. Motor Side Connector
- Plug Spec. : MS3108B 14-7S(MS)

2. Brake Power side Connector
- Connecting terminal Spec. : 1.5x3(Ring Terminal)

3. Cable Spec. : 4Cx2.5SQ or 4Cx14AWG

PIN No.	Signal	Color
1	BK+	Red
2	BK-	Black

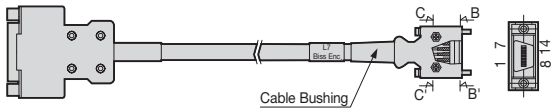
1. PLUG Spec. : 5264-02 (Molex)
2. PLUG Pin Spec. : 5263PBT (Molex)
3. Battery Spec. : ER6V/3.6V, 2000mAh (TOSHIBA)

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.
Note2) In case of 400V products, you can use Robotic Cable only.

Cable Length(m)	3	5	10	20
Robotic Cable(F)	F03	F05	F10	F20

DD Motor Signal Cable

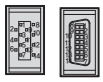
Type	Product Type	Model Name[Note1]	Applicable Drive	Specifications	Specifications
For Signal	L7 Encoder Cable	XLCS-E □□□ZS	XDL-L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	All Models of DD motor	



D-sub(15pin/female)

D.D SERVO ENCODER CABLE			
NO	Encoder Signal	NO	Encoder Signal
1	MA	9	+5V
2	SLO	10	-
3	GND_B	11	-
4	0V	12	-
5	SHELD	13	-
6	$\overline{MA}$	14	-
7	$\overline{SLO}$	15	-
8	+5V		-

(ENCODER CONNECTOR)
(Motor Connector)



Biss Serial Encoder
Encoder Cable Connector

PIN No.	Encoder Signal	PIN No.	Encoder Signal
1	-	8	-
2	-	9	-
3	MA	10	-
4	$\overline{MA}$	11	-
5	SLO	12	-
6	$\overline{SLO}$	13	-
7	0V	14	+5V
PLATE		SHIELD	

(Driver Connector)

1. Motor Side Connector
- Connector(D-SUB) : DA-15PF-N(Female connector
- Connector CASE(D-SUB) : SK-15H-1A

2. Drive Side Connector
- CASE Spec. : 10314-52A0-008(3M)
- Connector Spec. : 10114-3000VE(3M)

3. Cable Spec. : 3Px0.2SQ

DD Motor Power Cable

Type	Product Type	Model Name[Note1]	Applicable Drive	Specifications	Specifications
For Power	Power Cable	XLCS-PN □□□YS	XDL-L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML-DB03D/ DB06D/ DB09D/ DC06D/ DC12D/ DD18D/ DD12D/ DD22D/ DD34D/ DE40D/ DE60D	
For Power	Power Cable	XLCS-PN □□□ZS	XDL-L7SA□□□B L7NA□□□B L7NHA□□□U L7PA□□□U	XML-DFA1G/ DFA6G	





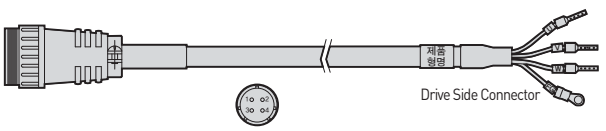
Nanaboshi Electronic
NJC-24-4-ADF(Female)
〈Motor side connecter〉

Item	Signal	PIN No.	Line Color
Motor	U	1	Red
	V	2	White
	W	3	Black
	Ground	4	Green

1. Motor Side Connector
- PLUG Spec. :
  NJC-24-4-ADF(Female connector)

2. Drive Side Connector
- U, V, W Pin PG Pin Spec. : UA-F2012(Seoil)
- FG Spec. : 1.5×4

3. Cable Spec. : 4Cx1.5SQ, LAPP Cable(P/N : 00257001)



Nanaboshi Electronic
NJC-24-4-ADF(Female)
〈Motor side connector〉

Item	Signal	PIN No.	Line Color
Motor	U	1	Red
	V	2	White
	W	3	Black
	Ground	4	Green

1. Motor Side Connector
- PLUG Spec. :
  NJC-24-4-ADF(Female connector)

2. Drive Side Connector
- U, V, W Pin PG Pin Spec. : UA-F2012(Seoil)
- FG Spec. : 2.5×4

3. Cable Spec. : 4Cx2.5SQ, LAPP Cable(P/N : 00257011)

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

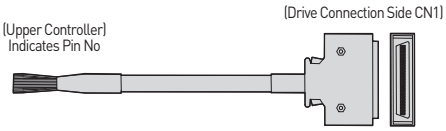
Cable Length(m)	3	5	10	20
Robotic Cable(F)	F03	F05	F10	F20
General Cable(N)	N03	N05	N10	N20

Signal Cable

Type	Product Type	Model Name [Note1]	Applicable Motor	Specifications
For Signal	CN1 Cable	XLC-CN1 □□A	XDL-L7S □□ □B XDL-L7NH □□ □U	

(Pin No. Display)

NO	I/O Signal	NO	I/O Signal	NO	I/O Signal	NO	I/O Signal	NO	I/O Signal
1	TRQCOM	11	PR+	21	SPD3	31	/BO	41	RDY-
2	REFCOM	12	PR-	22	SPD2	32	AO	42	TLOUT
3	PZO	13	PCON	23	SPD1	33	/AO	43	ZSPD
4	ZO	14	GAIN2(SEN)	24	GND	34	+15V	44	BRAKE
5	/ZO	15	PCLEAR	25	GND	35	-15V	45	INSPD/INPOS
6	SRO	16	TLIMIT	26	SETCOM	36	GND	46	DIR
7	/SRO	17	ALMRST	27	SPDCOM	373	GNDA	47	SVON
8	GNDA	18	EMG	28	MONIT1	8	ALARM+	48	STOP
9	RF+	19	CWLIM	29	MONIT2	39	ALARM-	49	PULCOM
10	PF-	20	CCWLIM	30	BO	40	RDY+	50	+24Vin

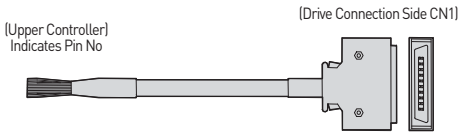


Drive Side Connection(CN1)
- Case Spec. : 10350-52A0-008(3M)
- Connector Spec. : 10150-3000VE(3M)
- Cable Spec. : 20276-SB 25P(AWG28)

Type	Product Type	Model Name	Applicable Motor	Specifications
For Signal	CN1 Cable	XLCS-CN1 □□A	XDL-L7S □□ □B XDL-L7NH □□ □U	

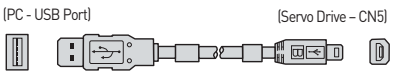
(Pin No. Display)

NO	Signal	NO	Signal	NO	Signal	NO	Signal
1	BRAKE+	6	24V	11	HOME	16	Spare Pin
2	BRAKE-	7	CWL	12	ALMRST	17	RDY+
3	ALARM+	8	CCWL	13	DI1	18	RDY-
4	ALARM-	9	PROBE1	14	DI2	19	DO1+
5	Spare Pin	10	PROBE2	15	Spare Pin	20	DO1-



Drive Side Connection(CN1)
- Case Spec. : 10320-52A0-008(3M)
- Connector Spec. : 10120-3000VE(3M)
- Cable Spec. : ROW-SB0.1C ×20C(AWG28)

Type	Product Type	Model Name	Applicable Motor	Specifications
For Signal	Communication Cable	XLCS-CN5L7U	All Models of XDL-L7 SERIES	

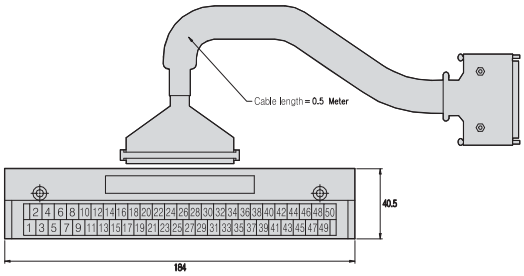


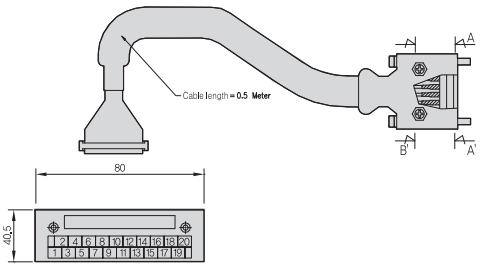
1. PC Side Connector : USB A Plug
2. Drive Side Connector(CN5) : Mini USB 5P Plug
3. Electric Requirements Spec :
   Double Shielded, Twisted Pair, EMI-filter attached type
   (Ex. : KU-AMB518, SANWA)
4. Only 1.8m length of cable is available to use

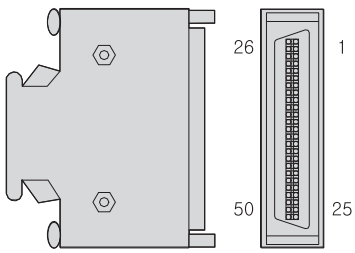
Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

Cable Length(m)	1	2	3	5
General Cable(N)	N01	N02	N03	N05
Robotic Cable(F)	F01	F02	F03	F05

Connector

<table>
<tr><th>Type</th><th>Product Type</th><th>Model Name [Note1]</th><th>Applicable Motor</th><th>Specifications</th></tr>
<tr><td rowspan="2">T/B</td><td>CN1 T/B</td><td>XLC- VSCN1T□□</td><td>XDL-L7S□□ □B
XDL-L7NH□□ □U</td><td rowspan="2">

• Extended CN1 T/B for VS/L7S
• Available Cable Length : 0.5[m], 1[m], 1.5[m], 2[m], 3[m]</td></tr>
<tr><td colspan="3">(Pin No. Display)
<table>
<tr><th>NO</th><th>I/O Signal</th><th>NO</th><th>I/O Signal</th><th>NO</th><th>I/O Signal</th><th>NO</th><th>I/O Signal</th><th>NO</th><th>I/O Signal</th></tr>
<tr><td>1</td><td>TRQCOM</td><td>11</td><td>PR+</td><td>21</td><td>SPD3</td><td>31</td><td>/BO</td><td>41</td><td>RDY-</td></tr>
<tr><td>2</td><td>REFCOM</td><td>12</td><td>PR-</td><td>22</td><td>SPD2</td><td>32</td><td>AO</td><td>42</td><td>TLOUT</td></tr>
<tr><td>3</td><td>PZO</td><td>13</td><td>PCON</td><td>23</td><td>SPD1</td><td>33</td><td>/AO</td><td>43</td><td>ZSPD</td></tr>
<tr><td>4</td><td>ZO</td><td>14</td><td>GAIN2(SEN)</td><td>24</td><td>GND</td><td>34</td><td>+15V</td><td>44</td><td>BRAKE</td></tr>
<tr><td>5</td><td>/ZO</td><td>15</td><td>PCLEAR</td><td>25</td><td>GND</td><td>35</td><td>-15V</td><td>45</td><td>INSPD/INPOS</td></tr>
<tr><td>6</td><td>SRO</td><td>16</td><td>TLIMIT</td><td>26</td><td>SETCOM</td><td>36</td><td>GND</td><td>46</td><td>DIR</td></tr>
<tr><td>7</td><td>/SRO</td><td>17</td><td>ALMRST</td><td>27</td><td>SPDCOM</td><td>37</td><td>GNDA</td><td>47</td><td>SVON</td></tr>
<tr><td>8</td><td>GNDA</td><td>18</td><td>EMG</td><td>28</td><td>MONIT1</td><td>38</td><td>ALARM+</td><td>48</td><td>STOP</td></tr>
<tr><td>9</td><td>RF+</td><td>19</td><td>CWLIM</td><td>29</td><td>MONIT2</td><td>39</td><td>ALARM-</td><td>49</td><td>PULCOM</td></tr>
<tr><td>10</td><td>PF-</td><td>20</td><td>CCWLIM</td><td>30</td><td>BO</td><td>40</td><td>RDY+</td><td>50</td><td>+24Vin</td></tr>
</table></td></tr>
<tr><td rowspan="2">CN1 T/B</td><td>XLCS-L7NCN1T-□□</td><td>XDL-L7S□□ □B
XDL-L7NH□□ □U</td><td rowspan="2">

• Extended CN1 T/B for L7N
• Available Cable Length : 0.5[m], 1[m], 1.5[m], 2[m]</td></tr>
<tr><td colspan="3">(Pin No. Display)
<table>
<tr><th>NO</th><th>Signal</th><th>NO</th><th>Signal</th><th>NO</th><th>Signal</th><th>NO</th><th>Signal</th></tr>
<tr><td>1</td><td>BRAKE+</td><td>6</td><td>24V</td><td>11</td><td>HOME</td><td>16</td><td>Spare Pin</td></tr>
<tr><td>2</td><td>BRAKE-</td><td>7</td><td>CWL</td><td>12</td><td>ALMRST</td><td>17</td><td>RDY+</td></tr>
<tr><td>3</td><td>ALARM+</td><td>8</td><td>CCWL</td><td>13</td><td>DI1</td><td>18</td><td>RDY-</td></tr>
<tr><td>4</td><td>ALARM-</td><td>9</td><td>PROBE1</td><td>14</td><td>DI2</td><td>19</td><td>DO1+</td></tr>
<tr><td>5</td><td>Spare Pin</td><td>10</td><td>PROBE2</td><td>15</td><td>Spare Pin</td><td>20</td><td>DO1-</td></tr>
</table></td></tr>
<tr><td>CN</td><td>CN1 Connector</td><td>XLC-CN1NNA</td><td>XDL-L7S□□ □B
XDL-L7NH□□ □U</td><td>

• Case Spec. : 10350-52A0-008(3M)
• Connector Spec. : 10150-3000VE(3M)</td></tr>
</table>

Note1) □ □ □ of Model Name indicates the kind and length of cable. And the declaration is as below.

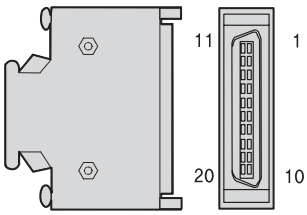
XLC-VSCN1T

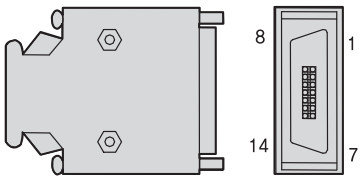
Cable Length(m)	0.5	1	2	3
Declaration	None	01	02	03

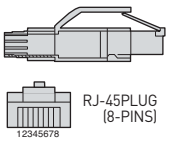
XLCS-L7NCN1T

Cable Length(m)	0.5	1	2	3
Declaration	None	01	02	03

Connector

<table>
<tr><td>CN</td><td>CN1
Connector</td><td>XLC-CN2NNA</td><td>XDL-
L7NA□□ □B
L7NH□□ □U</td><td>

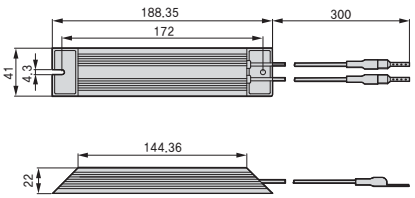
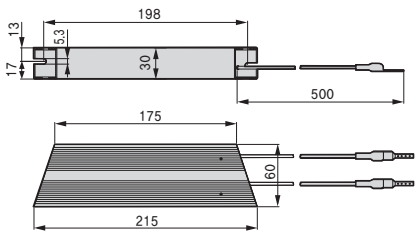
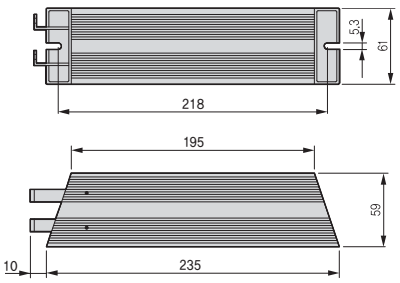
• Case Spec. : 10320-52A0-008(3M)
• Connector Spec. : 10120-3000VE(3M)</td></tr>
<tr><td>CN</td><td>CN2
Connector</td><td>XLC-CN3NNA</td><td>All models of
XDL-
L7 SERIES</td><td>

• Case Spec. : 10314-52A0-008(3M)
• Connector Spec. : 10114-3000VE(3M)</td></tr>
<tr><td>CN</td><td>CN3
CN4
EtherCAT
Connector</td><td>XLCS-CN4NNA</td><td>XDL-
L7NA□□ □B
L7NH□□ □U</td><td>

RJ-45PLUG
(8-PINS)
Note1) EtherCAT use
only 4wires(1, 2, 3, 6)
<table>
<tr><th>PIN No.</th><th>Signal</th><th>Line Color</th></tr>
<tr><td>1</td><td>TX/RX0 Plus</td><td>White/Orange</td></tr>
<tr><td>2</td><td>TX/RX0 Minus</td><td>Orange</td></tr>
<tr><td>3</td><td>TX/RX1 Plus</td><td>White/Green</td></tr>
<tr><td>4</td><td>TX/RX2 Plus</td><td>Blue</td></tr>
<tr><td>5</td><td>TX/RX2 Minus</td><td>White/Blue</td></tr>
<tr><td>6</td><td>TX/RX1 Minus</td><td>Green</td></tr>
<tr><td>7</td><td>TX/RX3 Plus</td><td>White/Brown</td></tr>
<tr><td>8</td><td>TX/RX3 Minus</td><td>Brown</td></tr>
<tr><td colspan="2">Plate</td><td>SHILDE</td></tr>
</table></td></tr>
<tr><td>CN</td><td>STO
Cable</td><td>XLCS-STO□□A</td><td>XDL-
L7NA□□ □B
L7NH□□ □U</td><td><table>
<tr><th>PIN No.</th><th>IO Signal</th><th>Color</th></tr>
<tr><td>1</td><td>NC</td><td>-</td></tr>
<tr><td>2</td><td>NC</td><td>-</td></tr>
<tr><td>3</td><td>HWBB1 Minus</td><td>Orange</td></tr>
<tr><td>4</td><td>HWBB1 Plus</td><td>Orange</td></tr>
<tr><td>5</td><td>HWBB2 Minus</td><td>Yellow</td></tr>
<tr><td>6</td><td>HWBB2 Plus</td><td>Yellow</td></tr>
<tr><td>7</td><td>EDM Plus</td><td>White</td></tr>
<tr><td>8</td><td>EDM Minus</td><td>White</td></tr>
</table>
1. Cable Length
• Only 0.3[m], 1[m], 3[m] of Cable is available to use.
2. Connector Model Name : APC-STO00A
* Caution During assembly of connector,
It can be broken easily without</td></tr>
</table>

200V Braking Resistor

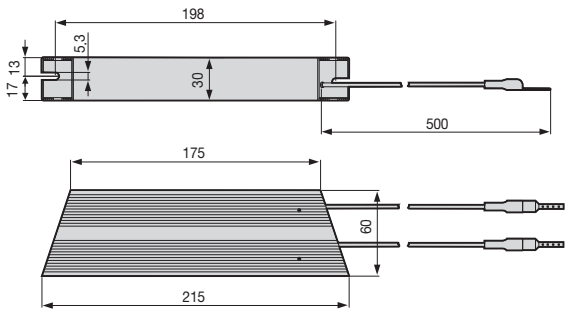
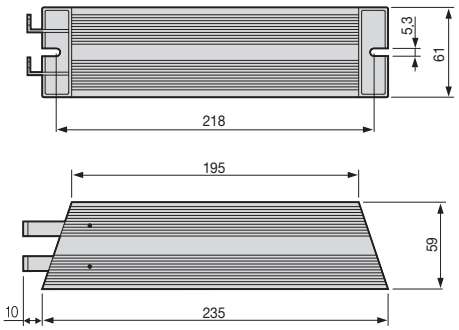
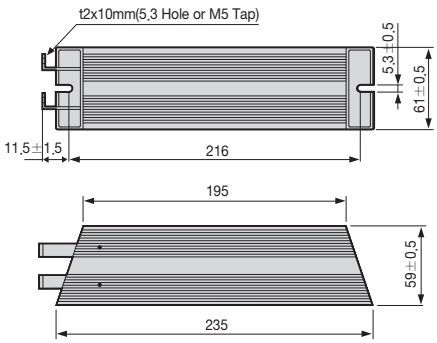
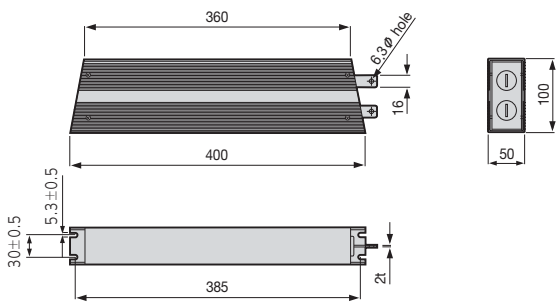
*Option braking resistors are selectable items for user's need.

Type	Product Type	Model Name [Note1]	Applicable Motor	Specifications
Resistor	Braking Resistor	XLCS-140R50	XDL- L7□A001□ L7□A002□ L7□A004□	 • IRH 140W 50ohm
Resistor	Braking Resistor	XLCS-300R30	XDL- L7□A008□ L7□A010□	 • IRV 300W 30ohm
Resistor	Braking Resistor	XLC-600R30	XDL- L7□A020□ L7□A035□	 **IRV 600W 30ohm** * L7□A020□ - 2pcs(Parallel Connection) L7□A030□ - 3pcs(Parallel Connection) **IRV 600W 28ohm** * L7□A050□ - 4pcs(Parallel Connection) Note1) IRV 600S 30ohm and 600S 28ohm have the same external dimensions.
		XLC-600R28	XDL- L7□A050□(4P)	

Note1) L7 Series 100W~7.5kW has the internal basic braking resistor. If the machine requires short deceleration time frequently, refer to table above and apply the appropriate braking resistor.

400V Braking Resistor

*Option braking resistors are selectable items for user's need.

Type	Product Type	Model Name (Note1)	Applicable Motor	Specifications
Resistor	Braking Resistor	XLCS-300R82 82[Ω]/300W	XDL- L7□B010□	 IRV300-82Ω
Resistor	Braking Resistor	XLCS-600R140 70Ω /1200W (140Ω / 600W ×2P)	XDL- L7□B020□ L7□B035□	 IRV600-140Ω
Resistor	Braking Resistor	XLCS-600R75 25Ω /800W (75Ω / 600W ×3P)	XDL- L7□B75□	 IRV600-75Ω
Resistor	Braking Resistor	XLCS-2000R13.4 13.4Ω /2000W	XDL- L7□B150□	 IRM2000-13.4Ω

Note1) L7 Series 100W~7.5kW has the internal basic braking resistor. If the machine requires short deceleration time frequently, refer to table above and apply the appropriate braking resistor.





Application

Contents

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XG-PM ---------- 126
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Worldwide Network ---------- 138

XDL Motion Module [EtherCAT]

Features

- 32 axes (master) and 4 axes (virtual) control
- EhterCAT CoE supported servo drive
- Communication cycle : 1ms
- Built-in DI/DO 8 points each and EtherCAT I/O 512 points
- Program 2MB
- External encoder input 2ch (line drive)
- Max. transmission distance : 100m



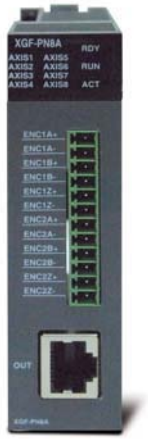
Specifications

Item		XGF-M32E
Communication		EtherCAT (CoE : CANopen over EtherCAT)
Number of axis	Real	32 axes
	Virtual	4axes
	I/O	Input/output 8 points each (built-in) EtherCAT I/O connection available
Control period		1ms, 2ms, 4ms (same as main task period)
Control unit		Pulse, mm, inch, degree
I/O	Internal	Input 8 points, output 8 points
	External	EtherCAT I/O 4 ea (max. 256 points)
Motion Program	No. of program	Max. 256 ea
	Capacity	Max. 2Mbyte
	Language	LD(FB), ST
	Position data	6400 points/all aixs
Control method		Position, Velocity, Torque(Servo drivers support) control, Synchronous control, Interpolation control
Range of position/velocity		±LREAL, 0
Acc. Dec. process		Trapezoid type, S-type (Setting to specify the Jerk at function block)
Acc. Dec. time		1 ~ 2, 147, 483, 647ms
Manual operation		JOG operation
Torque unit		Rated torque % designation
Encoder input	Channel	2 channels
	Max. input	Max. 500Kpps
	Input method	Line drive input (RS-422A IEC specification) Open collector output type encoder
	Input type	CW/CCW, Pulse/Dir, Phase A/B
Max. distance		100m
Communication cable		Over CAT.5 STP(Shielded Twisted-pair) cable
Error indication		Indicated by LED
Communication status indication		Indicated by LED
Occupied point I/O		Variable: 16 point, Fixed: 64 point
Communication physical layer		100BASE-TX
Consumable current(mA)		900mA
Weight		122g

Positioning Module(EtherCAT)

Features

- XGF-PN8B : Standard EtherCAT Network Support(XGT Servo XDL Series)
- Direct connect with servo driver Max 8
- 2~8 axis linear interpolation, 2axis circular interpolation, 3axis helical interpolation
- Position, speed, feed control is possible through the various operation
- Parameters, the operation data stored in the FRAM(without Battery)
- CAM for controlling up to eight different types of CAM data



Specifications

Item		XGF-PN8B			
Number of axis		8 axis			
Interpolation		2~8 axis linear, 2axis circular, 3axis helical interpolation			
Control method		Position, speed, Speed/position, position/speed position/torque, Feed control			
Setting unit		pulse, mm, inch, degree			
Positioning data		Each axis has 400 data items (Operation step number 1~400). It is available to set with software package or programming.			
XG-PM	Port	RS-232C, USB			
	Data	Basic, expansion, manual, servo parameter, operation data, cam data, command information			
	Monitor	Operation, trace, input sort, error information			
Back-up		FRAM(parameter, operation data) no battery			
Positioning	Positioning method	Absolute/Incremental			
	Position address range		Absolute	Incremental	Speed/position, position/speed conversion control
		mm	-214748364.8 ~ 214748364.7(㎛)	-214748364.8 ~ 214748364.7(㎛)	-214748364.8 ~ 214748364.7(㎛)
		inch	-21474.83648 ~ 21474.83647	-21474.83648 ~ 21474.83647	-21474.83648 ~ 21474.83647
		degree	-21474.83648 ~ 21474.83647	-21474.83648 ~ 21474.83647	-21474.83648 ~ 21474.83647
		pulse	-2147483648 ~ 2147483647	-2147483648 ~ 2147483647	-2147483648 ~ 2147483647
	Position speed range	mm	0.01 ~ 20000000.00(mm/Min)		
		inch	0.001 ~ 2000000.000(inch/Min)		
		degree	0.001 ~ 2000000.000(degree/Min)		
		pulse	1 ~ 20.000.000(pulse/Sec)		
		RPM	0.1 ~ 100000.0(RPM)		
	Accel/Decel pattern	Trapezoidal & S-curve acceleration/deceleration			
	Accel/Decel time	1~2.147.483.647 ms			
Manual		Jog/ MPG/ inching			
Homing method		Max+Z(Forward), Min+Z(Backward), Near-point+Z(Forward, Backward), Max+near-point+Z(Forward), Min+near-point+Z(Backward), Z(Forward, Backward), near-point(Forward, Backward)			
The ability to Change speed		Absolute/Percent			
Torque		Rated torque %			
Absolute position System		0 (Absolute encoder type servo)			
Encoder input	Channel	2 Channel			
	Max. Input	Max. 200 Kpps			
	Input method	line-drive input(RS-422A IEC), open collector output type			
	Type	CW/CCW, Pulse/Dir, Phase A/B			
	Connector	12 Pin connector			
Communication Cycle		800 ㎲			
Max. distance		100 m			
Cable		STP(Shielded Twisted-pair) cable			
Error display		LED			
Operation display		LED			
Occupied points of I/O		64points (Fixed type), 16points (Variable type)			
Current consumption (mA)		500 ㎃			
Weight(kg)		115 g			

Positioning Module [APM]

Features

- Highly reliable position control with LSIS ASIC-embedded processor
- Enhanced control with fast control processing speed
- High-speed motor control (Max. pulse output: 1Mbps)
- Circular/linear interpolation, separate/ synchronous operation
- Trapezoidal & S-curve acceleration/deceleration
- Easy and quick control through external input (JOG operation included)
- Encoder input support
- High-speed processing of command (4ms)
- Easy to set positioning parameters (Windows)
- Monitoring/Tracking/Simulation
- Available to edit operation parameter data in EXCEL
- Self-diagnosis
- Real-time information and solution for each error



Specifications

Item			Specifications		
			XGF-PO1A, XGF-PD1A	XGF-PO2A, XGF-PD2A	XGF-PO3A, XGF-PD3A
Number of axis			1	2	3
Interpolation				2-axis linear interpolation, 2-axis circular interpolation	2/3-axis linear interpolation, 2-axis circular interpolation
Control method			Position control, speed control, speed/position control, position/speed control		
Setting unit			Pulse, mm, inch, degree		
Positioning data			Each axis has 400 data items (Operation step number 1~400). It is available to set with software package or programming.		
Software package			Available (Connected with RS-232C Port of CPU module)		
Data backup			Flash memory (No battery)		
Positioning	Positioning method		Absolute / relative method		
	Position speed range	mm	-214748364.8 ~ 214748364.7 (㎛)		
		Inch	-21474.83648 ~ 21474.83647		
		Degree	-21474.83648 ~ 21474.83647		
		Pulse	-2147483648 ~ 2147483647		
	Type		XGF-PO□A: Open collector, XGF-PD□A: Line Driver		
	Position speed range	mm	0.01 ~ 20000000.00 (㎜/min)		
		Inch	0.001 ~ 2000000.000 (inch/min)		
		Degree	0.001 ~ 2000000.000 (degree/min)		
		Pulse	XGF-PO□A: 1~200,000 (pulse/sec), XGF-PD□A: 1~1,000,000 (pulse/sec)		
	Accel/Decel pattern		Trapezoidal & S-curve acceleration/deceleration		
	Accel/Decel time		1 ~ 65,535㎳		
Max. output pulse			XGF-PO□A: 200Kpps / XGF-PD□A: 1Mpps		
Max. distance			XGF-PO□A: 2m / XGF-PD□A: 10m		
Max. encoder input			200 Kpps		
Error display			LED		
Operation display			LED		
Connection connector			40 Pin connector		
Size of cable			AWG #24		
Occupied points of I/O			64 points (Fixed type), 16 points (Variable type)		
Current consumption (mA)			XGF-PO1A: 340	XGF-PO2A: 360	XGF-PO3A: 400
			XGF-PD1A: 510	XGF-PD2A: 790	XGF-PD3A: 860
Weight (kg)			0.12	0.13	0.135

* XGF-PO□O: Open Collector type, □: Number of axis
XGF-PD□D: Line Drive type, □: Number of axis

Positioning Module [XPM]

Features

- Max 4Axis, Max pulse output 4Mpps
- Circular/linear/ellipse/helical interpolation
- Asymmetric acceleration and deceleration driving
- FRAM parameter
- XG-PM monitoring, simulation, trace
- CAM profile program



Specifications

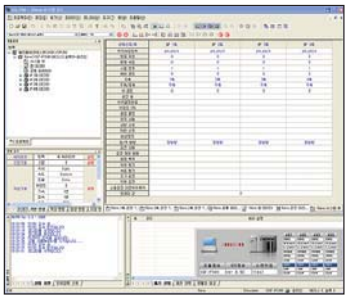
Item			XGF-PO1H XGF-PD1H	XGF-PO2H XGF-PD2H	XGF-PO3H XGF-PD3H	XGF-PO4H XGF-PD4H
Number of axis			1 axis	2 axis	3 axis	4 axis
Interpolation			-	Circular, linear, ellipse	Circular, linear, helical, ellipse	
Control method			Position control, speed control, speed/position control, position/speed control, FEED			
Positioning data			Each axis has 400 data items (Operation step number 1~400). It is available to set with XG-PM or programming.			
Configuration Tool			XG-PM (Connected with USB or RS-232C Port of CPU module)			
Data backup			FRAM (Parameter, Operation data), Flash memory (CAM Data), No battery			
Pulse output			XGF-POxH: Open collector, XGF-PDxH: linedriver			
Positioning	Positioning method		Absolute / Incremental			
	Position address range	mm	-214,748,364.8 ~ 214,748,364.7(㎛)			
		inch	-21,474.83648 ~ 21,474.83647			
		degree	-21,474.83648 ~ 21,474.83647			
		pulse	-2,147,483,648 ~ 2,147,483,647			
	Position address speed	mm	0.01 ~ 20,000,000.00(㎜/min)			
		inch	0.001 ~ 2,000,000.000(inch/min)			
		degree	0.001 ~ 2,000,000.000(degree/min)			
		pulse	1 ~ 500,000(pulse/sec): Open collector, 1 ~ 4,000,000(pulse/sec): linedriver			
		RPM	0.1 ~ 100,000.0 (RPM)			
	Accel/Decel pattern		Trapezoidal & S-curve acceleration/deceleration			
	Accel/Decel time		0~2,147,483,647ms			
Max. output pulse			Open collector: 500kpps, linedriver: 4Mpps			
Max. distance			Open collector: 5m, linedriver: 10m			
Max. encoder input			500kpps			
Error display			LED			
Size of cable			AWG #24			
Occupied points of I/O			64 points (Fixed type), 16 points (Variable type)			
Connection connector			40Pin		80Pin	
Current consumption (mA)			XGF-PO1H:400mA	XGF-PO2H:410mA	XGF-PO3H:420mA	XGF-PO4H:430mA
			XGF-PD1H:520mA	XGF-PD2H:600mA	XGF-PD3H:850mA	XGF-PD4H:890mA
Weight (kg)			120		130	

Features

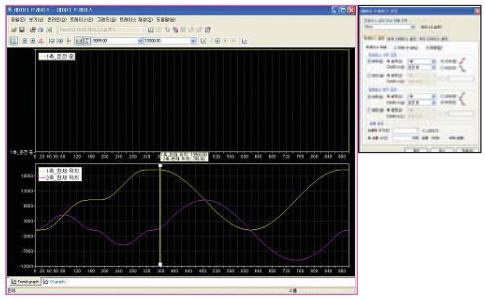
- Configuration tool with updated APM software package
- All models can be used for XGT Positioning module(APM, XPM)
- Simultaneous communications can be accessed with XG5000
- Powerful simulation, trace, monitoring



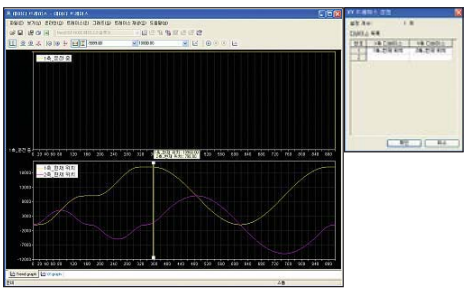
System View



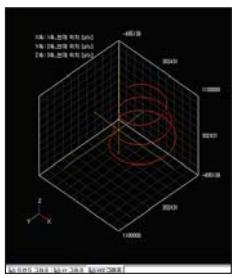
Data trace(trend graph)



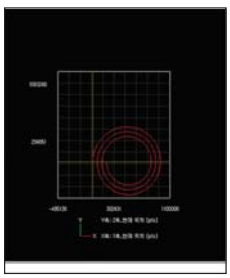
Data trace(XY graph)



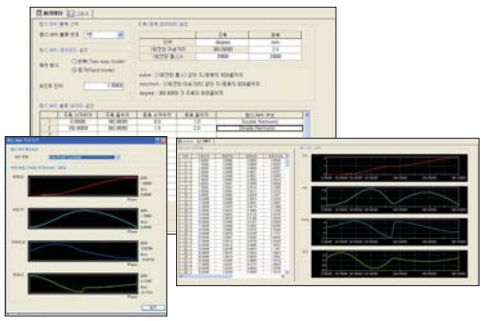
XYZ trend(3D View)



XYZ monitor(2D View)



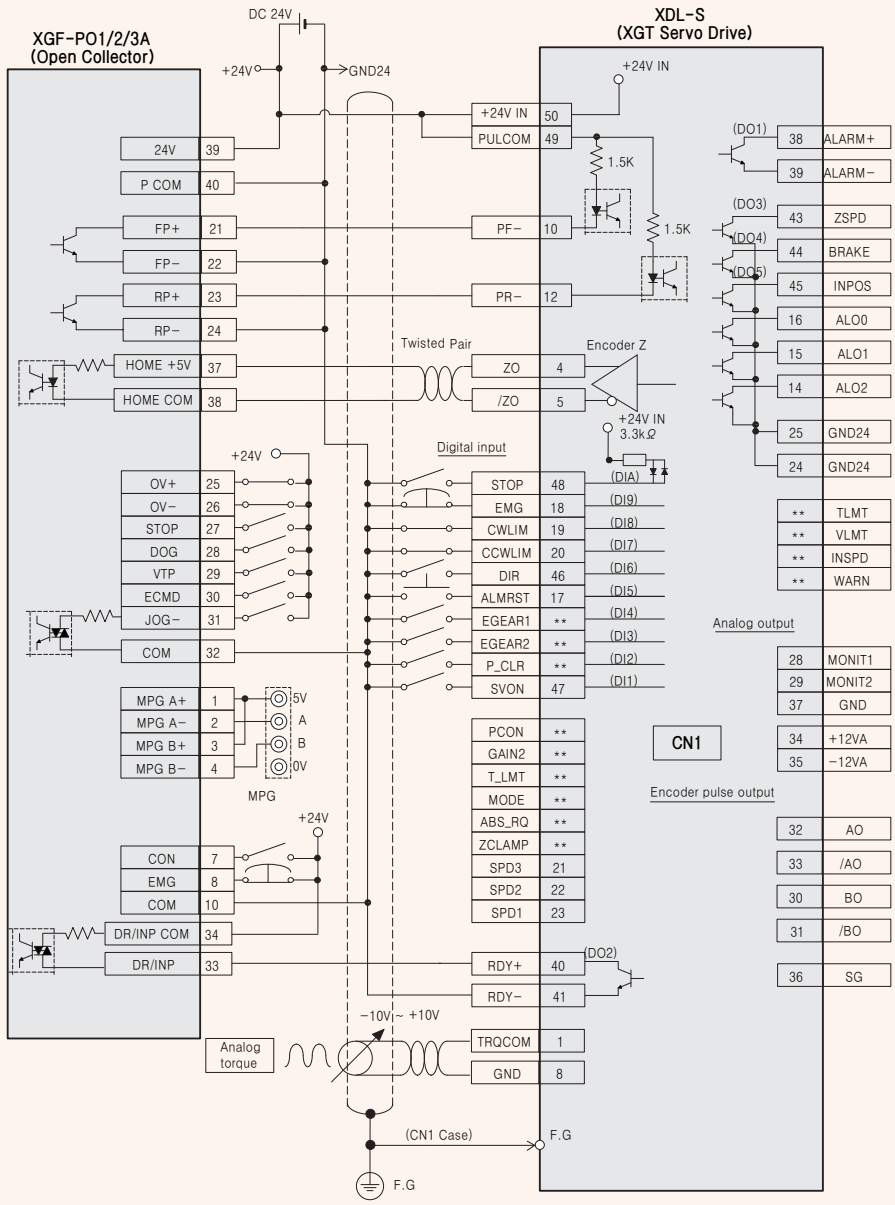
CAM control profile



Simulation

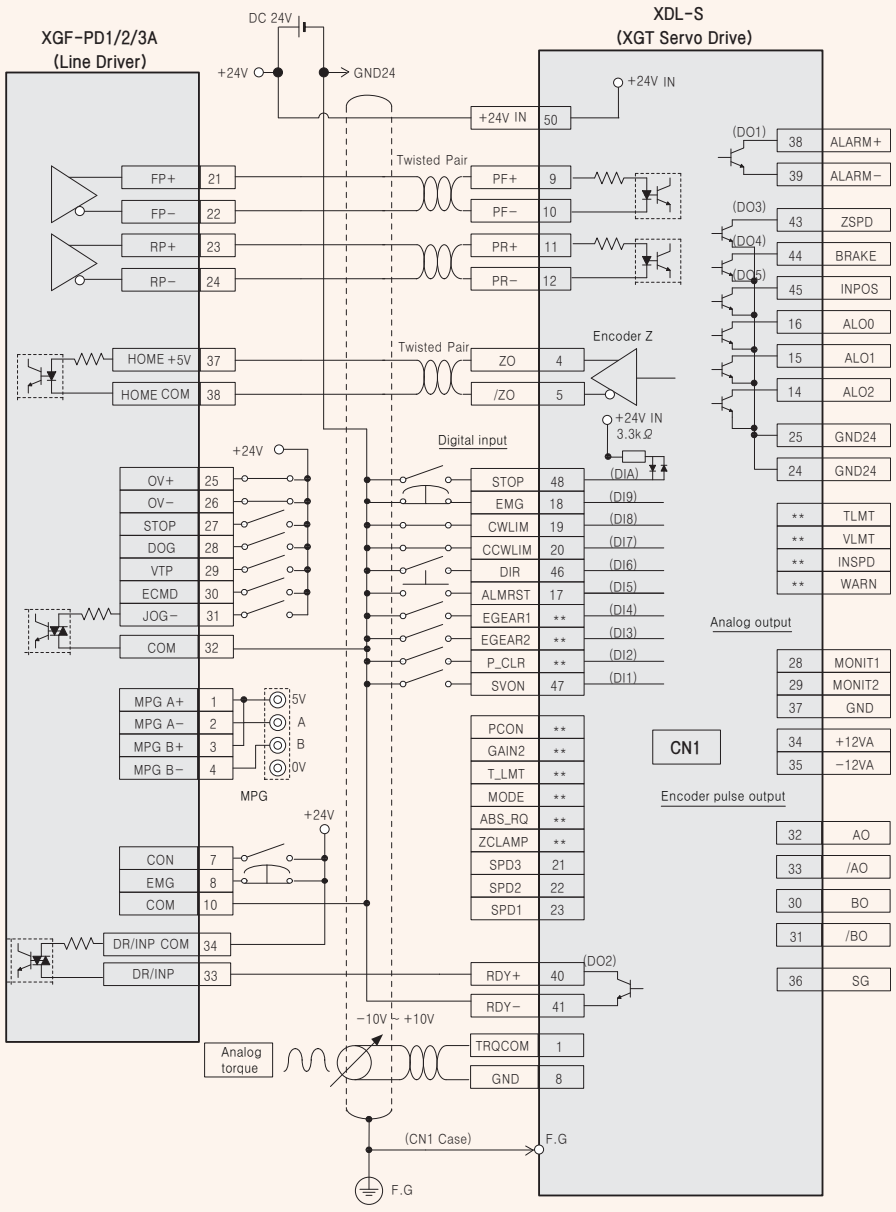


XGF-PO1/2/3A (Open Collector)



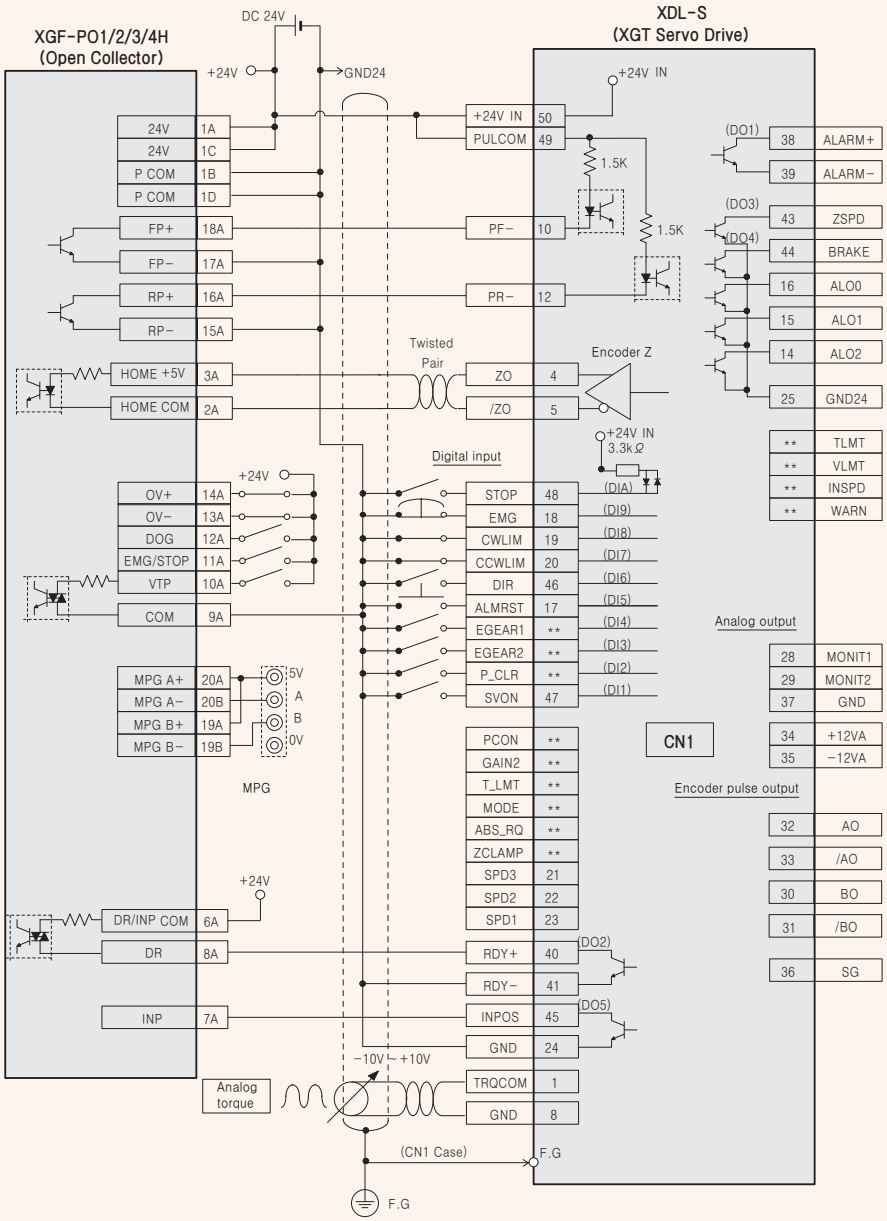
Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non−allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

XGF-PD1/2/3A (Line Driver)



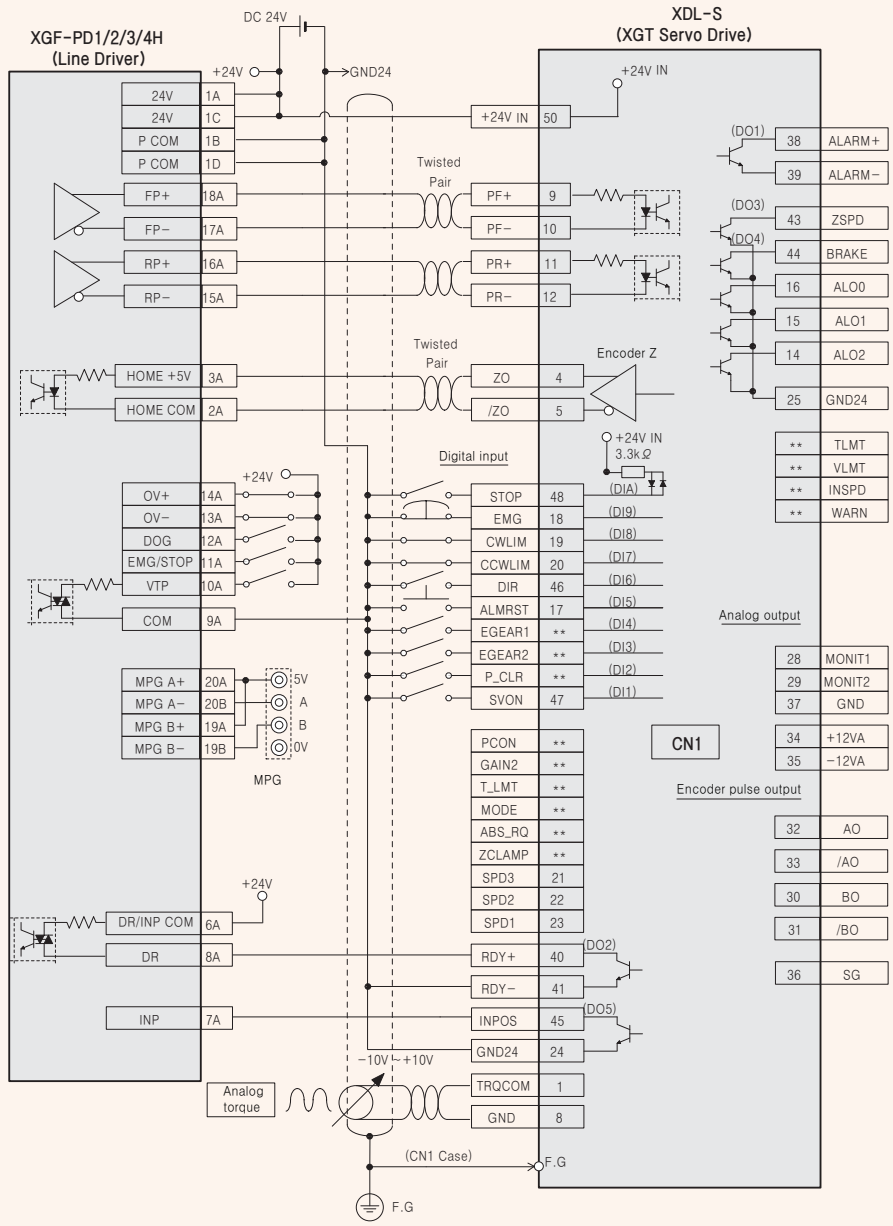
Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non−allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

XGF-PO1/2/3/4H (Open Collector)



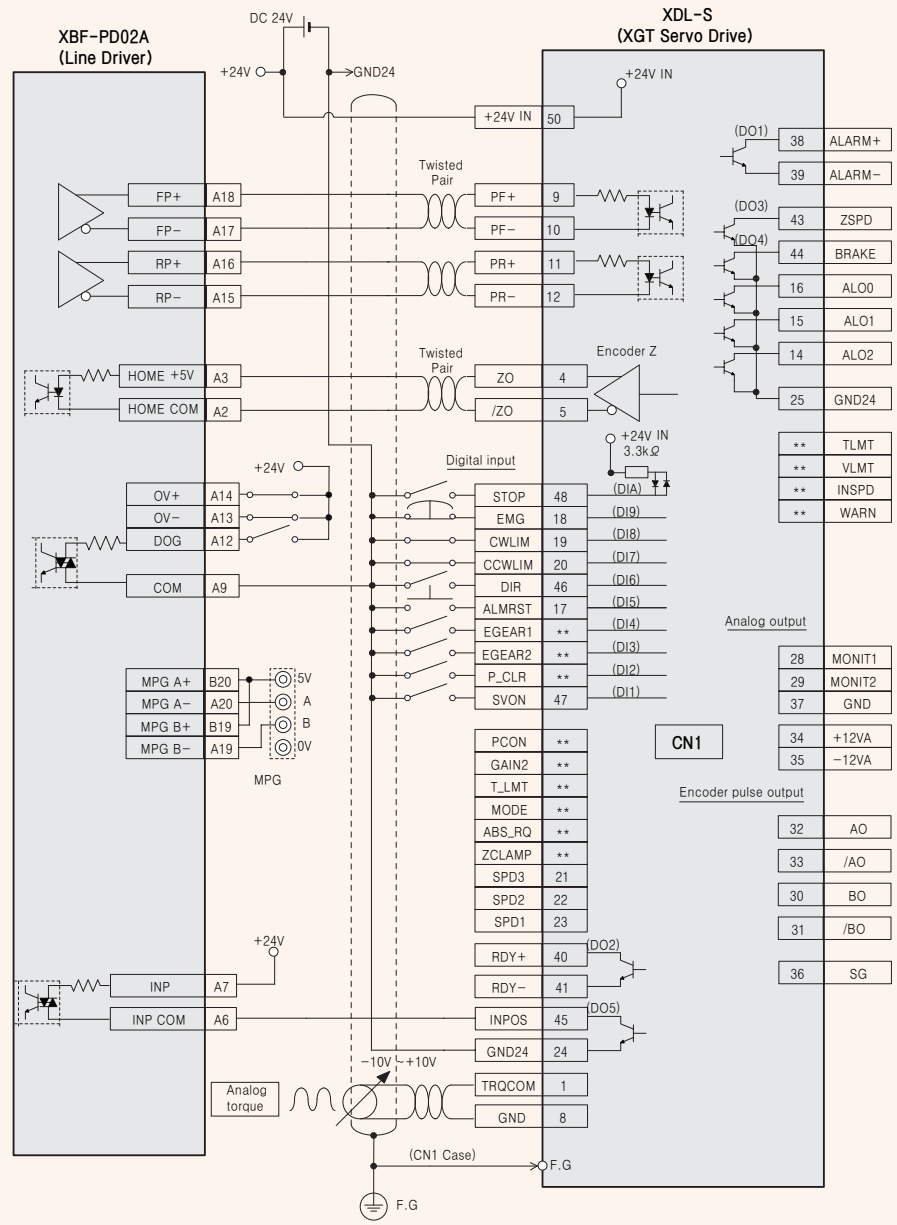
Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non−allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

XGF-PD1/2/3/4H (Line Driver)



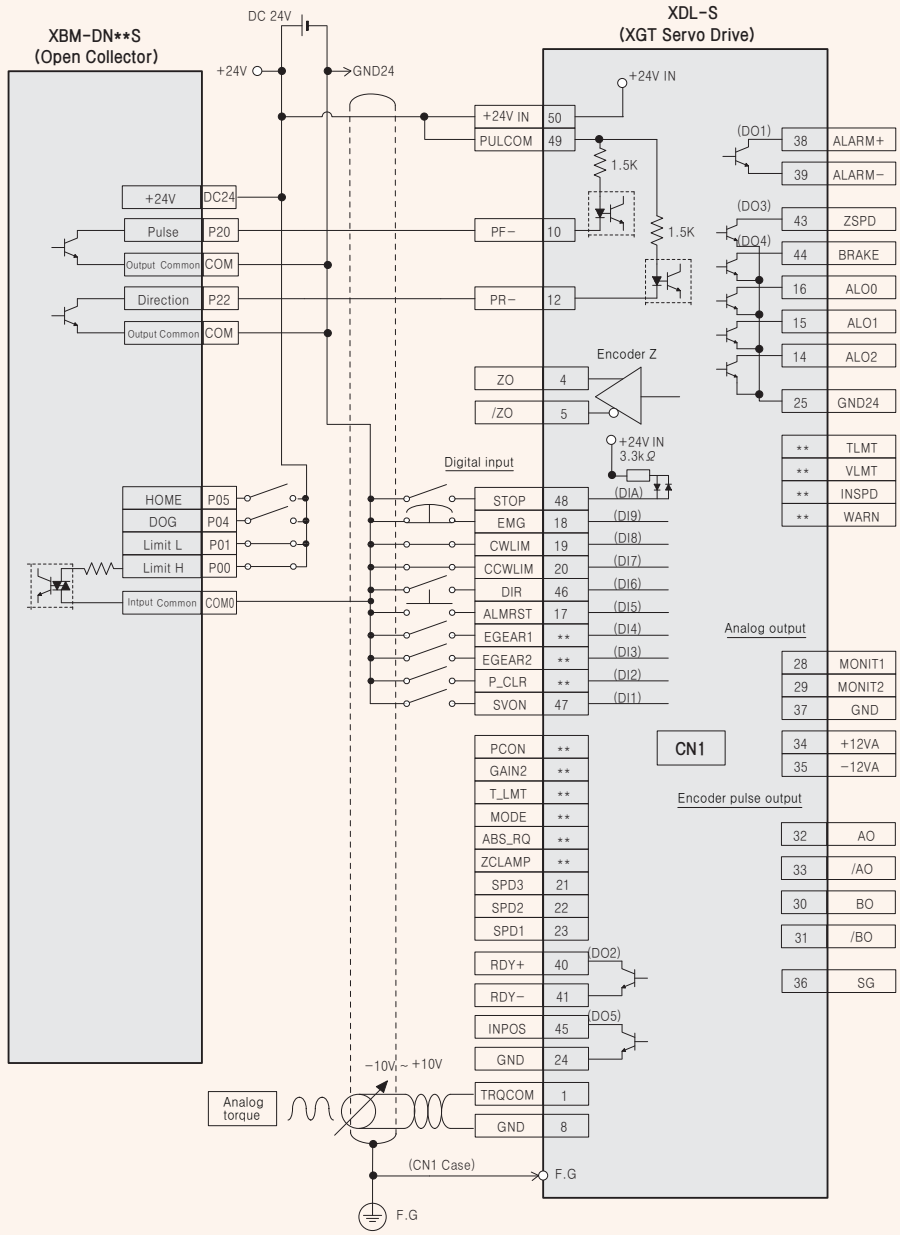
Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non−allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

XBF-PD02A(Line Driver)



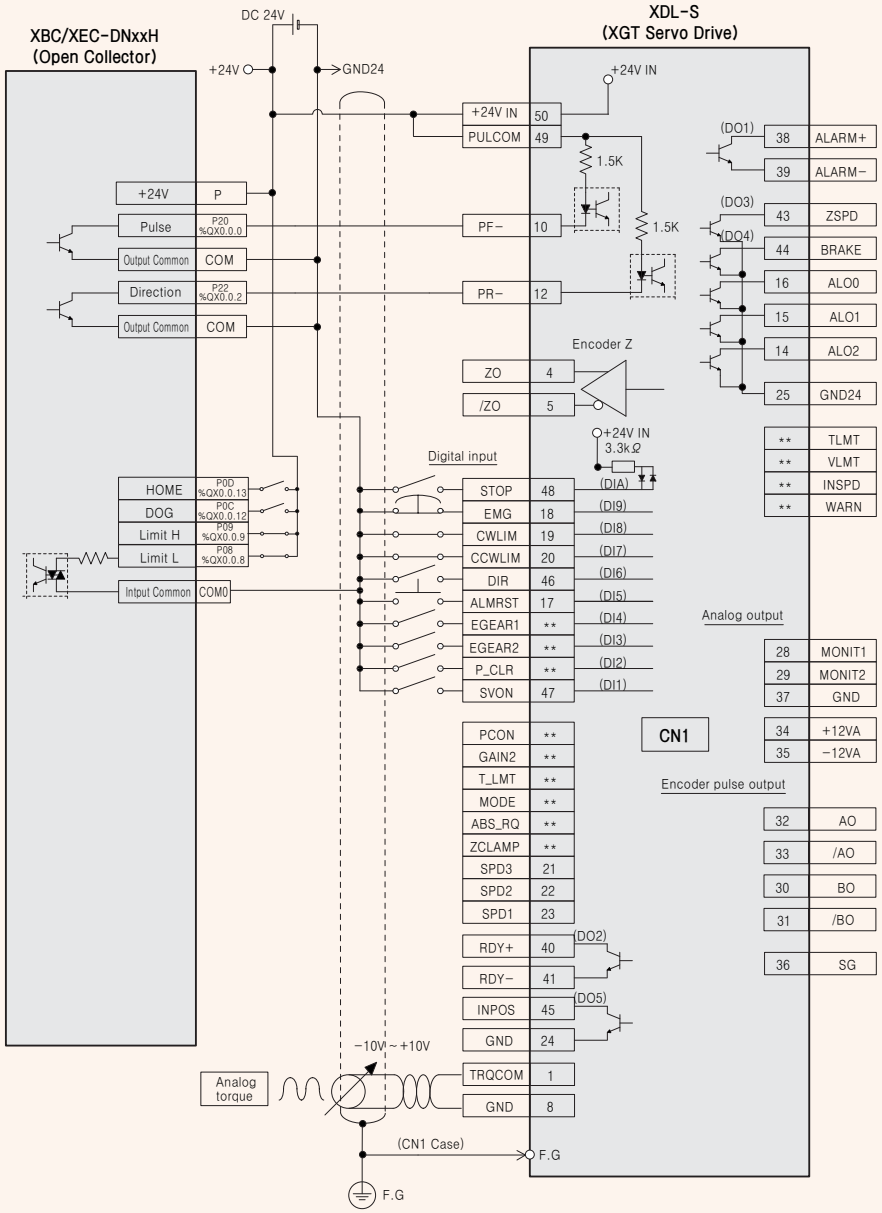
Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non−allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

XBM-DN**S(Open Collector)



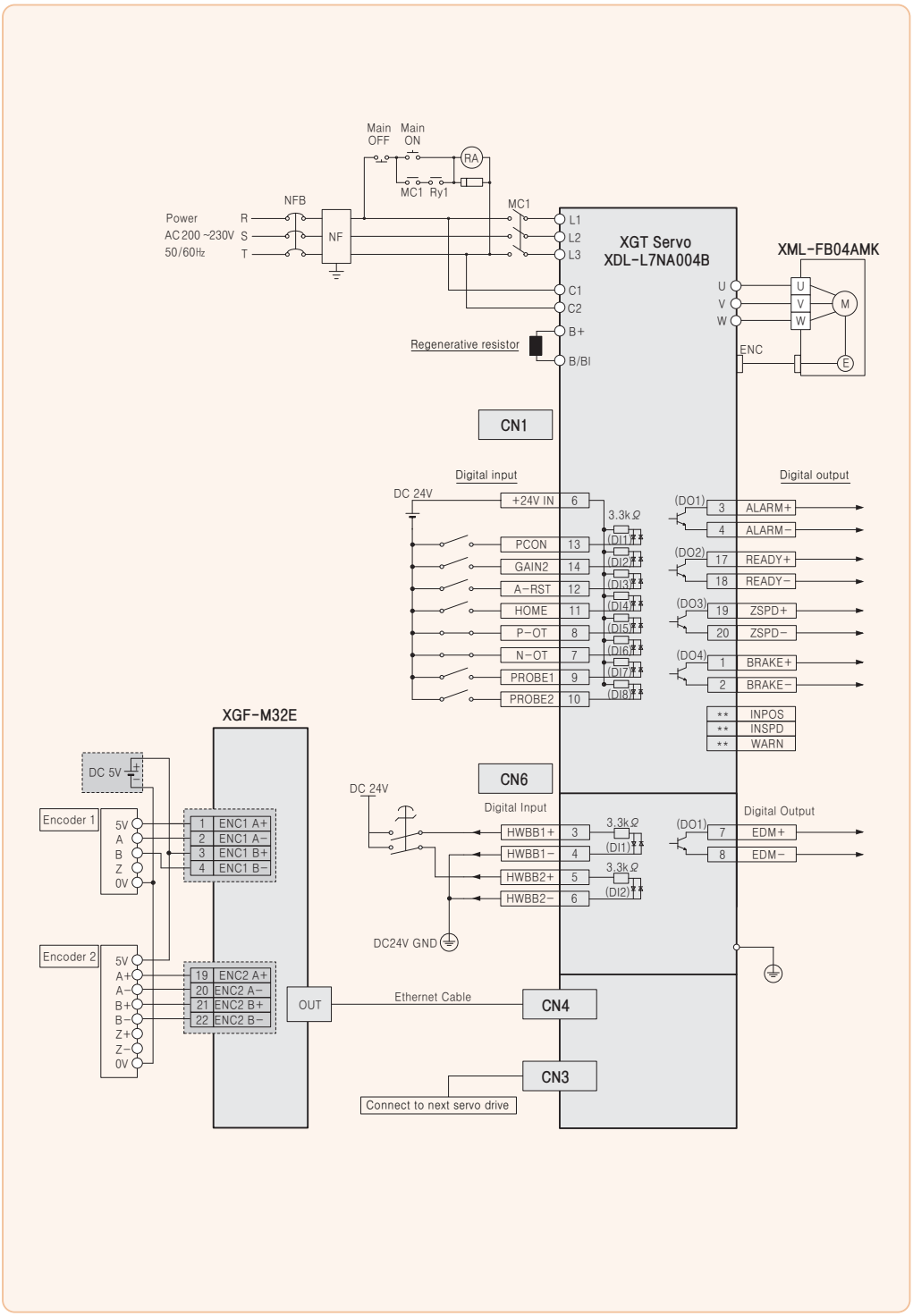
Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non-allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

XBC/XEC-DN**H(Open Collector)

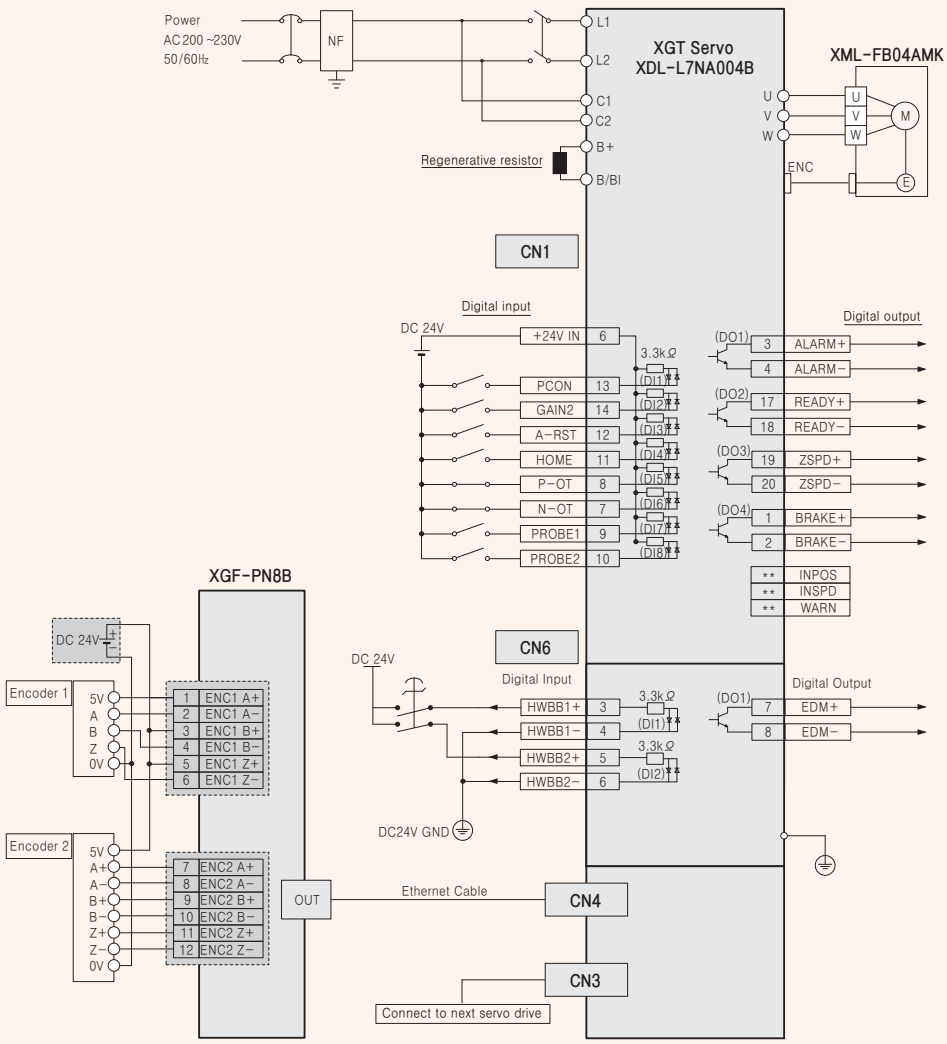


Note1) Input signals DI1 to DIA and output signals DO1 to DO5 are default signals allocated by the factory.
Note2) These are non−allocated signals. You can change their allocation by setting parameters. For more information, refer to XDL/XML servo manual.

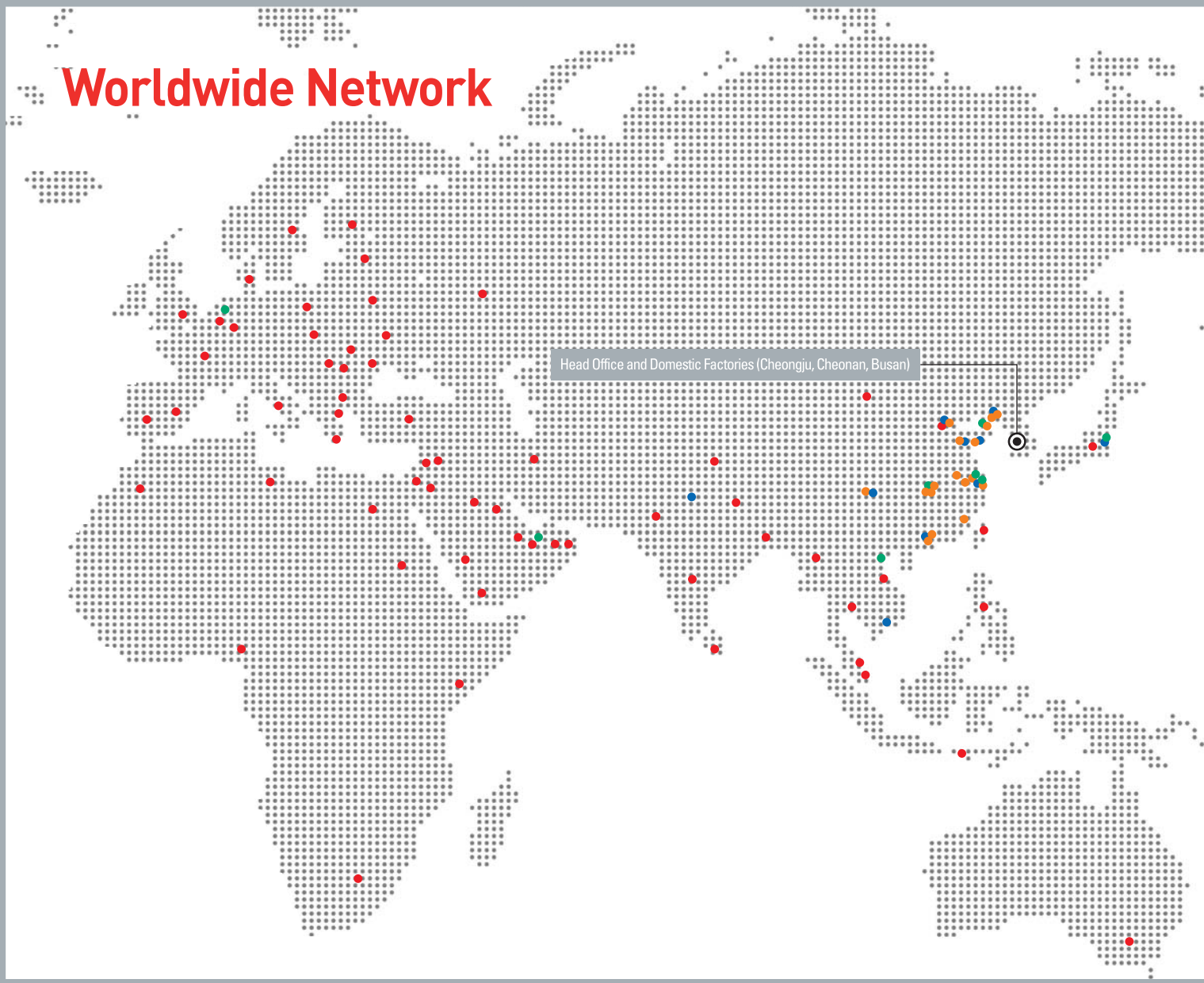
XGF-M32E


Main OFF
Main ON
RA
MC1
Ry1
NFB
MC1
Power
AC200 ~230V
50/60Hz
R
S
T
NF
L1
L2
L3
C1
C2
B+
B/BI
Regenerative resistor
XGT Servo
XDL-L7NA004B
XML-FB04AMK
U
V
W
M
ENC
E
CN1
Digital input
Digital output
DC 24V
+24V IN 6
PCON 13
GAIN2 14
A-RST 12
HOME 11
P-OT 8
N-OT 7
PROBE1 9
PROBE2 10
3.3kΩ
(DI1)
(DI2)
(DI3)
(DI4)
(DI5)
(DI6)
(DI7)
(DI8)
(DO1) 3 ALARM+
4 ALARM-
(DO2) 17 READY+
18 READY-
(DO3) 19 ZSPD+
20 ZSPD-
(DO4) 1 BRAKE+
2 BRAKE-
** INPOS
** INSPD
** WARN
XGF-M32E
DC 5V
Encoder 1
5V
A
B
Z
0V
1 ENC1 A+
2 ENC1 A-
3 ENC1 B+
4 ENC1 B-
Encoder 2
5V
A+
A-
B+
B-
Z+
Z-
0V
19 ENC2 A+
20 ENC2 A-
21 ENC2 B+
22 ENC2 B-
OUT
Ethernet Cable
CN4
CN3
Connect to next servo drive
CN6
DC 24V
Digital Input
HWBB1+ 3
HWBB1- 4
HWBB2+ 5
HWBB2- 6
3.3kΩ
(DI1)
(DI2)
DC24V GND
Digital Output
(DO1) 7 EDM+
8 EDM-

XGF-PN8B


Power
AC200~230V
50/60Hz
NF
L1
L2
C1
C2
B+
B/BI
Regenerative resistor
XGT Servo
XDL-L7NA004B
XML-FB04AMK
U
V
W
M
ENC
E
CN1
Digital input
DC 24V
+24V IN 6
3.3kΩ
PCON 13
GAIN2 14
A-RST 12
HOME 11
P-OT 8
N-OT 7
PROBE1 9
PROBE2 10
(DI1)
(DI2)
(DI3)
(DI4)
(DI5)
(DI6)
(DI7)
(DI8)
Digital output
(DO1) 3 ALARM+
4 ALARM-
(DO2) 17 READY+
18 READY-
(DO3) 19 ZSPD+
20 ZSPD-
(DO4) 1 BRAKE+
2 BRAKE-
** INPOS
** INSPD
** WARN
XGF-PN8B
DC 24V
Encoder 1
5V
A
B
Z
0V
1 ENC1 A+
2 ENC1 A-
3 ENC1 B+
4 ENC1 B-
5 ENC1 Z+
6 ENC1 Z-
Encoder 2
5V
A+
A-
B+
B-
Z+
Z-
0V
7 ENC2 A+
8 ENC2 A-
9 ENC2 B+
10 ENC2 B-
11 ENC2 Z+
12 ENC2 Z-
OUT
Ethernet Cable
CN6
DC 24V
Digital Input
HWBB1+ 3
HWBB1- 4
HWBB2+ 5
HWBB2- 6
3.3kΩ
(DI1)
3.3kΩ
(DI2)
DC24V GND
Digital Output
(DO1) 7 EDM+
8 EDM-
CN4
CN3
Connect to next servo drive

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  181 Samseong-ri,Mokcheon-myeon, Cheonan-si Chungnam-do,330-840 Korea
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  1-19 Block Hwajeon-dong, Gangseo-gu,Busan, 618-280, Korea
  Tel : 82-51-795-6114 Fax : 82-51-795-6169

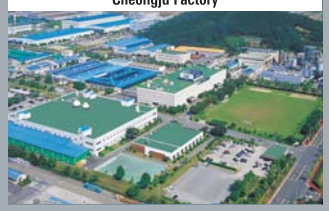
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  Room 1311, 13th Floor, M3-M4 Building91 Nguyen Chi Thanh street, Hanoi, Vietnam.
  Tel : 84-4-6275-8055 Fax : 84-4-6275-8056

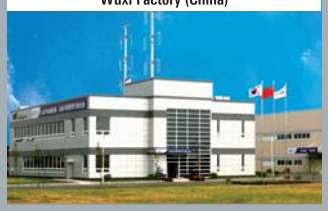
R&D Center

- Advanced Technology R&D Center
  533 Hogye-dong, Dongan-gu, Anyang-si, Gyeonggi-do, 431-749, Korea
  Tel : 82-31-450-7114
- Electro Technology R&D Center
  1 Songjeong-dong, Cheongju-si, Chungcheongbuk-do, 361-720, Korea
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  1 Songjeong-dong, Cheongju-si, Chungcheongbuk-do, 361-720, Korea
  Tel : 82-43-261-6114

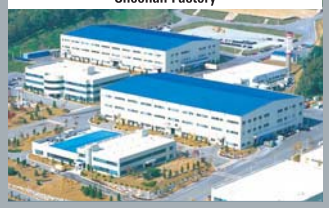
Cheongju Factory



Wuxi Factory (China)



Cheonan Factory



Dalian Factory (China)

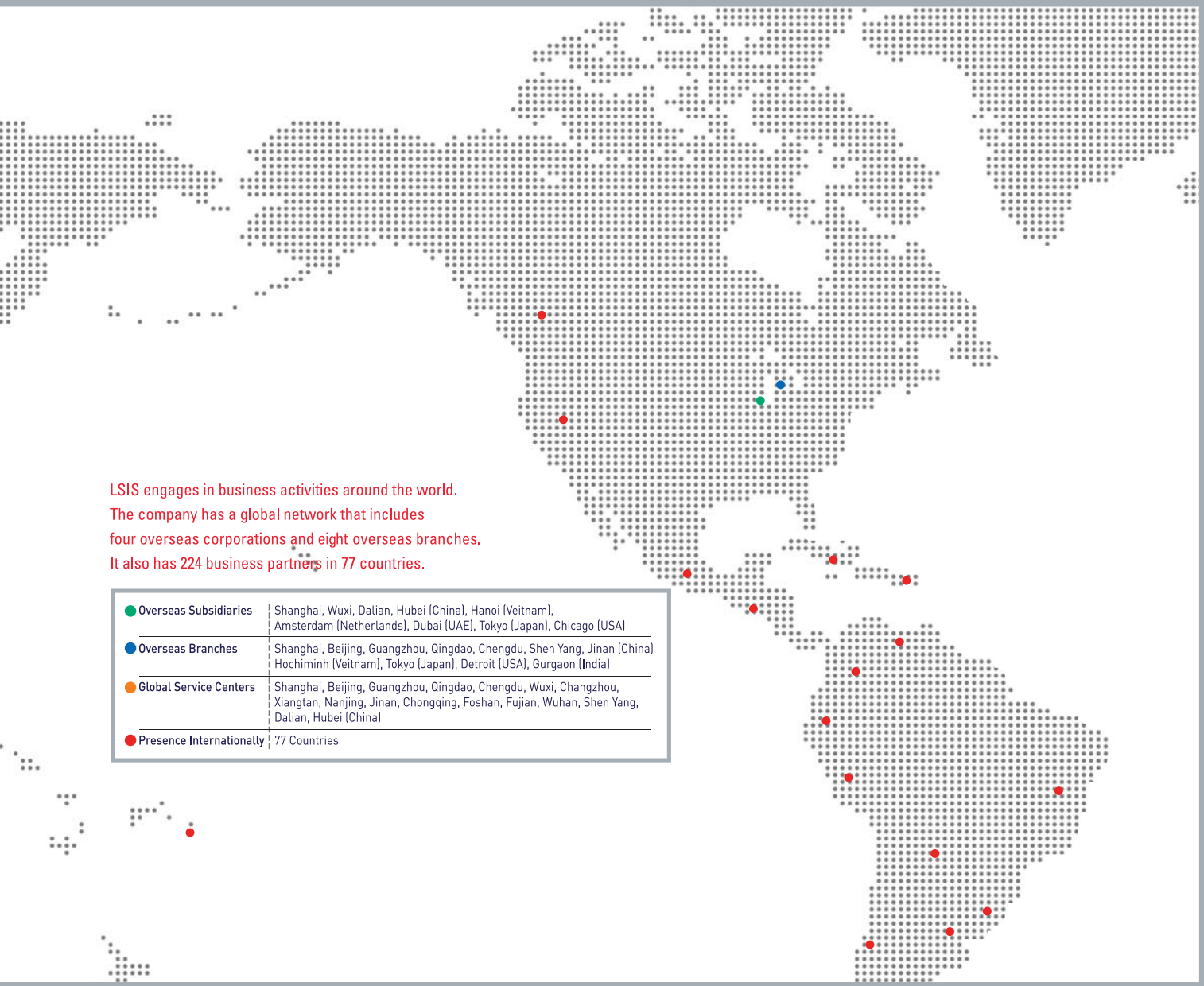


Busan Factory



Hanoi Factory (Vietnam)





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It also has 224 business partners in 77 countries.

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Presence Internationally	77 Countries

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- LSIS(Shanghai) Co., Ltd. / CHINA
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  Tel : 86-21-5237-9977(609) Fax : 86-21-5237-7189
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  Tel : 86-411-8731-7542 Fax : 86-411-8730-7560 E-Mail : dskim@lsis.com
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  102-A, National High & New Tech Industrial Development Area, Wuxi, Jiangsu, P.R. China
  Tel : 86-510-8534-6666 Fax : 86-510-8534-4078 E-Mail : sojin@lsis.com
- LS Hukai Electric(Hubei) Co., Ltd. / CHINA
  No. 100, Tanjiahe Road, Dianjun District, Yichang City, Hubei Province, P.R. China
  Tel : 86-717-667-7536 Fax : 86-717-667-7222 E-Mail : jaewoongh@lsis.com
- LS-VINA Industrial Systems Co., Ltd. / VIETNAM
  Room 1311, 13th, M3-M4 Building 91 Nguyen Chi Thanh street, Hanoi, Vietnam
  Tel : 84-4-6275-8055 Fax : 86-21-5237-7189
- LSIS(ME) FZE / U.A.E.
  LOB 19-205, JAFZA View Tower, Jebel Ali Free Zone, Dubai, United Arab Emirates
  Tel : 971-4-886-5360 Fax : 971-4-886-5361 E-Mail : shunlee@lsis.com
- LSIS Europe B.V. / NETHERLANDS
  1st. Floor, Tupolevlaan 48, 1119NZ,Schiphol-Rijk, The Netherlands
  Tel : 31-20-654-1420 Fax : 31-20-654-1429 E-Mail : junshickp@lsis.com
- LSIS Japan Co., Ltd. / JAPAN
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  Tel : 81-3-3582-9128 Fax : 81-3-3582-2667 E-Mail : jschuna@lsis.com
- LSIS USA Inc. / U.S.A.
  2000 Millbrook Drive, Lincolnshire, Chicago, IL 60069, United States of America
  Tel : 847-941-8240 Fax : 847-941-8259

Overseas Branches

- LSIS Shanghai Office / CHINA
  Room E-G, 12th, Huamin Empire Plaza, No.726, West Yan'an Road, Shanghai, P.R. China
  Tel : 86-21-5237-9977(702) Fax : 86-21-5237-7189
- LSIS Beijing Office / CHINA
  Room 2306, Building B Landgent Center, No.24 Middle Road, East 3rd Ring Road, Chaoyang District, Beijing, P.R. China
  Tel : 86-10-5761-3127 Fax : 86-10-5761-3128 E-Mail : htroh@lsis.com
- LSIS Guangzhou Office / CHINA
  Room 1403, 14th, New Poly Tower, 2 Zhongshan Liu Road, Guangzhou, P.R China
  Tel : 86-20-8326-6784 Fax : 86-20-8326-6287 E-Mail : sojhtroh@lsis.com
- LSIS Qingdao Office / CHINA
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  Tel : 86-532-8501-6058 Fax : 86-532-8501-6057 E-Mail : htroh@lsis.com
- LSIS Chengdu Office / CHINA
  Room1710, 17/F Huamin Empire Plaza, NO.1 Fuxin Road, Chengdu, P.R. China
  Tel : 86-28-8670-3201 Fax : 86-28-8670-3203 E-Mail : yangcf@lsis.com
- LSIS ShenYang Office / CHINA
  Room 803, Hongyuan Building, 52 South Nanjing Road,Heping District, Shenyang, P.R. China
  Tel : 86-24 –2321-9050 Fax : 86-24 –8386-7210 E-Mail : yangcf@lsis.com
- LSIS Jinan Office / CHINA
  Room 417, Chuangzhan Center, No. 201, Shanda Road, Lixia District, Jinan, Shandong, P. R. China
  Tel : 86-531-8263-8026 Fax : 86-531-8263-8027 E-Mail : yangcf@lsis.com
- LSIS Tokyo Office / JAPAN
  16th, Higashi-Kan, Akasaka Twin Tower, 2-17-22, Akasaka, Minato-ku, Tokyo, Japan
  Tel : 81-3-3582-9128 Fax : 81-3-3582-2667
- LS-VINA Industrial Systems Hochiminh Office / VIETNAM
  4th, Yoco Building, 41 Nguyen Thi Minh Khai Street, Hochiminh City, Vietnam
  Tel : 84-8-3822-7941 Fax : 81-84-8-3822-7942 E-Mail : sjbaik@lsis.com
- LSIS Detroit Office / U.S.A.
  5700 Crooks Rd, Suite 211, Troy, MI 48098, United States of America
  Tel : 1-248-792-2637~8 Fax : 1-248-792-2642t E-Mail : sylee@lsis.com
- LSIS Gurgaon Office / INDIA
  109 First Floor, Park Central, Sector-30, Gurgaon- 122 002, Haryana, India
  Tel : +0091-124-493-0070 Fax : 91-1244-930-066 E-Mail : hwyim@lsis.com

FUTURING SMART ENERGY



Safety Instructions

- For your safety, please read user's manual thoroughly before operating.
- Contact the nearest authorized service facility for examination, repair, or adjustment.
- Please contact qualified service technician when you need maintenance.
  Do not disassemble or repair by yourself !
- Any maintenance and inspection shall be performed by the personnel having expertise concerned.

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HEAD OFFICE

LS Tower, 127, LS-ro, Dongan-gu, Anyang-si, Gyeonggi-Do, 431-848, Korea

■Southeast Asia	+82-2-2034-4888	cshwang@lsis.com (Charles Hwang)
■Europe	+82-2-2034-4676	sukyong@lsis.com (Brian Choi)
■Turkey/Israel/CIS	+82-2-2034-4879	dkimc@lsis.com (Daniel Kim)
■Oceania	+82-2-2034-4394	kacho@lsis.com (Kendra Cho)
■North/Latin America	+82-2-2034-4286	hkchung@lsis.com (Hank Raul Chung)
■Southwest Asia/Africa	+82-2-2034-4467	myleed@lsis.com (Henry Lee)
■Middle East	+971-4-886-5360	khchoi1@lsis.com (Lambert Choi)

Overseas Subsidiaries

- **LSIS(Shanghai) Co., Ltd. /CHINA**
  32nd Room 1~4, 32/F, Great Wall Building, No.3000 North Zhongshan Road,
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- **LS Hukai Electric(Hubei) Co., Ltd./CHINA**
  No. 100, Tanjiahe Road, Dianjun District, Yichang City, Hubei Province, P.R. China
  Tel : 86-717-667-7536 Fax : 86-717-667-7222 E-Mail : jaewoongh@lsis.com
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  Tel : 84-4-6275-8055 Fax : 86-21-5237-7189
- **LSIS(ME) FZE/U.A.E.**
  LOB 19-205, JAFZA View Tower, Jebel Ali Free Zone, Dubai, United Arab Emirates
  Tel : 971-4-886-5360 Fax : 971-4-886-5361 E-Mail : shunlee@lsis.com
- **LSIS Europe B.V./NETHERLANDS**
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  Tel : 31-20-654-1420 Fax : 31-20-654-1429 E-Mail : htha@lsis.com
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  Room 2001, Galaxy Building, 29 ShanDong Road, ShiNan District, QingDao, ShanDong, P.R. China
  Tel : 86-532-8501-6058 Fax : 86-532-8501-6057 E-Mail : htroh@lsis.com
- **LSIS Chengdu Office/CHINA**
  Room1710, 17/F Huamin Empire Plaza, NO.1 Fuxin Road, Chengdu, P.R. China
  Tel : 86-28-8670-3201 Fax : 86-28-8670-3203 E-Mail : yangcf@lsis.com
- **LSIS ShenYang Office/CHINA**
  Room 803, Hongyuan Building, 52 South Nanjing Road,Heping District, Shenyang, P.R. China
  Tel : 86-24-2321-9050 Fax : 86-24 -8386-7210 E-Mail : yangcf@lsis.com
- **LSIS Jinan Office/CHINA**
  Room 417, Chuangzhan Center, No. 201, Shanda Road, Lixia District, Jinan, Shandong, P. R. China
  Tel : 86-531-8263-8026 Fax : 86-531-8263-8027 E-Mail : yangcf@lsis.com
- **LSIS Tokyo Office/JAPAN**
  16th, Higashi-Kan, Akasaka Twin Tower, 2-17-22, Akasaka, Minato-ku, Tokyo, Japan
  Tel : 81-3-3582-9128 Fax : 81-3-3582-2667
- **LS-VINA Industrial Systems Hochiminh Office/VIETNAM**
  4th, Yoco Building, 41 Nguyen Thi Minh Khai Street, Hochiminh City, Vietnam
  Tel : 84-8-3822-7941 Fax : 81-84-8-3822-7942 E-Mail : sjbaik@lsis.com
- **LSIS Detroit Office/U.S.A.**
  5700 Crooks Rd, Suite 211, Troy, MI 48098, United States of America
  Tel : 1-248-792-2637~8 Fax : 1-248-792-2642 E-Mail : sylee@lsis.com
- **LSIS Gurgaon Office/INDIA**
  109 First Floor, Park Central, Sector-30, Gurgaon- 122 002, Haryana, India
  Tel : +0091-124-493-0070 Fax : 91-1244-930-066 E-Mail : hwyim@lsis.com

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